

1. Let V be a vector space with scalar field F and $T : V \rightarrow V$ be linear. Identify each of the following statements as true or false:
 - (a) If $T(\mathbf{v}) = \lambda\mathbf{v}$, then \mathbf{v} is an eigenvector of T .
 - False: we would need to exclude $\mathbf{v} = \mathbf{0}$ here, since by definition $\mathbf{v} = \mathbf{0}$ is not an eigenvector.
 - (b) Every linear transformation on V has at least one eigenvector.
 - False: there are linear transformations with no eigenvectors, e.g., integration on $\mathbb{R}[x]$.
 - (c) If V is finite-dimensional, every linear transformation on V has at least one eigenvector.
 - False: the characteristic polynomial may have no roots in the scalar field. For example, the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with $T(x, y) = (y, -x)$ has no real eigenvalues hence no eigenvectors.
 - (d) Any two eigenvectors of T are linearly independent.
 - False: this is only true if the associated eigenvalues are different.
 - (e) The sum of two eigenvectors of T is also an eigenvector of T .
 - False: usually not, e.g, for $T(x, y) = (x, 2y)$ then $(1, 0)$ and $(0, 1)$ are eigenvectors, but $(1, 1)$ is not.
 - (f) The sum of two eigenvalues of T is also an eigenvalue of T .
 - False: usually not, e.g., for $T(x, y) = (x, 2y)$ then 1 and 2 are eigenvalues, but 3 is not.
 - (g) If two matrices are similar, then they have the same eigenvectors.
 - False: as we showed, if $A = QBQ^{-1}$ and $A\mathbf{v} = \lambda\mathbf{v}$ then $B(Q\mathbf{v}) = \lambda(Q\mathbf{v})$. This means the eigenspaces of A and B are related by left-multiplication by Q , but are not necessarily equal.
 - (h) If two matrices have the same eigenvalues, then they are similar.
 - False: for example, the matrices $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ have the same eigenvalues but are not similar (the latter is not diagonalizable but the former is).
 - (i) If two matrices are similar, then they have the same eigenvalues.
 - True: similar matrices have the same characteristic polynomial hence the same eigenvalues.
 - (j) If $\dim(V) = n$, then T has at most n distinct eigenvalues in F .
 - True: the characteristic polynomial $p(t) = \det(tI - A)$ has degree n hence at most n roots in F .
 - (k) If $\dim(V) = n$, then T has exactly n distinct eigenvalues in F .
 - False: the characteristic polynomial may have repeated roots, in which case it would have fewer than n distinct roots. It may also have irreducible terms of degree > 1 , which would further lower the number of roots.
 - (l) If the characteristic polynomial of A is $p(t) = t(t - 1)^2$, then the 1-eigenspace of A has dimension 2.
 - False: although 1 is a double root of the characteristic polynomial, this means only that the 1-eigenspace can have dimension 1 or 2.
 - (m) If the characteristic polynomial of A is $p(t) = t(t - 1)^2$, then the only vector \mathbf{v} with $A\mathbf{v} = 3\mathbf{v}$ is $\mathbf{v} = \mathbf{0}$.
 - True: such a vector would be an element of the 3-eigenspace, but since 3 is not an eigenvalue of A , the 3-eigenspace is trivial.
 - (n) V has a basis $\beta = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ of eigenvectors of T if and only if T is diagonalizable.
 - True: $\beta = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ is a basis of eigenvectors with eigenvalues $\lambda_1, \dots, \lambda_n$ if and only if $[T]_\beta^\beta$ is diagonal with diagonal entries $\lambda_1, \dots, \lambda_n$.
-

2. For each matrix A over each field F , (i) find all eigenvalues of A over F , (ii) find a basis for each eigenspace of A , and (iii) determine whether or not A is diagonalizable over F and if so find an invertible matrix Q and diagonal matrix D such that $D = Q^{-1}AQ$.

(a) The matrix $\begin{bmatrix} 3 & 1 \\ -2 & 5 \end{bmatrix}$ over \mathbb{R} .

