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0 Elliptic Curves and Modular Forms

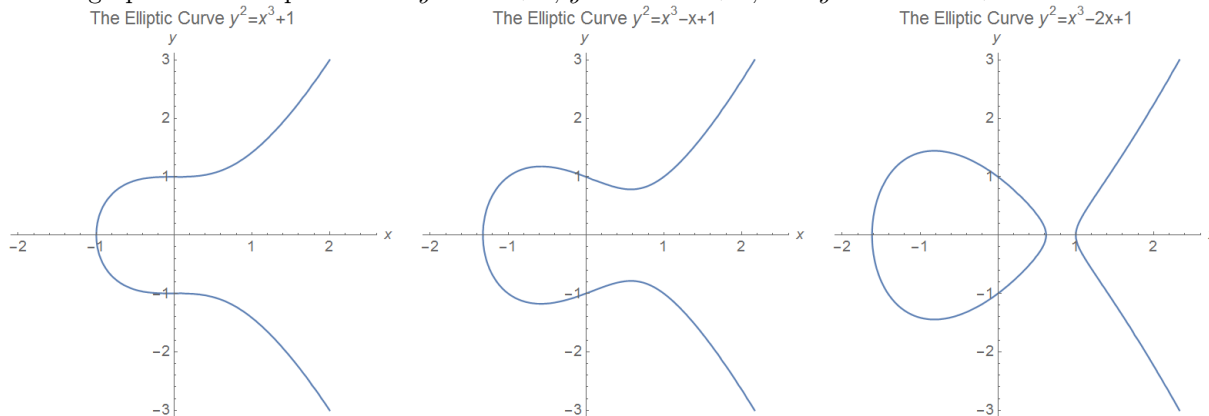
These are lecture notes for the graduate course Math 7359: Elliptic Curves and Modular Forms, taught at Northeastern in Fall 2026.

0.1 (Sep 9) Overview + The Group Law

- The goal of this course is to give an overview of elliptic curves and modular forms, highlighting in particular the modern development of modularity, which establishes a very deep connection between these two otherwise very different classes of objects.
 - Elliptic curves are algebraic curves of genus 1 that arise in a wide variety of contexts in mathematics and their study involves techniques from nearly every discipline: algebra, analysis, geometry, topology, and (of course) number theory.
 - Modular forms are analytic functions on the complex upper half-plane satisfying a certain functional equation, and although they are intrinsically analytic objects, they turn out to have surprisingly deep connections to the (seemingly far more) algebraically-flavored elliptic curves.
 - In particular, the connection between elliptic curves and modular forms is central to Wiles's proof of Fermat's Last Theorem, and one of the goals at the end of the course is to elucidate some of the major ideas of this connection.
- In elementary coordinate geometry, one begins by studying the behavior of lines in the plane, which have the general equation $ax + by + c = 0$, and then afterwards studies quadratic curves (i.e., the conic sections) having the general equation $ax^2 + bxy + cy^2 + dx + ey + f = 0$.
 - In each case, we often perform simple algebraic manipulations and changes of variable to put the equations into a more standard form.

- For example, if $b \neq 0$, we can rewrite $ax + by + c = 0$ as $y = (-a/b)x + (-c/b)$, which for $m = -a/b$ and $b' = -c/b$ has the more familiar form $y = mx + b'$.
- Similarly, if $a \neq 0$, we can perform a change of variable $x' = y + (b/(2a))x$ in the equation $ax^2 + bxy + cy^2 + dx + ey + f = 0$ to remove the cross term bxy , and then we can complete the square in x and in y and then rescale the variables to obtain an equation of the form $x^2 \pm y^2 = 1$ or $y = x^2$, depending on which quadratic coefficients are zero.
- Our goal now is to study cubic curves in the plane, which have the general form $ax^3 + bx^2y + cxy^2 + dy^3 + ex^2 + fxy + gy^2 + hx + iy + j = 0$.
 - Like in the case of quadratic curves above, we can perform various changes of variable to reduce the general form to a simpler one.
 - We will not give the full details of the procedure now, as it relies on some facts about cubic curves that we will prove later.
 - Instead, we will summarize matters by saying that as long as the equation is actually cubic (i.e., it is not the case that all of a, b, c, d are zero), then the general equation above can always be transformed using rational changes of variable into one of the form $y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6$, for appropriate coefficients a_1, a_2, a_3, a_4, a_6 .
- Definition: An elliptic curve E over a field K is a curve having an equation of the form $y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6$, for appropriate coefficients a_1, a_2, a_3, a_4, a_6 in K . This expression is called the Weierstrass form of E .
 - This expression is not the simplest possible one: as long as the characteristic of K is not 2 or 3, we can simplify it further by completing the square in y and completing the cube in x .
 - Explicitly, if we set $y' = y + (a_1/2)x + (a_3/2)$ and $x' = x + (a_2/3)$, we can reduce the Weierstrass equation above to one of the form $(y')^2 = (x')^3 + A(x') + B$.
 - An elliptic curve having an equation of the form $y^2 = x^3 + Ax + B$ is sometimes said to be in “reduced” Weierstrass form.
 - This reduced form is much more amenable for computations, and (in fact) it is nearly unique: the only change of variables that preserves it is one of the form $x = u^2x', y = u^3y'$ for some nonzero u , from which we see that $A = u^4A'$ and $B = u^6B'$.

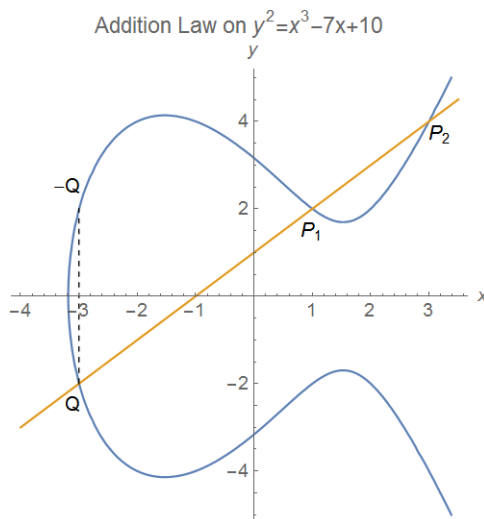
- Here are graphs of the elliptic curves $y^2 = x^3 + 1$, $y^2 = x^3 - x + 1$, and $y^2 = x^3 - 2x + 1$ over $\mathbb{R}$:



- In general, we can see that the graph of an elliptic curve $y^2 = x^3 + Ax + B$ will always be symmetric about the x -axis, since if (x, y) satisfies the equation then so does $(x, -y)$. The graph will also have either one or two connected components according to the number of real roots that $x^3 + Ax + B$ has.
- Exercise: Show that graph of an elliptic curve over $\mathbb{R}$ will have two components when the polynomial $x^3 + Ax + B$ has three distinct real roots, and will have one component otherwise.

