# Math 2321 (Multivariable Calculus) Lecture #17 of 38 $\sim$ March 1, 2021

Double Integrals in Polar Coordinates

- Double Integrals in Polar Coordinates
- Triple Integrals

This material represents  $\S3.3.2 + \S3.2.1$  from the course notes.

### Polar Coordinates

Last time we briefly reviewed polar coordinates:

#### Definition

The <u>polar coordinates</u>  $(r, \theta)$  of a point (x, y) satisfy  $x = r \cos(\theta)$ ,  $y = r \sin(\theta)$ , for  $r \ge 0$  and  $0 \le \theta \le 2\pi$ .

- The parameter r gives the radial distance from the origin (or "pole"), while  $\theta$  measures the angle with respect to the positive x-axis.
- Some conventions allow for negative values of *r*. We will insist that *r* ≥ 0 in our setup.
- Since sine and cosine are periodic, we implicitly identify angles  $\theta$  that differ by an integral multiple of  $2\pi$  radians.

• We have 
$$r = \sqrt{x^2 + y^2}$$
,  $\theta = \begin{cases} \tan^{-1}(y/x) \text{ for } x > 0\\ \tan^{-1}(y/x) + \pi \text{ for } x < 0 \end{cases}$ 

The primary reason to use polar coordinates is that they will simplify integrals over regions that are portions of circles, because circles have simple descriptions in polar coordinates.

- Specifically, the circle x<sup>2</sup> + y<sup>2</sup> = a<sup>2</sup> in rectangular coordinates (over which it is cumbersome to set up double integrals) becomes the much simpler equation r = a in polar coordinates.
- Polar coordinates are also useful in simplifying functions which involve  $x^2 + y^2$  or (especially)  $\sqrt{x^2 + y^2}$ .
- Lines through the origin also have reasonably simple descriptions in polar: the line y = mx becomes the pair of rays θ = tan<sup>-1</sup>(m) and θ = tan<sup>-1</sup>(m) + π when written in polar coordinates. (The two rays point in opposite directions.)

Now we can describe how to set up iterated integrals in polar coordinates.

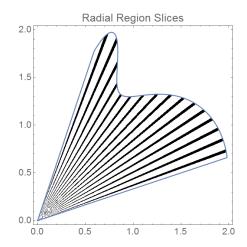
- Suppose we want to integrate the function f(x, y) on the region R: this is the double integral  $\iint_R f(x, y) dA$ .
- To set this up as an iterated integral in polar coordinates, we typically use the integration order  $dr d\theta$ , since most of the polar curves we will work with have the form  $r = f(\theta)$  or  $\theta = \text{constant}$ .

There are three things we must do:

- 1. Convert the limits of integration to polar coordinates.
- 2. Convert the function to polar coordinates.
- 3. Convert the area differential dA to polar coordinates.

### Integration in Polar Coordinates, III

Now imagine "slicing" our region radially:



Using the radial slices, we can identify the limits of integration in polar coordinates:

- The limits for  $\theta$  will be the minimum and maximum values of  $\theta$ : the range of values of  $\theta$  where we have slices.
- The limits for r will be the minimum and maximum value of r on any given slice, in terms of  $\theta$ .
- For regions that lie between two curves r = f<sub>inner</sub>(θ) and r = f<sub>outer</sub>(θ), the inner curve is the lower limit and the outer curve is the upper limit.

To convert the function f(x, y) to polar coordinates, we simply plug in  $x = r \cos \theta$  and  $y = r \sin \theta$ .

The last task is to convert the area differential dA into polar coordinates.

- Your first guess is probably that  $dA = dr d\theta$ , in parallel to the rectangular area differential dA = dy dx = dx dy.
- However, this is not correct!
- To explain why, consider where the area differential comes from: it is the area of the region formed by changing the parameters x and y by small amounts δx and δy.
- The resulting shape is simply a rectangle with side lengths  $\Delta x$  and  $\Delta y$ , so we get  $\Delta A = \Delta x \Delta y$ .
- As  $\Delta x$  and  $\Delta y$  become small, the limit is dA = dx dy.