- The characteristic polynomial is $\det(tI - A) = \begin{vmatrix} t-3 & -1 \\ 2 & t-5 \end{vmatrix} = t^2 - 8t + 17$.
- The roots of this polynomial are $\lambda = 4 \pm i$. Thus, there are no eigenvalues over \mathbb{R} , and so it is not diagonalizable.

(b) The matrix $\begin{bmatrix} 1 & 1 & -1 \\ -2 & 3 & -2 \\ -1 & 0 & 1 \end{bmatrix}$ over \mathbb{Q} .

- The characteristic polynomial is $\det(tI - A) = \begin{vmatrix} t-1 & -1 & 1 \\ 2 & t-3 & 2 \\ 1 & 0 & t-1 \end{vmatrix} = (t-1)(t-2)^2$.
- Thus, the eigenvalues are $\lambda = \boxed{1, 2, 2}$.

- Row-reducing $\lambda I - A$ yields the 1-eigenspace basis $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$, and the 2-eigenspace basis $\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$.

- Since the 2-eigenspace is only 1-dimensional, the matrix is not diagonalizable.

(c) The matrix $\begin{bmatrix} 3 & 1 \\ -2 & 5 \end{bmatrix}$ over \mathbb{C} .

- The characteristic polynomial was calculated in (a) as $p(t) = t^2 - 8t + 17$.
- Over \mathbb{C} , the eigenvalues are $\lambda = \boxed{4 + i, 4 - i}$ with respective eigenbases $\begin{bmatrix} 1 - i \\ 2 \end{bmatrix}$ and $\begin{bmatrix} 1 + i \\ 2 \end{bmatrix}$.
- The matrix is diagonalizable: we can take $D = \begin{bmatrix} 4 + i & 0 \\ 0 & 4 - i \end{bmatrix}$ and $Q = \begin{bmatrix} 1 - i & 1 + i \\ 2 & 2 \end{bmatrix}$.

(d) The matrix $\begin{bmatrix} 0 & -1 & 1 \\ 0 & 2 & 0 \\ -2 & -1 & 3 \end{bmatrix}$ over \mathbb{C} .

- The characteristic polynomial is $\det(tI - A) = (t-1)(t-2)^2$. Thus, the eigenvalues are $\lambda = \boxed{1, 2, 2}$.

- Row-reducing $\lambda I - A$ yields the 1-eigenbasis $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ and the 2-eigenbasis $\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}$.

- Since the sum of the eigenspace dimensions is 3, the matrix is diagonalizable: the diagonalization

is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ via the matrix $Q = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 2 \\ 1 & 2 & 0 \end{bmatrix}$.

(e) The matrix $\begin{bmatrix} -5 & 9 \\ -4 & 7 \end{bmatrix}$ over \mathbb{R} .

- The characteristic polynomial is $\det(tI - A) = \begin{vmatrix} t+5 & -9 \\ 4 & t-7 \end{vmatrix} = t^2 - 2t + 1$ with roots $\lambda = \boxed{1, 1}$.

- Row-reducing $\lambda I - A = I - A = \begin{bmatrix} 6 & -9 \\ 4 & -6 \end{bmatrix}$ yields $\begin{bmatrix} 2 & -3 \\ 0 & 0 \end{bmatrix}$, with nullspace basis $\begin{bmatrix} 3 \\ 2 \end{bmatrix}$.

- Since the 1-eigenspace is only 1-dimensional, the matrix is not diagonalizable.

(f) The matrix $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 3 & 1 & 2 \end{bmatrix}$ over \mathbb{C} .

- The characteristic polynomial is $\det(tI - A) = (t - 6)(t^2 - 3)$ with roots $\lambda = \boxed{6, \sqrt{3}, -\sqrt{3}}$.
 - Row-reducing $\lambda I - A$ for each of the three possible eigenvalues λ yields that each eigenspace is 1-dimensional.
 - Explicitly: 6-eigenbasis $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $\sqrt{3}$ -eigenbasis $\begin{bmatrix} -1 - \sqrt{3} \\ -1 + \sqrt{3} \\ 2 \end{bmatrix}$, $-\sqrt{3}$ -eigenbasis $\begin{bmatrix} -1 + \sqrt{3} \\ -1 - \sqrt{3} \\ 2 \end{bmatrix}$.
 - Since the sum of the eigenspace dimensions is 3, the matrix is diagonalizable.
 - The diagonalization is $\begin{bmatrix} 6 & 0 & 0 \\ 0 & \sqrt{3} & 0 \\ 0 & 0 & -\sqrt{3} \end{bmatrix}$ via the matrix $Q = \begin{bmatrix} 1 & -1 - \sqrt{3} & -1 + \sqrt{3} \\ 1 & -1 + \sqrt{3} & -1 - \sqrt{3} \\ 1 & 2 & 2 \end{bmatrix}$.
-