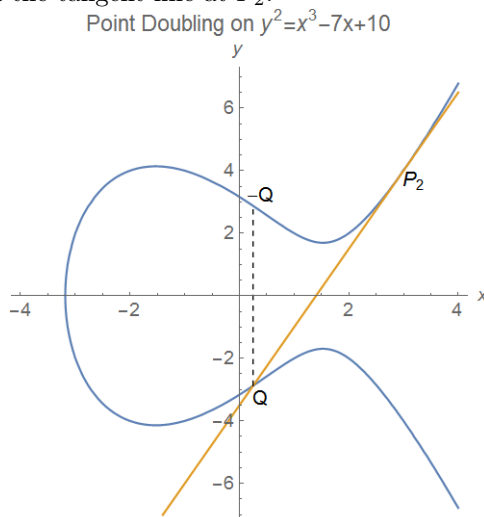
- Notice also that the tangent line at each crossing of the x -axis is vertical for each curve above. Using implicit differentiation, we can compute $y' = \frac{3x^2 + A}{2y}$: thus, we see that $y' = \infty$ when y is zero, provided that $3x^2 + A$ is not also zero. This behavior can only occur when $x^3 + Ax + B$ has a root in common with its derivative $3x^2 + A$, which is in turn equivalent to saying that $x^3 + Ax + B$ has a double root.
- Definition: If the polynomial $x^3 + Ax + B$ has a repeated root, we say that the elliptic curve $y^2 = x^3 + Ax + B$ is singular. Otherwise (if the roots are distinct) we say the elliptic curve is nonsingular. A curve is singular if and only if its discriminant $\Delta = -16(4A^3 + 27B^2)$ is zero.
 - The second statement follows from the observations above: the polynomial $x^3 + Ax + B$ has a repeated root if and only if it has a root in common with its derivative $3x^2 + A$. This occurs precisely when $x^2 = -A/3$, from which we see that $x(2A/3) + B = 0$ so $x = -3B/(2A)$: then substituting for x yields $\Delta = 0$ almost immediately.
 - Remark: The presence of the constant -16 is superfluous here, but there is also a definition of Δ in terms of the original coefficients a_1, a_2, a_3, a_4, a_6 for a general Weierstrass form. To avoid having denominators in that expression, we end up needing an extra factor of -16 in the one we gave above.
- The core property of elliptic curves that makes them so interesting is that if we have two points that lie on the curve, we can use them to construct a third point on the curve.
 - Explicitly, suppose $P_1 = (x_1, y_1)$ and $P_2 = (x_2, y_2)$ are two distinct points on an elliptic curve E : $y^2 = x^3 + Ax + B$.
 - Draw the line through P_1 and P_2 : we claim that this line L must intersect E in a third point Q .
 - To see this, suppose the line through P_1 and P_2 has equation $y = mx + b$. (We are tacitly excluding the possibility that the line is vertical, but we will come back to this case in a moment.)
 - Then the intersection points between L and E are the solutions to the system $y = mx + b$ and $y^2 = x^3 + Ax + B$. Equivalently, we must solve $(mx + b)^2 = x^3 + Ax + B$, or $x^3 + (-m^2)x^2 + (A - 2mb)x + (B - b^2) = 0$.
 - However, we already know that this cubic has the two roots $x = x_1$ and $x = x_2$, so it must have a third root: this gives us the third point Q we wanted.
- Once we construct a third point on an elliptic curve this way, we might try to find more points.
 - If we try this procedure directly using our points P_1 , P_2 , and Q , however, we will not get anywhere: the line through any of these two points intersects the elliptic curve at the other point.
 - However, we can also exploit the vertical symmetry of the curve to make new points: if $P = (x, y)$ lies on the curve, then the point $-P = (x, -y)$ also lies on the curve.
 - If we combine these two procedures, we can often generate many points on the curve starting from just two.
- Definition (Group Law I): If P_1 and P_2 are two distinct points on the elliptic curve E : $y^2 = x^3 + Ax + B$, let $Q = (x', y')$ be the third intersection point of E with the line L joining P_1 and P_2 . We define the sum $P_1 + P_2$ to be the point $-Q = (x', -y')$.
 - It is not immediately clear why we define the sum of two points to be the reflection of Q rather than Q itself. This will become clearer in a moment.
 - Note that if we attempt to add two points which are vertical reflections of one another on the graph of $y^2 = x^3 + Ax + B$, the resulting line will not intersect the curve again.
 - To remedy this, we declare that the curve also includes a point at ∞ , which we denote simply as ∞ , that we consider as lying on any vertical line. (What we are really doing here is working with the projective model of the curve, rather than the affine one.)
- Example: Given the points $P_1 = (1, 2)$ and $P_2 = (3, 4)$ on the elliptic curve $y^2 = x^3 - 7x + 10$, find the sums $P_1 + P_2$ and $(P_1 + P_2) + P_2$.

- It is easy to verify that both points lie on the curve. Here is a plot of the curve and the line $y = x + 1$ through the two points:



- The point Q lies on the intersection of $y = x + 1$ and $y^2 = x^3 - 7x + 10$, so $(x + 1)^2 = x^3 - 7x + 10$.
- This equation is equivalent to $x^3 - x^2 - 9x + 9 = 0$, which factors as $(x - 1)(x - 3)(x + 3) = 0$. Then the x -coordinate of Q is -3 so $Q = (-3, -2)$.
- Thus, the sum $P_1 + P_2$ is the vertical reflection of Q , which is $\boxed{(-3, 2)}$.
- To find the sum $(P_1 + P_2) + P_2$ we perform a similar procedure: the line through $P_1 + P_2$ and P_2 has equation $y = \frac{1}{3}x + 3$.
- Then we must solve $(\frac{1}{3}x + 3)^2 = x^3 - 7x + 10$, or $x^3 - \frac{1}{9}x^2 - 9x + 1 = 0$.
- Factoring yields $(x - \frac{1}{9})(x + 3)(x - 3) = 0$, so $Q' = (\frac{1}{9}, \frac{82}{27})$, and thus $(P_1 + P_2) + P_2 = \boxed{(\frac{1}{9}, -\frac{82}{27})}$.
- We would also like to be able to add a point to itself.
 - It is straightforward to see from our definition that if P_1 and P_2 are distinct points, then $P_1 + P_2$ is a continuous function of the coordinates of the points.
 - If we are working over $\mathbb{R}$, or another field where limits exist, we could define the addition $P + P$ to be the limit as $P_1 \rightarrow P$ of sums $P + P_1$. Geometrically, the lines used in the construction also have a limit as $P \rightarrow P_1$: they approach the tangent line to the curve E at the point P .
 - Since we want a definition over any field, we define $P + P$ by letting L be the tangent line to E at P , and then taking Q to be the third point of intersection of L with E .
- Definition (Group Law II): If P is any point on the elliptic curve $E : y^2 = x^3 + Ax + B$, let $Q = (x', y')$ be the third intersection point of E with the tangent line L to E at P . We define the sum $P + P$ to be the point $-Q = (x', -y')$.
- Example: Given the points $P_1 = (1, 2)$ and $P_2 = (3, 4)$ on the elliptic curve $y^2 = x^3 - 7x + 10$, find the sums $P_2 + P_2$ and $(P_1 + P_2) + P_2$.
 - Differentiating implicitly yields $2yy' = 3x^2 - 7$ so that $y' = (3x^2 - 7)/(2y)$. Thus, the tangent line to E at P_2 has slope $\frac{5}{2}$ and its equation is $y = \frac{5}{2}x - \frac{7}{2}$.