Now consider what happens if we have a radial region with radius r, and we change r by  $\Delta r$  and  $\theta$  by  $\Delta \theta$ :

- The resulting shape is a radial annulus with inner radius r, outer radius r + Δr, and angle Δθ.
- The area is

$$\Delta A = \frac{1}{2} (\Delta \theta) [(r + \Delta r)^2 - r^2] = \frac{1}{2} \Delta \theta [2r\Delta r + (\Delta r)^2]$$
$$= r\Delta r\Delta \theta + \frac{1}{2} (\Delta r)^2 \Delta \theta.$$

 As Δr and Δθ become small, the second term drops away, and we obtain dA = r dr dθ. Note the factor of r in front! So, putting all of this together, to set up an iterated integral  $\iint_R f(x, y) dA$  in polar coordinates, we do the following:

- 1. Draw the region R. Slice it radially and use the slices to identify the polar limits of integration.
- 2. Convert the function f(x, y) to polar coordinates by setting  $x = r \cos \theta$  and  $y = r \sin \theta$ .
- 3. Write down the polar area differential  $dA = r dr d\theta$ .
- 4. Evaluate the resulting integral.

- The region is defined by  $r \le 1$ . Since we have no restrictions on  $\theta$ , we want  $0 \le \theta \le 2\pi$ .
- Since r is always nonnegative, our limits for r are  $0 \le r \le 1$ .
- The function is  $f(r \cos \theta, r \sin \theta) = \cos^2 \theta + \sin^2 \theta = 1$ .
- The differential is  $dA = r dr d\theta$ .

- The region is defined by  $r \le 1$ . Since we have no restrictions on  $\theta$ , we want  $0 \le \theta \le 2\pi$ .
- Since r is always nonnegative, our limits for r are  $0 \le r \le 1$ .
- The function is  $f(r\cos\theta, r\sin\theta) = \cos^2\theta + \sin^2\theta = 1$ .
- The differential is  $dA = r dr d\theta$ .
- Then the integral is  $\int_0^{2\pi} \int_0^1 (r^2) r \, dr \, d\theta = \int_0^{2\pi} \int_0^1 r^3 \, dr \, d\theta$ =  $\int_0^{2\pi} \frac{1}{4} r^4 \Big|_{r=0}^1 d\theta = \int_0^{2\pi} \frac{1}{4} d\theta = \frac{\pi}{2}.$

### Integration in Polar Coordinates, IX

#### Integration in Polar Coordinates, IX

Example: Integrate the function  $f(x, y) = x^2 + y^2$  on the region R given by the interior of the unit circle  $x^2 + y^2 \le 1$ .

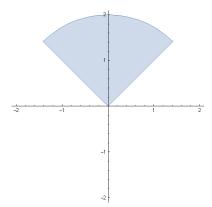
• We could have done this problem in rectangular coordinates. Using the integration order *dy dx*, here is how that goes:

$$\int_{-1}^{1} \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} (x^2 + y^2) \, dy \, dx = \int_{-1}^{1} \left( x^2 y + \frac{1}{3} y^3 \right) \Big|_{y=-\sqrt{1-x^2}}^{\sqrt{1-x^2}} \, dx$$
  
$$= \int_{-1}^{1} 2 \left( x^2 \sqrt{1-x^2} - \frac{1}{3} (1-x^2)^{3/2} \right) \, dx$$
  
$$= \frac{1}{6} \left[ (x+2x^3) \sqrt{1-x^2} + 3\sin^{-1} x \right] \Big|_{x=-1}^{1}$$
  
$$= \pi/2.$$

Note that there is an integration by parts and some trigonometric substitutions (omitted!) needed to get from line 2 to line 3.

Example: Integrate f(x, y) = x + 2y on the region R lying above the lines y = x and y = -x and inside the circle  $x^2 + y^2 = 4$ .

Example: Integrate f(x, y) = x + 2y on the region R lying above the lines y = x and y = -x and inside the circle  $x^2 + y^2 = 4$ . This region is a quarter-disc:



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- To find the limits of integration, we convert the equations for the boundary into polar coordinates and use the picture.
- The line y = x gives the right boundary  $\theta = \pi/4$  and the line y = -x gives the left boundary  $\theta = 3\pi/4$ .
- The circle  $x^2 + y^2 = 4$  becomes r = 2.
- Thus, our limits are  $\pi/4 \le \theta \le 3\pi/4$  and  $0 \le r \le 2$ .
- The function is  $f(x, y) = x + 2y = r \cos \theta + 2r \sin \theta$ , while the area differential, as always, is  $dA = r dr d\theta$ .

• So the integral is 
$$\int_{\pi/4}^{3\pi/4} \int_0^2 (r\cos\theta + 2r\sin\theta) \cdot r \, dr \, d\theta$$

Example: Integrate f(x, y) = x + 2y on the region R lying above the lines y = x and y = -x and inside the circle  $x^2 + y^2 = 4$ .