3. For each operator $T : V \rightarrow V$ on each vector space V , (i) find all its eigenvalues and a basis for each eigenspace, and (ii) determine whether the operator is diagonalizable and if so, find a basis for which $[T]_{\beta}^{\beta}$ is diagonal:

(a) The map $T : \mathbb{Q}^2 \rightarrow \mathbb{Q}^2$ given by $T(x, y) = (x + 4y, 3x + 5y)$.

- With respect to the standard basis β the associated matrix is $A = [T]_{\beta}^{\beta} = \begin{bmatrix} 1 & 4 \\ 3 & 5 \end{bmatrix}$.
- The characteristic polynomial is $p(t) = \det(tI - A) = t^2 - 6t - 1 = (t - 7)(t + 1)$. Hence the eigenvalues are $\lambda = \boxed{7, -1}$, and row-reducing yields corresponding eigenbases $\boxed{(2, 3)}$ and $\boxed{(-2, 1)}$.
- Since the sum of the eigenspace dimensions is 2, the transformation is diagonalizable: the diagonalization is $\begin{bmatrix} 7 & 0 \\ 0 & -1 \end{bmatrix}$ via the basis $\beta = \boxed{\{(2, 3), (-2, 1)\}}$.

(b) The derivative operator $D : P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ given by $D(p) = p'$.

- With respect to the standard basis $\beta = \{1, x, x^2\}$, the associated matrix is $[D]_{\beta}^{\beta} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$.
- Since this matrix is upper-triangular, the eigenvalues are just the diagonal elements $\lambda = \boxed{0, 0, 0}$. Row-reducing yields that the 0-eigenspace is 1-dimensional and has basis $\boxed{\{1\}}$.
- Since the eigenspace is only 1-dimensional, the transformation is not diagonalizable.

(c) The transpose map $T : M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ given by $T(M) = M^T$.

- With standard basis $\beta = \{e_{1,1}, e_{1,2}, e_{2,1}, e_{2,2}\}$, the associated matrix is $A = [T]_{\beta}^{\beta} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$.
 - The characteristic polynomial is $p(t) = \det(tI - A) = (t - 1)^3(t + 1)$. Hence the eigenvalues are $\lambda = \boxed{1, 1, 1, -1}$.
 - Row-reducing yields corresponding eigenbases $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ and $\left\{ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}$.
Alternatively, one could observe that the 1-eigenspace is the space of symmetric matrices, while the (-1) -eigenspace is the space of skew-symmetric matrices.
 - Since the sum of the eigenspace dimensions is 4, the transformation is diagonalizable: the diagonalization is $\begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & -1 \end{bmatrix}$ via the basis $\beta = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}$.
-