- Here is a plot of the curve and the tangent line at P_2 :



- The point Q lies on the intersection of $y = \frac{5}{2}x - \frac{7}{2}$ and $y^2 = x^3 - 7x + 10$, so $(\frac{5}{2}x - \frac{7}{2})^2 = x^3 - 7x + 10$.
- This equation is equivalent to $x^3 - \frac{25}{4}x^2 + \frac{21}{2}x - \frac{9}{4} = 0$, which factors as $(x - \frac{1}{4})(x - 3)(x - 3) = 0$.
- Then the x -coordinate of Q is $1/4$ so $Q = (\frac{1}{4}, -\frac{23}{8})$, and so $P_2 + P_2 = \boxed{(\frac{1}{4}, \frac{23}{8})}$.
- To find the sum $P_1 + (P_2 + P_2)$ we then find the sum of $P_1 = (1, 2)$ with $(\frac{1}{4}, \frac{23}{8})$. The line through these points is $y = -\frac{7}{6}x + \frac{19}{6}$.
- Then we must solve $(-\frac{7}{6}x + \frac{19}{6})^2 = x^3 - 7x + 10$, which has solutions $x = \frac{1}{9}, \frac{1}{4}, 1$.
- Then $Q' = (\frac{1}{9}, \frac{82}{27})$, and thus $P_1 + (P_2 + P_2) = \boxed{(\frac{1}{9}, \frac{82}{27})}$.
- Note that in the previous two examples, we computed $(P_1 + P_2) + P_2 = (\frac{1}{9}, -\frac{82}{27}) = P_1 + (P_2 + P_2)$, and so we see in this case that the addition law is actually associative. Much more is true:
- Theorem (Group Law): If K is any field and E is any elliptic curve defined over K , then under the addition law defined above, the set of K -valued points on E forms an abelian group with identity ∞ and with the inverse of any point P given by $-P$.
 - We will give arguments for an elliptic curve of the form $y^2 = x^3 + Ax + B$, but the theorem holds in full generality for any elliptic curve.
 - Proof: The addition law is commutative, since the line used in computing $P_1 + P_2$ and $P_2 + P_1$ is the same in each case.
 - To see that ∞ is an identity, consider the sum $P + \infty$. The line passing through P and ∞ is the vertical line through P which also intersects E at the point $-P$. Then by the geometric definition, $P + \infty = -(-P) = P$.
 - To see that $-P$ is an inverse of P , observe that the line passing through P and $-P$ is a vertical line, so the other point on it is ∞ . The reflection of ∞ is also ∞ , so $P + (-P) = \infty$.
 - Associativity of the addition law is the only nontrivial result in this theorem. It can be done with a tedious algebraic computation using explicit formulas for the addition law (see below).
 - We give another argument using the following consequence of basic linear algebra: if C_1 and C_2 are two distinct plane cubics intersecting in 9 points, then any other cubic D passing through 8 of them must be a linear combination of C_1 and C_2 hence also pass through the 9th point.

- To prove this we merely observe that the vector space of all equations of cubic curves is 10-dimensional and each point imposes one linear condition, so the space of equations passing through 8 given points is 2-dimensional by the nullity-rank theorem (this also requires checking that the linear conditions are independent, which we omit). Since C_1 and C_2 are distinct their equations yield a basis for this space, and so any other cubic D is a linear combination. In particular, then, since the 9th point satisfies the equation for both C_1 and C_2 , it also satisfies the equation for any linear combination.
- So suppose P_1, P_2, P_3 are points on an elliptic curve E . Construct the following lines:
 L_1 through P_1, P_2, S L_2 through $-S, P_3, T$ L_3 through $\infty, U, -U$
 M_1 through $\infty, S, -S$ M_2 through P_2, P_3, U M_3 through $-U, P_1, T'$
- Then $-T = (P_1 + P_2) + P_3$ and $-T' = P_1 + (P_2 + P_3)$, so we wish to show that $T = T'$.
- Let C_1 be the cubic $L_1 L_2 L_3$ and C_2 be the cubic $M_1 M_2 M_3$ (by which we mean, write down the cubic equation $(ax+by+c)(a'x+b'y+c')(a''x+b''y+c'') = 0$ obtained by multiplying together the corresponding equations for the lines).
- Then C_1 and E both pass through the 9 points $P_1, P_2, P_3, S, -S, \infty, U, -U$, and T . Since C_2 also passes through the first 8 of these points, it must also pass through the 9th, which is T .
- But since C_2 and E can only intersect in at most 9 points by Bézout's theorem¹, and these 9 points are $P_1, P_2, P_3, S, -S, \infty, U, -U$, and T' , we must have $T' = T$.
- For convenience in doing numerical computations, we will also write down the general formula for the group law on any reduced Weierstrass curve:
- **Proposition (Explicit Group Law):** Let $P_1 = (x_1, y_1)$ and $P_2 = (x_2, y_2)$ be points on the elliptic curve $E: y^2 = x^3 + Ax + B$. Then $P_1 + P_2 = (x_3, y_3)$ where $x_3 = m^2 - x_1 - x_2$ and $y_3 = -m(x_3 - x_1) - y_1$, with $m = \begin{cases} (y_2 - y_1)/(x_2 - x_1) & \text{if } P_1 \neq P_2 \\ (3x_1^2 + A)/(2y_1) & \text{if } P_1 = P_2 \end{cases}$. If m is infinite, then $P_1 + P_2 = \infty$.
 - Observe in particular that the addition formula is rational, in the sense that the result is always a rational function of the inputs. In particular, the sum of two points whose coordinates lie in a field K will also lie in K .
 - **Proof:** If $P_1 \neq P_2$ then the line joining P_1 and P_2 has equation $y - y_1 = m(x - x_1)$ where $m = \frac{y_2 - y_1}{x_2 - x_1}$.
 - We therefore obtain the equation $(mx - mx_1 + y_1)^2 = x^3 + Ax + B$, which has the form $x^3 - m^2x^2 + Cx + D = 0$ for appropriate constants C and D .
 - The polynomial $x^3 - m^2x^2 + Cx + D$ must factor as $(x - x_1)(x - x_2)(x - x_3)$, so upon multiplying out we see that $x_1 + x_2 + x_3 = m^2$. This yields the stated value of x_3 , and then $y_3 = m(x_3 - x_1) + y_1$ (where we have multiplied by -1 to account for the vertical reflection).
 - If $P_1 = P_2$ then everything is the same, except instead m is the slope of the tangent line at P_1 . By implicit differentiation, we see that $2yy' = 3x^2 + A$ so $m = \frac{3x_1^2 + A}{2y_1}$ here, as claimed.
- **Example:** If $P_1 = (1, 3)$ and $P_2 = (0, 2)$ on the elliptic curve $y^2 = x^3 + 4x + 4$ over $\mathbb{F}_5$ (i.e., with coefficients mod 5), find $P_1 + P_2$ and $P_1 + P_1$.
 - We simply apply the appropriate formulas: adding $Q_1 = (x_1, y_1)$ to $Q_2 = (x_2, y_2)$ produces (x_3, y_3) where $x_3 = m^2 - x_1 - x_2$ and $y_3 = -m(x_3 - x_1) - y_1$, and $m = \begin{cases} (y_2 - y_1)/(x_2 - x_1) & \text{if } Q_1 \neq Q_2 \\ (3x_1^2 + A)/(2y_1) & \text{if } Q_1 = Q_2 \end{cases}$.
 - With $(x_1, y_1) = (1, 3)$ and $(x_2, y_2) = (0, 2)$ we obtain $m = \frac{2 - 3}{0 - 1} = 1$, so $x_3 = 0$ and $y_3 = -1(0 - 1) - 3 = 3$, so $P_1 + P_2 = \boxed{(0, 3)}$.