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• Now we just have to evaluate the integral:

$$\int_{\pi/4}^{3\pi/4} \int_0^2 (r\cos\theta + 2r\sin\theta) \cdot r \, dr \, d\theta = \int_{\pi/4}^{3\pi/4} (\cos\theta + 2\sin\theta) \cdot \frac{1}{3} r^3 \Big|_{r=0}^2 \, d\theta$$
$$= \int_{\pi/4}^{3\pi/4} \frac{8}{3} (\cos\theta + 2\sin\theta) \, d\theta$$
$$= \frac{8}{3} (-\sin\theta + 2\cos\theta) \Big|_{\theta=\pi/4}^{3\pi/4} = \frac{8\sqrt{2}}{3}.$$

We can also convert integrals that have been set up in rectangular coordinates to polar coordinates.

- Of course, usually we only want to do this when the integral will be easier to evaluate in polar coordinates.
- An iterated integral will be easier to evaluate in polar coordinates when the region and function both have reasonably nice descriptions in polar.
- Some obvious signs suggesting polar coordinates are if the function involves  $\sqrt{x^2 + y^2}$  terms, or if the region turns out to be a portion of a circle.

# Integration in Polar Coordinates, XIV

Example: Evaluate 
$$\int_{-2}^{2} \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} \sqrt{x^2 + y^2} \, dy \, dx.$$

Example: Evaluate 
$$\int_{-2}^{2} \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} \sqrt{x^2 + y^2} \, dy \, dx.$$

- Here, the function involves  $\sqrt{x^2 + y^2}$  (in fact, that *is* the function!) and the region is the interior of the circle  $x^2 + y^2 = 4$ , so we will switch to polar coordinates.
- In polar coordinates, the bounds are  $0 \le \theta \le 2\pi$  and  $0 \le r \le 2$ , with function  $f(x, y) = \sqrt{x^2 + y^2} = r$  and differential  $dA = r dr d\theta$ .

• So, in polar, the integral is  

$$\int_{0}^{2\pi} \int_{0}^{2} r \cdot r \, dr \, d\theta = \int_{0}^{2\pi} \int_{0}^{2} r^{2} \, dr \, d\theta = \int_{0}^{2\pi} \frac{8}{3} d\theta = \frac{16\pi}{3}.$$

# Integration in Polar Coordinates, XV

Example: Evaluate the integral 
$$\int_0^1 \int_0^{\sqrt{1-x^2}} e^{\sqrt{x^2+y^2}} dy dx$$
.

### Integration in Polar Coordinates, XV

Example: Evaluate the integral 
$$\int_0^1 \int_0^{\sqrt{1-x^2}} e^{\sqrt{x^2+y^2}} dy dx$$
.

- As before we have various signs (from both the function and the region) suggesting that we should try polar coordinates.
- In polar coordinates, the bounds are  $0 \le \theta \le \pi/2$  and  $0 \le r \le 1$ , with function  $f(x, y) = e^{\sqrt{x^2 + y^2}} = e^r$  and differential  $dA = r \, dr \, d\theta$ .

• So, in polar, the integral is  $\int_{0}^{\pi/2} \int_{0}^{1} e^{r} \cdot r \, dr \, d\theta = \int_{0}^{\pi/2} \left[ r \, e^{r} - e^{r} \right] \Big|_{r=0}^{1} d\theta = \int_{0}^{\pi/2} 1 \, d\theta = \pi/2.$ 

### Integration in Polar Coordinates, XVI

As an application of integration in polar coordinates, we can evaluate the famous Gaussian integral  $I = \int_{-\infty}^{\infty} e^{-x^2} dx$ .

- This integral is quite difficult to compute because the function e<sup>-x<sup>2</sup></sup> does not have an elementary antiderivative. Even using a Taylor series approach (i.e., writing e<sup>-x<sup>2</sup></sup> as a power series in x) does not work, because the integral is improper.
- This integral is fundamental in statistics, since  $p(x) = e^{-x^2}$  arises (after a change of variables) as the probability density function of the Gaussian normal distribution.
- The normal distribution describes the distributions of quantities arising as the sum of independent small variations, such as human heights, errors in measurements, exam grades, and many other physical phenomena.
- To learn more, take Math 3081 (Probability and Statistics)! (Unrelated fun fact: I'm teaching it in summer 2.)