4. Let F be a field and let L and R be the left shift and right shift operators on infinite sequences of elements of F , defined by $L(a_1, a_2, a_3, a_4, \dots) = (a_2, a_3, a_4, \dots)$ and $R(a_1, a_2, a_3, a_4, \dots) = (0, a_1, a_2, a_3, \dots)$.
- (a) Find all of the eigenvalues and a basis for each eigenspace of L .
- Solving $L(a_1, a_2, a_3, a_4, \dots) = (\lambda a_1, \lambda a_2, \lambda a_3, \lambda a_4, \dots)$ gives $(a_2, a_3, a_4, a_5, \dots) = (\lambda a_1, \lambda a_2, \lambda a_3, \lambda a_4, \dots)$ whence $a_2 = \lambda a_1, a_3 = \lambda a_2, \dots, a_{i+1} = \lambda a_i, \dots$
 - It is then easy to see that the λ -eigenspace is 1-dimensional and spanned by the vector $(1, \lambda, \lambda^2, \lambda^3, \dots)$. In particular, every element $\lambda \in F$ is an eigenvalue of L .
- (b) Find all of the eigenvalues and a basis for each eigenspace of R .
- Solving $R(a_1, a_2, a_3, a_4, \dots) = (\lambda a_1, \lambda a_2, \lambda a_3, \lambda a_4, \dots)$ gives $(0, a_1, a_2, a_3, \dots) = (\lambda a_1, \lambda a_2, \lambda a_3, \lambda a_4, \dots)$ whence $\lambda a_1 = 0, \lambda a_2 = a_1, \dots, \lambda a_{i+1} = a_i$.
 - If $\lambda \neq 0$ then cancelling λ gives $a_i = 0$ for all i (but the zero vector is not an eigenvector by definition), while if $\lambda = 0$ then again we see $a_i = 0$ for all i .
 - Thus R has no eigenvalues since $(a_1, a_2, a_3, \dots) = \lambda(0, a_1, a_2, a_3, \dots)$ forces $a_1 = a_2 = a_3 = \dots = 0$.
-

5. Suppose V is a vector space and $S, T : V \rightarrow V$ are linear operators on V .
- (a) If S and T commute (i.e., $ST = TS$), show that S maps each eigenspace of T into itself.
- Suppose $T\mathbf{v} = \lambda\mathbf{v}$. Then $\lambda(S\mathbf{v}) = S(\lambda\mathbf{v}) = S(T\mathbf{v}) = T(S\mathbf{v})$ so $S\mathbf{v}$ is also a λ -eigenvector of T .
- (b) If \mathbf{v} is an eigenvector of T , show that it is also an eigenvector of T^n for any positive integer n .
- Suppose $T\mathbf{v} = \lambda\mathbf{v}$. Then $T^2\mathbf{v} = T(T\mathbf{v}) = T(\lambda\mathbf{v}) = \lambda(T\mathbf{v}) = \lambda^2\mathbf{v}$.
 - By repeating this argument (equivalently, by a trivial induction) we see that $T^n\mathbf{v} = \lambda^n\mathbf{v}$, so \mathbf{v} is also an eigenvector of T^n with corresponding eigenvalue λ^n .
-

6. Suppose A is an invertible $n \times n$ matrix and that $p(t) = t^n + a_{n-1}t^{n-1} + \dots + a_1t + a_0$ is its characteristic polynomial. Note that $a_0 = (-1)^n \det(A)$ is nonzero.
- (a) If $B = -\frac{1}{a_0}(A^{n-1} + a_{n-1}A^{n-2} + \dots + a_2A + a_1I_n)$, show that $AB = I_n$. [Hint: Cayley-Hamilton.]
- By the Cayley-Hamilton theorem, we know that $A^n + a_{n-1}A^{n-1} + \dots + a_2A^2 + a_1A + a_0I_n = 0$, so rearranging yields $A^n + a_{n-1}A^{n-1} + \dots + a_2A^2 + a_1A = -a_0I_n$.
 - From the definition of B , we can multiply through by A to see that $AB = -\frac{1}{a_0}(A^n + a_{n-1}A^{n-1} + \dots + a_2A^2 + a_1A) = -\frac{1}{a_0}(-a_0I_n) = I_n$, as claimed.
- (b) Show that there exists a polynomial $q(x)$ of degree at most $n - 1$ such that $A^{-1} = q(A)$.
- By part (a) we see that $AB = I_n$ so that $B = A^{-1}$.
 - The desired statement is then immediate from the expression in part (a), since the expression for B is a polynomial in A of degree $n - 1$.
-

7. Suppose V is finite-dimensional and $T : V \rightarrow V$ is a projection, so that $T^2 = T$.
- (a) Show that the only possible eigenvalues of T are 0 and 1.
- Suppose \mathbf{v} is an eigenvector of T with eigenvalue λ , so that $T(\mathbf{v}) = \lambda\mathbf{v}$.
 - Then $\lambda^2\mathbf{v} = T^2(\mathbf{v}) = T(\mathbf{v}) = \lambda\mathbf{v}$, so $(\lambda^2 - \lambda)\mathbf{v} = \mathbf{0}$. Since $\mathbf{v} \neq \mathbf{0}$ this means $\lambda^2 = \lambda$, so $\lambda = 0, 1$.
- (b) Show that T is diagonalizable. [Hint: See homework 5.]
- As shown in problem 7b of homework 5, if β is a basis for $\ker(T)$ followed by a basis for $\text{im}(T)$, then $[T]_\beta^\beta$ is diagonal with diagonal entries all 0s (for the kernel elements) and 1s (for the image elements). This β is a diagonalizing basis for T .