¹Bézout's theorem states that two plane curves of degrees m and n not sharing a common component will intersect in mn points over an algebraically closed field, counting multiplicities. Applied when $m = n = 3$, we see that two plane cubics intersect in 9 points (over an algebraically closed field, counting multiplicities).

- Likewise, with $(x_1, y_1) = (x_2, y_2) = (1, 3)$ we obtain $m = \frac{3+4}{2 \cdot 3} = 2$, so $x_3 = 2$ and $y_3 = -2(2-1)-3 = 0$, so $P_1 + P_1 = \boxed{(2, 0)}$.
- We will also remark that there are formulas for the addition law on a more general elliptic curve $y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6$.
 - We use the same geometric construction as for an elliptic curve in reduced Weierstrass form $y^2 = x^3 + Ax + B$, namely, by taking the additive inverse of a point P to be the other point on the (vertical) line joining P to ∞ , and by taking the sum $P_1 + P_2$ to be the additive inverse of the other point on the line joining P_1 and P_2 (which is the tangent line when $P_1 = P_2$).
- (Tedious) Exercise: Suppose E is an elliptic curve with a Weierstrass equation $y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6$ with $P_1 = (x_1, y_1)$ and $P_2 = (x_2, y_2)$ on E . Show that the additive inverse is given by $-P_1 = (x_0, -y_0 - a_1x_0 - a_3)$, and the sum $P_1 + P_2$ is given by ∞ when $x_1 = x_2$ and $y_1 = -y_2 - a_1x_2 - a_3$ and by (x_3, y_3) where $x_3 = m^2 + a_1m - a_2 - x_1 - x_2$ and $y_3 = -(m + a_1)x_3 - b - a_3$ where $y = mx + b$ is the line joining P_1 and P_2 (or the tangent line when $P_1 = P_2$), which explicitly has $m = \frac{y_2 - y_1}{x_2 - x_1}$, $b = \frac{x_2y_1 - x_1y_2}{x_2 - x_1}$ when $P_1 \neq P_2$ and has $m = \frac{3x_1^2 + 2a_2x_1 + a_4 - a_1y_1}{2y_1 + a_1x_1 + a_3}$ and $b = \frac{-x_1^3 + a_4x_1 + 2a_6 - a_3y_1}{2y_1 + a_1x_1 + a_3}$ when $P_1 = P_2$.
- Now that we have established the group law, we can now (attempt to) compute the abelian group structure of the set of points on a given elliptic curve over a field K .
- Definition: If E is an elliptic curve with coefficients lying in a field K , we define the set $E(K)$, the K -rational points on E , to be the set of points on E whose entries lie in K , along with the point ∞ .
 - When K is finite, clearly $E(K)$ must also be finite, in which case (in principle) we can simply list all of the elements of $E(K)$ and write down the group structure explicitly.
- Example: Find all of the points on the elliptic curve $y^2 = x^3 + 4x + 4$ over $\mathbb{F}_3$ and identify the group structure explicitly.
 - By simply computing $x^3 + 4x + 4$ for each $x \in \mathbb{F}_3$ and testing which are squares we can see that there are 4 points on E : $(0, 1)$, $(0, 2)$, $(1, 0)$, and ∞ .
 - The group of points is therefore either cyclic and isomorphic to $\mathbb{Z}/4\mathbb{Z}$, or isomorphic to the Klein 4-group $(\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/2\mathbb{Z})$, but since $(0, 1) + (0, 1) = (1, 0)$ is not the identity, in fact the group must be cyclic and generated by $(0, 1)$.
- Exercise: Pick an elliptic curve in Weierstrass form (e.g., $y^2 = x^3 + 4x + 1$) and after checking whether it is nonsingular, find all of its points over $\mathbb{F}_3$, $\mathbb{F}_5$, $\mathbb{F}_7$, $\mathbb{F}_{11}$, and $\mathbb{F}_{13}$, and identify the group structure explicitly in each case.
- We have some additional notation useful when computing orders of elements:
- Definition: If P is a point on an elliptic curve E , we define the multiples of P as $[n]P = \underbrace{P + P + \cdots + P}_{n \text{ terms}}$ for positive integers n , with $[0]P = \infty$ and $[-n]P = -[n]P$. The subgroup of $E(K)$ generated by P is then simply the set $\{[n]P : n \in \mathbb{Z}\}$, and as usual the order of P is the cardinality of this set.
 - Trivially, ∞ is the only point of order 1 on E .
 - The first nontrivial case is to identify the points of order 2: these points satisfy $P + P = \infty$. Geometrically, this means that the tangent line to the graph of E at P passes through $-\infty = \infty$, meaning that the tangent line at P is vertical. From the explicit formula $2yy' = 3x^2 + A$ we see that this is, in turn, equivalent to saying that $y = 0$.
 - Therefore, the points (x, y) of order 2 are those having $y = 0$. Since this requires $x^3 + Ax + B = 0$, we see that there are at most 3 such points.