#### Integration in Polar Coordinates, XVII

Here is how to compute  $I = \int_{-\infty}^{\infty} e^{-x^2} dx$ :

- First, we can also write  $I = \int_{-\infty}^{\infty} e^{-y^2} dy$ . Multiplying gives  $I^2 = \left[ \int_{-\infty}^{\infty} e^{-x^2} dx \right] \left[ \int_{-\infty}^{\infty} e^{-y^2} dy \right] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(x^2+y^2)} dy dx.$
- Now convert to polar coordinates: the region for this last integral is the entire plane, with integration bounds
   0 ≤ θ ≤ 2π and 0 ≤ r < ∞.</li>
- The function is  $e^{-(x^2+y^2)} = e^{-r^2}$ , and of course  $dA = r dr d\theta$ .
- Thus, in polar coordinates we see  $I^2 = \int_0^{2\pi} \int_0^\infty e^{-r^2} r \, dr \, d\theta$ .
- We can evaluate the polar integral using a substitution  $u = r^2$ to see  $l^2 = \int_0^{2\pi} \left[\frac{1}{2}e^{-r^2}\right] \Big|_{r=0}^{\infty} d\theta = \int_0^{2\pi} \frac{1}{2}d\theta = \pi.$

• Therefore, since I > 0, we deduce that  $I = \sqrt{\pi}$ .

- This volume is given as a double integral  $\iint_R (16 x^2 y^2) dA$  where R is the region in the plane where the surface  $z = 16 x^2 y^2$  lies above the xy-plane.
- The region R is where  $16 x^2 y^2 \ge 0$ , which is to say, where  $x^2 + y^2 \le 16$ .
- Since this is the interior of a circle, this integral will be easiest to set up in polar coordinates.

### Integration in Polar Coordinates, XIX

#### Integration in Polar Coordinates, XIX

- The region R, in polar, is  $0 \le \theta \le 2\pi$  and  $0 \le r \le 4$ .
- The function is  $f(x, y) = 16 x^2 y^2 = 16 r^2$ , and as always the polar area differential is  $dA = r dr d\theta$ .
- Thus, the volume integral is

$$\int_{0}^{2\pi} \int_{0}^{4} (16 - r^{2}) r \, dr \, d\theta = \int_{0}^{2\pi} \int_{0}^{4} (16r - r^{3}) dr \, d\theta$$
$$= \int_{0}^{2\pi} (8r^{2} - \frac{1}{4}r^{4}) \Big|_{r=0}^{4}$$
$$= \int_{0}^{2\pi} 64 d\theta = 128\pi.$$

#### Integration in Polar Coordinates, XX

Example: Evaluate the double integral  $\iint_R \frac{x^2}{x^2 + y^2} dA$  where R is the region  $2 \le x^2 + y^2 \le 3$  where x > 0.

#### Integration in Polar Coordinates, XX

Example: Evaluate the double integral  $\iint_R \frac{x^2}{x^2 + y^2} dA$  where R is the region  $2 \le x^2 + y^2 \le 3$  where x > 0.

- The region *R*, in polar, is the right half of the annulus between the circles  $r = \sqrt{2}$  and  $r = \sqrt{3}$ .
- The portion with x > 0 corresponds to -π/2 ≤ θ ≤ π/2. (Here it is convenient to use negative θ to avoid splitting the region into 2 pieces.)
- The function is  $\frac{x^2}{x^2 + y^2} = \frac{r^2 \cos^2 \theta}{r^2} = \cos^2 \theta$ , and  $dA = r \, dr \, d\theta$ . • We get  $\int_{-\pi/2}^{\pi/2} \int_{\sqrt{2}}^{\sqrt{3}} \cos^2 \theta \cdot r \, dr \, d\theta = \int_{-\pi/2}^{\pi/2} \cos^2 \theta = \frac{\pi}{2}$ .

For the last week, we have been discussing double integrals. Now we bump our discussion into 3 dimensions with triple integrals.

- Like with double integrals, we outline the fundamental definition using Riemann sums.
- Then (next time) we will discuss how to set up and evaluate triple integrals as iterated integrals.
- After that, we will explain how to do general coordinate changes, and then talk about two very useful 3-dimensional generalizations of polar coordinates: cylindrical coordinates and spherical coordinates.

So, now we want to integrate functions f(x, y, z) over regions in 3-space instead of functions f(x, y) over regions in the plane.

- For clarity, we will use *D* to denote solid regions in 3-space, and reserve *R* for regions in the plane.
- The motivating problem for integration in three variables is somewhat less clear, however.
- For single integrals we wanted to find the area under a curve y = f(x), and for double integrals we wanted to find the volume under a surface z = f(x, y).
- For triple integrals, it is somewhat harder to envision what happens when we move up by 1 dimension: we would then be finding "the 4-dimensional volume under a 3-dimensional hypersurface" (whatever that means!).

One way to interpret what a triple integral represents is to think of a function f(x, y, z) as being the density of a solid object D at a given point (x, y, z).

- Then the triple integral of f(x, y, z) on the region D represents the total mass of the solid.
- We will give some other uses and interpretations of triple integrals later. (Many of the applications are motivated by physics / related areas, such as computing electrical or magnetic flux.)