- (c) Suppose A and B are projection maps on V of the same rank. Show that A and B are similar. Deduce that up to similarity, there are $\dim(V) + 1$ different projection maps on V .
- From (a) and (b) together, we can characterize a projection map up to similarity by its diagonalization, whose diagonal entries must be either 0s or 1s.
 - If $\dim(V) = n$, there are clearly $n + 1$ such matrices (with n zero entries, $n - 1$ zero entries, \dots , 1 zero entry, 0 zero entries) and each of these matrices has a different rank: namely, 0, 1, \dots , $n - 1$, n . Thus, up to similarity, there are $n + 1$ different projection maps on V .

8. The goal of this problem is to give some counterexamples for results about orthogonal complements, projections, best approximations, and adjoints in infinite-dimensional spaces. Let V be the vector space of infinite real sequences $\{a_i\}_{i \geq 1} = (a_1, a_2, \dots)$ with only finitely many nonzero terms, with inner product given by $\langle \{a_i\}, \{b_i\} \rangle = \sum_{i=1}^{\infty} a_i b_i$. (Note that this sum converges since only finitely many terms are nonzero.) Let \mathbf{e}_i be the i th unit coordinate vector and observe that $\{\mathbf{e}_i\}_{i \geq 1}$ is an orthonormal basis for V . Now for each $n \geq 2$, let $\mathbf{v}_n = \mathbf{e}_1 - \mathbf{e}_n$ and define $W = \text{span}(\mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \dots)$.