- For points of order 3, we see that such points P satisfy $P + P + P = \infty$ so that $P + P = -P$, which means that the third intersection point of the tangent line to E at P also goes through P . Equivalently, this says that the point P is an inflection point of the curve.
- We can be more precise if we work with the subgroup of $E(K)$ consisting of all m -torsion points together:
- Definition: The m -torsion subgroup of an elliptic curve E defined over K is the kernel of the multiplication-by- m map (i.e., the points $P \in E(K)$ with $[m]P = \infty$) and is denoted $E_K[m]$.
 - Later, we will also be interested in the full group of m -torsion points on E when we consider E as being defined over the algebraic closure $\bar{K}$: this full m -torsion group is denoted $E[m]$.
- Example: Find the points of order 2 on the elliptic curve $E : y^2 = x^3 + x$ over $\mathbb{Q}$ and over $\mathbb{C}$, and identify the group structure of the 2-torsion group $E[2]$ over each field.
 - From the discussion above, the 2-torsion points are the points with $y = 0$, which requires $x^3 + x = 0$ so that $x = 0$ or $x = \pm i$.
 - Over $\mathbb{Q}$, there is therefore one 2-torsion point $\boxed{(0, 0)}$. Then the 2-torsion group $E_{\mathbb{Q}}[2]$ is $\{\infty, (0, 0)\}$ and its group structure is isomorphic to $\mathbb{Z}/2\mathbb{Z}$.
 - Over $\mathbb{C}$ we have three 2-torsion points: $\boxed{(0, 0), (i, 0), (-i, 0)}$. Then the 2-torsion group $E_{\mathbb{C}}[2]$ is $\{\infty, (0, 0), (i, 0), (-i, 0)\}$. Since all of the nontrivial elements in this group have order 2, the group structure is isomorphic to the Klein 4-group $V_4 \cong (\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/2\mathbb{Z})$.
- For points of higher order, it is more difficult to give nice geometric or algebraic descriptions of $E[m]$ directly from the definition.
 - As we will show later using complex lattices, for any elliptic curve defined over (a subfield of) $\mathbb{C}$, the m -torsion subgroup $E[m]$ is always isomorphic to $(\mathbb{Z}/m\mathbb{Z}) \times (\mathbb{Z}/m\mathbb{Z})$, and the same is true more generally in any field of characteristic zero.
 - Exercise: Show that for an elliptic curve $y^2 = x^3 + Ax + B$ over $\mathbb{C}$, the 2-torsion subgroup $E[2]$ is always isomorphic to the Klein 4-group $V_4 \cong (\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/2\mathbb{Z})$.
 - Exercise: Show that for an elliptic curve $y^2 = x^3 + Ax + B$ over $\mathbb{C}$, the 3-torsion subgroup $E[3]$ is always isomorphic to $(\mathbb{Z}/3\mathbb{Z}) \times (\mathbb{Z}/3\mathbb{Z})$. [Hint: If $P = (x, y)$, write out the x -coordinate of $2P$.]

0.2 (Sep 14) The Nagell-Lutz Theorem and Mazur's Theorem

- The following theorem of Nagell and Lutz provides a convenient way to calculate the torsion points on any elliptic curve over $\mathbb{Q}$:
- Theorem (Nagell-Lutz): Suppose E is an elliptic curve over $\mathbb{Q}$ with Weierstrass equation $y^2 = x^3 + Ax + B$ where A and B are integers, and let $D = -4A^3 - 27B^2$ be the reduced discriminant of E . If $P = (x, y)$ is a rational point of finite order, then x and y are integers. Furthermore, either $y = 0$ or y^2 divides D .
 - Exercise: Show that by making an appropriate change of variables, any rational Weierstrass form can be converted into one with A, B integers. Illustrate by finding a Weierstrass form with integer coefficients for $y^2 = x^3 + \frac{3}{2}x + \frac{2}{5}$.
 - We emphasize here that the Nagell-Lutz theorem is not an if-and-only-if: there can exist points (x, y) with y dividing D that do not have finite order.
 - To prove the theorem we will assemble a few preliminary lemmas.
- Lemma 1: Let $P = (x, y)$ be a point on an elliptic curve E over $\mathbb{Q}$ such that P and $[2]P$ both have integral coordinates. Then either $y = 0$ or y^2 divides the reduced discriminant of E .
 - Proof: If $[2]P = \infty$ then from our discussion of 2-torsion points we see that $y = 0$.

- Otherwise assume $[2]P \neq \infty$. If E has Weierstrass equation $y^2 = x^3 + Ax + B$, then by the explicit group law formula the x -coordinate of $[2]P$ is $\frac{(3x^2 + A)^2}{4y^2} - 2x$. Since this quantity is an integer by hypothesis, we must have $y|(3x^2 + A)$.
- Now we invoke the identity $D = 27(x^3 + Ax - B)(x^3 + Ax + B) - (3x^2 + 4A)(3x^2 + A)^2$, which can be derived by applying the Euclidean algorithm in $\mathbb{Z}[x]$ to $x^3 + Ax + B$ and the square of its derivative $(3x^2 + A)^2$.
- Since y^2 divides both $x^3 + Ax + B = y^2$ and $(3x^2 + A)^2$, it divides Δ , as claimed.
- We now record some facts about the coordinates of $[m]P$:
- (Tedious) Exercise: Let E be an elliptic curve and $P = (x, y)$ be a point on E . Define the polynomials $\varphi_0 = 0$, $\varphi_1 = 1$, $\varphi_2 = 2y$, $\varphi_3 = 3x^4 + 6Ax^2 + 12Bx - A^2$, $\varphi_4 = 4y(x^6 + 5Ax^4 + 20Bx^3 - 5A^2x^2 - 4ABx - 8B^2 - A^3)$, and in general $\varphi_{2n+1} = \varphi_{n+2} \cdot \varphi_n^3 - \varphi_{n-1}\varphi_{n+1}$ and $\varphi_{2n} = \frac{\varphi_n}{2y} \cdot (\varphi_{n+2}\varphi_{n-1}^3 - \varphi_{n-2}\varphi_{n+1}^2)$ for $n \geq 2$.
 1. With $y^2 = x^3 + Ax + B$, show that φ_n can be written as a polynomial in $\mathbb{Z}[x, A, B]$ when n is odd and can be written as y times a polynomial in $\mathbb{Z}[x, A, B]$ when n is even.
 2. Show that φ_n^2 is a polynomial of degree $n^2 - 1$ in x with leading coefficient n^2 while $x\varphi_n^2 - \varphi_{n-1}\varphi_{n+1}$ is a polynomial of degree n^2 in x with leading coefficient 1.
 3. Show that the coordinates of $[n]P$ are (x_n, y_n) where $x_n = \frac{x\varphi_n^2 - \varphi_{n-1}\varphi_{n+1}}{\varphi_n^2}$ and $y_n = \frac{\varphi_{n+2}\varphi_{n-1}^2 - \varphi_{n-2}\varphi_{n+1}^2}{4y\varphi_n^3}$.
- Lemma 2: If E is an elliptic curve over $\mathbb{Q}$ and P is a point on E such that $[m]P$ has integral coordinates for some $m \geq 1$, then P itself has integral coordinates.
 - Proof: Suppose that $P = (s/t, y)$ where s and t are relatively prime and $t > 0$. By the exercise above, x_m is the quotient of a monic polynomial of degree n^2 in x by a polynomial of degree at most $n^2 - 1$ in x .
 - This means that the value of the numerator polynomial $x\varphi_n^2 - \varphi_{n-1}\varphi_{n+1}$ is of the form a/t^{n^2} with a, t relatively prime, while the denominator polynomial is of the form b/t^{n^2-1} for some b . But then x_m is of the form $a/(tb)$ which cannot be an integer unless $t = 1$. Then the x -coordinate of P is integral, so then since $y^2 = x^3 + Ax + B$ is an integer and y is rational, y is also integral, as required.
- Lemma 3: If $P = (x, y)$ has rational coordinates on $E : y^2 = x^3 + Ax + B$, then $(x, y) = (q/d^2, s/d^3)$ for some positive integer d and some integers p, r relatively prime to d .
 - Proof: Letting $x = q/r$ and $y = s/t$ in lowest terms with $r, t > 0$ and clearing denominators in $y^2 = x^3 + Ax + B$ yields $s^2r^3 = t^2(q^3 + Ar^2p + Br^3)$.
 - Then r is relatively prime to $q^3 + Ar^2p + Br^3$ hence r^3 divides t^2 , and likewise t is relatively prime to s^2 hence t^2 divides r^3 . Thus $t^2 = r^3$ so letting $d = t/r$ we see $r = d^2$ and $t = d^3$, as required.
- We can now assemble the results for a proof of Nagell-Lutz:
 - Proof (of Nagell-Lutz): Suppose $P = (x, y)$ is a torsion point on E . We first show that P has integer coordinates.
 - Let p be a prime divisor of m and consider $Q = [m/p]P$, which is a torsion point of order p . By Lemma 2 it suffices to show that $Q = (x_Q, y_Q)$ has integer coordinates, since this would imply that P itself has integer coordinates.
 - If $p = 2$ then $[2]Q = \infty$ which requires $y_Q = 0$ so that $x_Q^3 + Ax_Q + B = 0$ so that x_Q is integral by the rational root test; then y_Q is also necessarily integral since it is rational and its square is the integer $x_Q^3 + Ax_Q + B$.
 - Otherwise suppose p is odd. Since $[p]Q = \infty$, the denominator term φ_p of the x -coordinate must vanish when evaluated at x_Q . But for fixed integers A and B and odd p , φ_p is a polynomial in x with integer coefficients of degree $(p^2 - 1)/2$ and leading coefficient p .