### Riemann Sums, I

We formalize things using Riemann sums.

#### Definition

For a region D in 3-space, a <u>partition</u> of D into n pieces is a list of disjoint rectangular boxes inside D, where the kth rectangle contains the point  $(x_k, y_k, z_k)$ , has length  $\Delta x_k$ , width  $\Delta y_k$ , height  $\Delta z_k$ , and volume  $\Delta V_k = \Delta z_k \cdot \Delta y_k \cdot \Delta x_k$ .

The <u>norm</u> of the partition P is the largest number among the dimensions of all of the boxes in P.

Then, for a continous function f(x, y, z) and a partition P of the region D, we define the <u>Riemann sum</u> of f(x, y, z) on D

corresponding to P to be  $RS_P(f) = \sum_{k=1} f(x_k, y_k, z_k) \Delta V_k$ .

### Riemann Sums, II

The idea now is that we can define the triple integral of f(x, y, z)on D by taking an appropriate limit of Riemann sums:

#### Definition

For f(x, y, z) a continuous function, we define the (triple) integral of f on the region R,  $\iiint_{D} f(x, y, z) \, dV$ , to be the value of L such that, for every  $\epsilon > 0$ , there exists a  $\delta > 0$  (depending on  $\epsilon$ ) such that for every partition P with  $\operatorname{norm}(P) < \delta$ , we have  $|RS_P(f) - L| < \epsilon$ .

This is essentially the same definition that we had for double integrals. The value  $\iiint_D f(x, y, z) dV$ , roughly speaking, is the limit of the Riemann sums of f on D, as the size of the subregions in the partition becomes small.

### Riemann Sums, III

For C an arbitrary constant and f(x, y, z) and g(x, y, z) continuous functions, the following properties hold:

- 1. Integral of constant:  $\iiint_D C dV = C \cdot \text{Volume}(D)$ .
- 2. Constant multiple of a function:  $\iiint_D C f(x, y, z) \, dV = C \cdot \iiint_D f(x, y, z) \, dV.$
- 3. Addition of functions:

$$\iint_D f(x, y, z) \, dV + \iint_D g(x, y, z) \, dV = \\ \iiint_D [f(x, y, z) + g(x, y, z)] \, dV.$$

4. Subtraction of functions:

$$\iint_D f(x, y, z) \, dV - \iint_D g(x, y, z) \, dV = \\ \iiint_D [f(x, y, z) - g(x, y, z)] \, dV.$$

- 5. Nonnegativity: if  $f(x, y, z) \ge 0$ , then  $\iint_D f(x, y, z) dV \ge 0$ .
- 6. Union: If  $D_1$  and  $D_2$  don't overlap and have union D,  $\iiint_{D_1} f(x, y, z) \, dV + \iiint_{D_2} f(x, y, z) \, dV = \iiint_D f(x, y, z) \, dV.$

Like with double integrals, we will write all of our triple integrals as iterated integrals.

- Computing a triple integral, once we have written it down, is usually straightforward, much like with a double integral.
- Generally, the more difficult part of the problems is setting up the integral, which requires us to sketch the region and figure out the proper bounds of integration.
- To be fair, actully computing a triple integral can involve a lot of algebra and it may take a while to do all the calculations, but there is nothing conceptually harder than what we were doing with iterated double integrals.
- Once we have the iterated integral set up, however, it's just calculation.

To finish today, let's work through the evaluation of an iterated triple integral.

# Iterated Triple Integrals, II

Example: Evaluate the integral 
$$\int_0^1 \int_0^2 \int_1^3 4xz \, dz \, dy \, dx$$
.

#### Iterated Triple Integrals, II

<u>Example</u>: Evaluate the integral  $\int_0^1 \int_0^2 \int_1^3 4xz \, dz \, dy \, dx$ .

• We just work one step at a time, starting from the inside:

$$\int_{0}^{1} \int_{0}^{2} \int_{1}^{3} 4xz \, dz \, dy \, dx = \int_{0}^{1} \int_{0}^{2} (2xz^{2}) \Big|_{z=1}^{3} \, dy \, dx$$
$$= \int_{0}^{1} \int_{0}^{2} 16x \, dy \, dx$$
$$= \int_{0}^{1} (16xy) \Big|_{y=0}^{2} \, dx$$
$$= \int_{0}^{1} 32x \, dx$$
$$= (16x^{2}) \Big|_{x=0}^{1} = 16.$$



We discussed double integrals in polar coordinates. We introduced triple integrals.

Next lecture: Iterated triple integrals.