- (a) Show that $\mathbf{e}_1 \notin W$ so that W is a proper subspace of V , but that $W^\perp = \{\mathbf{0}\}$.
- If we have $\mathbf{e}_1 = a_2 \mathbf{v}_2 + a_3 \mathbf{v}_3 + \dots + a_n \mathbf{v}_n$, then expanding out yields $\mathbf{e}_1 = (a_1 + \dots + a_n) \mathbf{e}_1 - a_2 \mathbf{e}_2 - a_3 \mathbf{e}_3 - \dots - a_n \mathbf{e}_n$ so since the \mathbf{e}_i are linearly independent, we would have $a_1 + \dots + a_n = 1$ and also $a_2 = a_3 = \dots = a_n = 0$, but this is contradictory. Thus $\mathbf{e}_1 \notin W$.
 - Next, if $\mathbf{w} = b_1 \mathbf{e}_1 + \dots + b_n \mathbf{e}_n$ is an element of W^\perp , we have $0 = \langle b_1 \mathbf{e}_1 + \dots + b_n \mathbf{e}_n, \mathbf{v}_k \rangle = b_1 - b_k$. Thus $b_k = b_1$ for all k , but since only finitely many b_k can be nonzero, we must have $b_1 = b_2 = \dots = 0$, and so $\mathbf{w} = \mathbf{0}$.
- (b) Show that $W^\perp + W \neq V$ and that $(W^\perp)^\perp \neq W$.
- By (a) we have $W^\perp + W = W \neq V$, and also $(W^\perp)^\perp = (\{\mathbf{0}\})^\perp = V \neq W$.
- (c) For any $\mathbf{v} \notin W$, show that there does not exist any choice of $\mathbf{w} \in W$ and $\mathbf{w}^\perp \in W^\perp$ such that $\mathbf{v} = \mathbf{w} + \mathbf{w}^\perp$. Conclude that there is not a well-defined orthogonal projection map of V onto W .
- Suppose we had such $\mathbf{w}, \mathbf{w}^\perp$. From (a) we know that $W^\perp = \{\mathbf{0}\}$, so the only possible choice would be $\mathbf{w}^\perp = \mathbf{0}$. But this would imply $\mathbf{v} = \mathbf{w}$ which is impossible since \mathbf{v} is not in W .
- (d) Show that there exists $\mathbf{w}_n \in W$ such that $\|\mathbf{w}_n - \mathbf{e}_1\| = 1/n$ for any positive integer n . Deduce there is no possible best approximation $\mathbf{w} \in W$ to \mathbf{e}_1 , namely with $\|\mathbf{w} - \mathbf{e}_1\| \leq \|\mathbf{w}' - \mathbf{e}_1\|$ for all $\mathbf{w}' \in W$. [Hint: Take $\mathbf{w}_n = (1, -1/n^2, -1/n^2, \dots, -1/n^2, 0, 0, \dots)$.]
- Consider the vector $\mathbf{w}_n = (1, -1/n^2, -1/n^2, \dots, -1/n^2, 0, 0, \dots)$ with first entry 1 followed by n^2 entries equal to $-1/n^2$, and other entries 0.
 - Then $\|\mathbf{w}_n - \mathbf{e}_1\|^2 = \|(0, -1/n^2, -1/n^2, \dots, -1/n^2, 0, 0, \dots)\|^2 = n^2 \cdot (1/n^2)^2 = 1/n^2$ so $\|\mathbf{w}_n - \mathbf{e}_1\| = 1/n$ as desired.
 - Since $1/n \rightarrow 0$ as $n \rightarrow \infty$, a best approximation vector \mathbf{w} would necessarily have $\|\mathbf{w} - \mathbf{e}_1\| = 0$, but this is impossible since $\mathbf{e}_1 \notin W$.
- (e) Let $T : V \rightarrow V$ be the linear transformation defined by setting $T(\mathbf{e}_n) = \sum_{i=1}^n \mathbf{e}_i$ for each $i \geq 1$. If T had an adjoint $T^* : V \rightarrow V$, show that infinitely many components of $T^*(\mathbf{e}_1)$ would be nonzero. Deduce that T^* cannot exist.
- By hypothesis we have $\langle \mathbf{e}_k, T^*(\mathbf{e}_1) \rangle = \langle T(\mathbf{e}_k), \mathbf{e}_1 \rangle = \langle \sum_{i=1}^k \mathbf{e}_i, \mathbf{e}_1 \rangle = 1$ for each $k \geq 1$.
 - Conjugating then yields $\langle T^*(\mathbf{e}_1), \mathbf{e}_k \rangle = 1$: but this inner product is the coefficient of \mathbf{e}_k in $T^*(\mathbf{e}_1)$, so we would necessarily have $T^*(\mathbf{e}_1) = \sum_{k=1}^{\infty} \mathbf{e}_k$. But this vector is not an element of V since it has infinitely many nonzero components. This is a contradiction, so T^* cannot exist.

9. [Challenge] The goal of this problem is to prove various results about eigenvalues of complex matrices and stochastic matrices. Let $A \in M_{n \times n}(\mathbb{C})$, define $\rho_i(A)$ to be the sum of the absolute values of the entries in the i th row of A , and define $\rho(A) = \max_{1 \leq i \leq n} \rho_i(A)$.

(a) Define the i th Gershgorin disk C_i to be the disc in \mathbb{C} centered at $a_{i,i}$ with radius $r_i(A) = \rho_i(A) - |a_{i,i}|$. Prove Gershgorin's disc theorem: every eigenvalue of A is contained in one of the Gershgorin disks of A . [Hint: If $\mathbf{v} = (x_1, \dots, x_n)$ is an eigenvector where x_k has the largest absolute value among the entries of \mathbf{v} , show that $|\lambda x_k - a_{k,k}x_k| \leq r_i(A) |x_k|$ by noting that λx_k is the k th component of $A\mathbf{v}$.]