- By Lemma 3, in lowest terms we have $x_Q = q/d^2$ for some integer d , so since $\varphi_p(x) = px^{(p^2-1)/2} + O(x^{(p^2-3)/2})$, we see that $d^{p^2-1}\varphi_p(q/d^2) = p \cdot q^{(p^2-1)} + d^2 \cdot k$ for an integer k . Since this quantity must be zero and p is prime, this requires d^2 to divide p , and hence $d = 1$. This means x_Q is an integer, hence so is y_Q by the argument used above. Thus Q is integral and hence P is integral by Lemma 2.
 - By repeating the same argument for $[2]P$ we see that $[2]P$ is also integral. Then, finally, by Lemma 1, we conclude that either $y = 0$ or y^2 divides the reduced discriminant of E , as desired.
- The result of the Nagell-Lutz theorem gives us a very effective way to compute all of the torsion points on E : simply find all possible (x, y) on E where $y = 0$ or y^2 divides D , and then test whether these points have finite order.
 - A priori*, a rational point P could potentially have very large order, but since the torsion points form a subgroup and we have just listed all of the possible elements of this group, we have an upper bound on the possible order of the group and hence on the possible order of P .
 - More efficiently, to test whether P has finite order, we could simply compute the list $\{P, [2]P, [3]P, [4]P, \dots\}$, or even just $\{P, [2]P, [4]P, [8]P, \dots\}$: if any of the multiples of P fail to land on our list, then P cannot have finite order; otherwise, the multiples of P must necessarily repeat since our list is finite, in which case P (and all of its multiples) does have finite order.
- Example: Find the rational torsion points on the elliptic curve $E : y^2 = x^3 - 4x + 3$ and identify their group structure.
 - Here, we have $A = -4$ and $B = 3$, so the discriminant is $D = -4A^3 - 27B^2 = 13$.
 - Since D is squarefree, the only possible y -coordinates are 0 and ± 1 .
 - Testing $y = 0$ (so that $x^3 - 4x + 3 = 0$) yields a single rational solution $x = 1$, giving a 2-torsion point $(1, 0)$.
 - Testing $y = \pm 1$ (so that $x^3 - 4x + 3 = \pm 1$) yields no rational solutions in either case, as the resulting cubic is irreducible.
 - Therefore, we see that there are two rational torsion points on E : $\boxed{(1, 0) \text{ and } \infty}$. The torsion group has order 2 and is isomorphic to $\mathbb{Z}/2\mathbb{Z}$.
- Example: Find the rational torsion points on the elliptic curve $E : y^2 = x^3 - 351x + 1890$ and identify their group structure.
 - Here, we have $A = -351$ and $B = 1890$, so the discriminant is $D = -4A^3 - 27B^2 = 2^4 3^{14}$.
 - Then the possible y -coordinates are 0 and $\pm 2^a 3^b$ for $a \in \{0, 1, 2\}$ and $b \in \{0, 1, 2, 3, 4, 5, 6, 7\}$.
 - If $y = 0$ then we obtain three 2-torsion points, namely $(-21, 0)$, $(6, 0)$, $(15, 0)$.
 - For the other 24 possible values of y , some computation yields four additional candidate points: $(-3, \pm 54)$ and $(33, \pm 162)$.
 - With $P = (33, 162)$ we can compute $[2]P = (15, 0)$, $[3]P = (33, -162)$, and $[4]P = \infty$, so this point has order 4.
 - Likewise, with $Q = (-3, 54)$ we can compute $[2]Q = (15, 0)$, $[3]Q = (-3, -54)$, and $[4]Q = \infty$, so this point also has order 4.
 - Thus, there are eight rational torsion points on E : $\boxed{(-3, \pm 54), (33, \pm 162), (-21, 0), (6, 0), (15, 0), \text{ and } \infty}$. The torsion group has order 8 and is isomorphic to $(\mathbb{Z}/4\mathbb{Z}) \times (\mathbb{Z}/2\mathbb{Z})$, where we can take (a, b) mapping to $[a]P + [b](Q - P)$.
- We can also use the Nagell-Lutz theorem to establish that a given point has infinite order on E .
 - Most obviously, if a rational point does not have integral coordinates, then it is not a torsion point. Even if its coordinates are integral, if its y -coordinate is nonzero and its square does not divide D , then the point cannot be a torsion point.

- Furthermore, even if all of these conditions are satisfied, if we compute $[2]P, [3]P, [4]P, \dots$ and any of these points have non-integral coordinates or have a nonzero y -coordinate with y^2 not dividing D , then P must have infinite order.
- Example: Show that the elliptic curve $E : y^2 = x^3 + 2$ has infinitely many rational points.
 - Testing small values of x reveals two integral points: $(x, y) = (-1, \pm 1)$.
 - If we take $P = (-1, -1)$, then P could be a torsion point, since its y -coordinate -1 has its square dividing the discriminant $D = -108$.
 - However, we can calculate $[2]P = (17/4, 71/8)$, and so since $[2]P$ does not have integral coordinates, it is not a torsion point, and thus neither is P .
 - This means that P has infinite order, which is to say, all of the points $P, [2]P, [3]P, [4]P, \dots$ are distinct. Since these all have rational coordinates, we see that E has infinitely many rational points.
 - Indeed (though this is much harder to prove) the group of rational points on E is generated by P .
- It follows from the Nagell-Lutz theorem that the group of rational torsion points on an elliptic curve is always finite, since there are only finitely many points with $y = 0$ or y^2 dividing D .
 - Although it may seem that the group could potentially be arbitrarily large, in fact, it cannot have order greater than 16.
 - The following quite deep theorem of Mazur establishes that there is a fairly small list of possible torsion groups:
- Theorem (Mazur): If E is an elliptic curve, then the number of rational torsion points can be any integer from 1 to 12 inclusive, excluding 11, or 16. More explicitly, there are 15 possible group structures for the rational torsion points: the trivial group (order 1), $\mathbb{Z}/2\mathbb{Z}$ (order 2), $\mathbb{Z}/3\mathbb{Z}$ (order 3), $(\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/2\mathbb{Z})$ or $\mathbb{Z}/4\mathbb{Z}$ (order 4), $\mathbb{Z}/5\mathbb{Z}$ (order 5), $\mathbb{Z}/6\mathbb{Z}$ (order 6), $\mathbb{Z}/7\mathbb{Z}$ (order 7), $(\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/4\mathbb{Z})$ or $\mathbb{Z}/8\mathbb{Z}$ (order 8), $\mathbb{Z}/9\mathbb{Z}$ (order 9), $\mathbb{Z}/10\mathbb{Z}$ (order 10), $(\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/6\mathbb{Z})$ or $\mathbb{Z}/12\mathbb{Z}$ (order 12), or $(\mathbb{Z}/2\mathbb{Z}) \times (\mathbb{Z}/8\mathbb{Z})$ (order 16).
 - The proof of this theorem involves quite advanced methods: the idea is to study the points on various modular curves and use a (tremendous!) amount of case analysis to eliminate all of the other possible torsion orders and other possible group structures.
 - There also exist infinite families of elliptic curves having each of the groups listed as its torsion group.
- Over finite fields, all points are torsion points since $E(K)$ is finite, so the question of computing $E(K)$ reduces to that of computing the torsion points. Over infinite fields, however, $E(K)$ can have many linearly independent points of infinite order, which makes the group structure quite a lot more challenging to determine.
 - Indeed, even over $K = \mathbb{Q}$, it can often be quite computationally intensive to compute generators and relations for $E(\mathbb{Q})$, let alone over larger fields K .
 - Modern software packages such as Sage have functionality to compute generators for $E(K)$ when K is a number field.
 - We do not have the tools currently to prove many of these results, but we will give some examples for illustration.
- Example: Consider the elliptic curve $E : y^2 = x^3 + 4x + 1$ over $\mathbb{Q}$.
 - Quite obviously, $P = (0, 1)$ is a rational point on E .
 - We can then compute $[2]P = (4, -9)$, $[3]P = (9/4, 37/8)$, $[4]P = (28/81, -1135/729)$, $[5]P = (2664/49, 137593/343)$, and so forth.
 - Computing larger multiples of P will yield increasingly complicated rational points on E . Indeed, P has infinite order since $[3]P$ has non-integral coordinates, and so these integer multiples of P yield infinitely many distinct rational points on E .
 - In fact, P is actually a generator for the group $E(\mathbb{Q})$, although this is quite a lot harder to prove. As a consequence, the group $E(\mathbb{Q})$ is isomorphic to $\mathbb{Z}$.

- Example: Consider the elliptic curve $E : y^2 = x^3 - 2023x$ over $\mathbb{Q}$.
 - Quite obviously, $P = (0, 0)$ is a rational point on E . Here, however, since $[2]P = \infty$, we see that P is a torsion point.
 - Searching for other small rational points will reveal none, but in fact there are infinitely many points on E as well.
 - As one may verify with a computer, the point $Q = (84676804/180625, -775601419158/76765625)$ also lies on E , and it necessarily has infinite order since its coordinates are non-integral. Indeed, even just evaluating $[2]Q$ is messy by itself: $[2]Q = (52362044844804161854348549441681/434625338111430357812426490000, -351504781800873988198159892309132758495471097671/286531624685063323701511460309819791107000000)$.
 - In fact, P and Q generate the group of rational points, so since they are necessarily linearly independent, the group of rational points on E is isomorphic to $\mathbb{Z} \times (\mathbb{Z}/2\mathbb{Z})$.
- Example: Consider the elliptic curve $E : y^2 = x^3 - 43x + 166$ over $\mathbb{Q}$.
 - Searching for small integer points will eventually reveal that $P = (3, 8)$ lies on E .
 - Computing multiples of P yields $[2]P = (-5, -16)$, $[3]P = (11, -32)$, and $[4]P = (11, 32) = -[3]P$: thus P must have order 7.
 - In fact, the multiples of P turn out to be the only rational points on E , meaning that $E(\mathbb{Q})$ is isomorphic to $\mathbb{Z}/7\mathbb{Z}$.
- Example: Consider the elliptic curve $E : y^2 = x^3 - 2x$ over $\mathbb{Q}(i)$.
 - Clearly, $P = (0, 0)$ has order 2, while the points $Q = (i - 1, -2)$ and $R = (-1, 1)$ both have infinite order: for R this follows from Nagell-Lutz since $[2]R = (9/4, -21/8)$, but it is more work to show the result for Q since its entries are not rational (one approach is to show that the powers of 2 in the denominators of $[2^n]Q$ grow as n grows).
 - In fact the points Q and R are linearly independent, although this is even more work to show (since for example there is no reason *a priori* that there couldn't exist a relation like $[7]Q + [8]P = \infty$).
 - But since Q and R actually are linearly independent, each of the points $[a]Q + [b]R$ for integers a, b are distinct. As an example, we have $[2]Q + R = (\frac{13+84i}{25}, \frac{-462+709i}{125})$.
 - With even more effort, one may show that P , Q , and R generate $E(\mathbb{Q}(i))$, which is isomorphic to $\mathbb{Z} \times \mathbb{Z} \times (\mathbb{Z}/2\mathbb{Z})$.

0.3 (Sep 17) Mordell's Theorem

- In all of the examples above, the group $E(K)$ was finitely generated. In fact, the group $E(K)$ is always finitely generated whenever K is a number field², as shown for $K = \mathbb{Q}$ by Mordell and then extended to all number fields K by Weil:
- Theorem (Mordell-Weil): If K is a number field and E is an elliptic curve defined over K , then the group $E(K)$ is finitely generated.
 - We will not prove this theorem now since it requires substantially more number-theoretic background; even proving Mordell's theorem for the case $K = \mathbb{Q}$, which we will do below, is not at all trivial.
 - By the structure theorem for finitely generated abelian groups, this says $E(\mathbb{Q}) \cong \mathbb{Z}^r \oplus E_{\text{Tor}}(\mathbb{Q})$ where $E_{\text{Tor}}(\mathbb{Q})$ is the set of $\mathbb{Q}$ -torsion points of E (i.e., the set of $\mathbb{Q}$ -rational points of E having finite order), which is a finite abelian group and thus is a direct sum of cyclic groups.
 - For any given elliptic curve E , the torsion subgroup $E_{\text{Tor}}(\mathbb{Q})$ can be computed using Nagell-Lutz as we discussed above.