- Suppose $\mathbf{v} = (x_1, \dots, x_n)$ is an eigenvector with eigenvalue λ : then by taking the k th component of $A\mathbf{v} = \lambda\mathbf{v}$ we see that $\sum_{j=1}^n a_{k,j}x_j = \lambda x_k$.
- Thus, $|\lambda x_k - a_{k,k}x_k| = \left| \sum_{j=1}^n a_{k,j}x_j - a_{k,k}x_k \right| = \left| \sum_{j \neq k} a_{k,j}x_j \right| \leq \sum_{j \neq k} |a_{k,j}| |x_j| \leq \sum_{j \neq k} |a_{k,j}| |x_k| = (\rho_i(A) - |a_{k,k}|) |x_k| = r_i(A) |x_k|$, where we used the triangle inequality at the first \leq and the fact that $|x_j| \leq |x_k|$ for each j in the second \leq .
- Since $|x_k| > 0$ because $\mathbf{v} \neq \mathbf{0}$, dividing through by $|x_k|$ yields $|\lambda - a_{k,k}| \leq r_i(A)$: in other words, λ lies within a Gershgorin disk of A . This holds for all eigenvalues λ , so all eigenvalues lie within Gershgorin disks of A .

(b) For any eigenvalue λ of $A \in M_{n \times n}(\mathbb{C})$, prove that $|\lambda| \leq \rho(A)$.

- By Gershgorin's disc theorem from (a), we have $|\lambda - a_{k,k}| \leq \rho_k(A) - |a_{k,k}|$ for some k .
- Then by the triangle inequality, we have $|\lambda| \leq |\lambda - a_{k,k}| + |a_{k,k}| = \rho_k(A)$. Since the maximum of a set is greater than or equal to all of the elements, this immediately yields $|\lambda| \leq \max_{1 \leq i \leq n} \rho_i(A)$.

(c) Prove that if $A \in M_{n \times n}(\mathbb{R})$ has positive entries and there exists an eigenvalue λ such that $|\lambda| = \rho(A)$, then $\lambda = \rho(A)$ and the λ -eigenspace is 1-dimensional and spanned by the vector $\mathbf{v} = (1, 1, \dots, 1)$. [Hint: Analyze when equality can hold in (a) and (b).]

- If $|\lambda| = \rho(A)$ in part (b), then we must have equality in the triangle inequality: $|\lambda| = |\lambda - a_{k,k}| + |a_{k,k}|$. This occurs if and only if λ is real and $\lambda \geq a_{k,k}$, so since $a_{k,k}$ this means λ is a positive real number. Since $\rho(A)$ is also a positive real number, this means $\lambda = \rho(A)$.
- Furthermore, if $\mathbf{v} = (x_1, x_2, \dots, x_k)$ is a corresponding eigenvector (which is necessarily real, since λ is real), then to get equality in the argument for (a), we must have $\left| \sum_{j \neq k} a_{k,j}x_j \right| = \sum_{j \neq k} |a_{k,j}| |x_j|$ and also $|x_j| = |x_k|$ for each j . The first equality requires equality in the triangle inequality, meaning that all of the terms $a_{k,j}x_j$ have the same sign, and the second equality requires all of the x_j to have the same absolute value.
- Since all of the entries of A are positive, these two statements together are equivalent to $x_1 = x_2 = \dots = x_n$, meaning that \mathbf{v} is a scalar multiple of $(1, 1, \dots, 1)$. This means that the λ -eigenspace is 1-dimensional and spanned by $\mathbf{v} = (1, 1, \dots, 1)$.

(d) If M is a stochastic matrix (i.e., with nonnegative real entries and columns summing to 1), show that every eigenvalue λ of M has $|\lambda| \leq 1$. Also show that if M has all entries positive, then the only eigenvalue of M of absolute value 1 is $\lambda = 1$, and the 1-eigenspace has dimension 1. [Hint: Consider M^T .]

- Note that M^T has rows with nonnegative entries all summing to 1, and it has the same eigenvalues as M . Thus, $\rho_i(M^T) = 1$ for each i , so by (b), we immediately obtain $|\lambda| \leq 1$.
- Furthermore, since $M^T\mathbf{v} = \mathbf{v}$ where $\mathbf{v} = (1, 1, \dots, 1)$ we see that 1 is indeed an eigenvalue of M^T hence also of M .
- Therefore, by (c), all other eigenvalues of M have absolute value less than 1, and the 1-eigenspace of M^T (hence also of M) is 1-dimensional.