²Recall that a number field is a finite-degree field extension of $\mathbb{Q}$, meaning that K is finite-dimensional when considered as a vector space over $\mathbb{Q}$. Number fields can all be written as $K = \mathbb{Q}(\alpha)$ for some algebraic number α (i.e., a root of a nonzero polynomial with rational coefficients).

- The quantity r is called the rank of the elliptic curve, and is equal to the number of linearly-independent points one may construct on E . The rank is much more difficult to compute, and there is no known direct algorithm that is guaranteed to compute it (though in practice the rank of most curves can be computed).
- It is not currently known whether elliptic curves over $\mathbb{Q}$ can have an arbitrarily large rank, and the historical consensus has switched back and forth between thinking ranks can be arbitrarily large and thinking that ranks are uniformly bounded above. In 2006 Elkies gave a construction for an elliptic curve that has rank at least 28 (and it is expected this curve has rank exactly 28)³, and Elkies and Klagsbrun in 2024 constructed an elliptic curve of rank 29. In 2026 similar curves have been discovered of ranks 30 and 31.
- It has also been shown by Bhargava and Shankar in 2015 that the average rank (suitably defined) of an elliptic curve is at most $7/6$: the actual average is expected to be $1/2$ (with 50% of elliptic curves having rank 0 and 50% having rank 1, asymptotically).
- Here is the structure of the proof of Mordell’s theorem (and its generalization by Weil):
 - First, one proves the so-called “weak Mordell-Weil theorem”: that for any positive integer m and any number field K , the group $E(K)/mE(K)$ is finitely generated.
 - Of course, the weak Mordell-Weil theorem does not imply the full Mordell-Weil theorem directly, because there are many non-finitely-generated groups G such that G/mG is finitely generated (for example, $\mathbb{Q}$ and $\mathbb{R}$ both have $G/mG = 0$ for all m).
 - The difficulty is that knowing G/mG is finitely generated does not imply G is finitely generated, because G could contain many elements that are divisible by m .
 - The task then is to eliminate this possibility, which can be done using the theory of heights: one defines a “height function”, measuring roughly the complexity of a point on the curve, and then shows that the height of large multiples of a point tends to be larger than the height of the original point.
 - One such height function on points $(x, y) = (p_x/q_x, p_y/q_y)$ over $\mathbb{Q}$ is $\max(\log p_x, \log q_x)$: essentially, the maximum number of digits appearing in the numerator or denominator of the x -coordinate.
 - Next, one shows that there are a bounded number of points in $E(K)$ of height less than any fixed bound: thus, any point that is a multiple of m has to be “large” for large m .
 - By fine-tuning the details of this argument, we can deduce that a finite number of generators will suffice to generate the group $E(K)$: the idea is to show that for any point P on E , we may subtract appropriate multiples of the coset representatives of the finite group $E(K)/mE(K)$ to obtain a new point whose height is bounded independently of P . Since there are then only finitely many such points, adding them to our list will yield a finite generating set for $E(K)$.
 - A structurally similar argument works over arbitrary number fields K , but the details are more complicated.
- Before going into the details of Mordell’s theorem for $K = \mathbb{Q}$ we make some additional remarks.
 - The proof of weak Mordell(-Weil) is not effective, meaning that it does not yield an actual algorithm guaranteed to compute generators for $E(K)/mE(K)$, even for specific values of m (typically one uses $m = 2$).
 - Various practical computational methods (e.g., those implemented in Sage) have been developed that can provably compute generators for $E(K)$, but they are not always guaranteed to terminate.
 - In order to obtain Mordell(-Weil) it is only necessary to prove the finiteness of $E(K)/mE(K)$ for a single value of m , typically $m = 2$, which we will do in our argument.
- Theorem (Weak Mordell’s Theorem): If E is any elliptic curve defined over $\mathbb{Q}$, the group $E(\mathbb{Q})/2E(\mathbb{Q})$ is finite.

³The equation of Elkies’ curve is $y^2 + xy + y = x^3 - x^2 - 20067762415575526585033208209338542750930230312178956502x + 34481611795030556467032985690390720374855944359319180361266008296291939448732243429$

- Before proceeding with the actual argument, we outline the idea. What we will show is that there exists a homomorphism φ with kernel $2E(\mathbb{Q})$ from $E(\mathbb{Q})$ to a finite direct sum of groups of the form $(K^*)/(K^*)^2$ where K is a number field. We then show the image of $E(\mathbb{Q})$ inside each component is finite, which by the first isomorphism theorem implies that $E(\mathbb{Q})/2E(\mathbb{Q})$ is finite.
 - To motivate the existence of this homomorphism, suppose that E has a rational 2-torsion point. By translation we may move this point to the origin, in which case E has a Weierstrass equation $y^2 = x^3 + Cx^2 + Dx$.
 - If P, Q , and R are three collinear points on E none of which equals ∞ , then these three points lie on some line $y = mx + b$. Hence the x -coordinates of P, Q , and $-(P+Q)$ are the three roots of the equation $(mx + b)^2 = x^3 + Cx^2 + Dx$, or equivalently $x^3 + (C - m^2)x^2 + (D - 2mb)x - b^2$, so by the usual root formulas, the product of these three roots is b^2 : the square of a rational number.
 - Therefore, except at the 2-torsion points, the x -coordinate function $x : E(\mathbb{Q}) \rightarrow \mathbb{Q}^*$ satisfies the relation $x(P)x(Q)x(-P - Q) \in (\mathbb{Q}^*)^2$.
 - Since the x -coordinate of $-P - Q$ is the same as that of $P + Q$, and all of the quantities are rational numbers, this observation equivalently says that $x(P)x(Q)$ differs by a square factor from $x(P + Q)$, which is a convoluted way of saying that when we descend instead to the group $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$, the images of $x(P)x(Q)$ and $x(P + Q)$ are equal.
 - In other words, the image of the x -coordinate map satisfies the group homomorphism property, as a map from $E(\mathbb{Q})$ to $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$.
 - This does not give a complete description of the map, because we must still handle the situation of ∞ (which we clearly should map to the identity) and the origin $(0, 0)$, which we map to the value of the derivative of the cubic $x^3 + Cx^2 + Dx$ at that point: namely, D . One may then check that these conditions preserve the homomorphism property.
 - Now, $2E(\mathbb{Q})$ is certainly contained in the kernel of this homomorphism, since $x(2P) = x(P + P) = x(P)^2 = 1$ inside $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$ by the homomorphism property, since $x(P)^2$ is a square. However, the kernel will usually be much larger than $2E(\mathbb{Q})$.
 - In order to deal with this, we need to exploit the other points of order 2: that requires us to work with order-2 points located other places than the origin, and these points may not even lie in $E(\mathbb{Q})$. In general, if (α, β) has order 2, we instead want to work with the modified map $x^*(P) = x(P) - \alpha$ having image in $(K^*)/(K^*)^2$, where $K = \mathbb{Q}(\alpha)$, and we take the homomorphism to be the image of P under all three of these maps at once.
 - A convenient way to package these calculations is instead to consider the polynomial quotient ring $\mathbb{Q}[x]/(x^3 + Ax + B)$, which automatically keeps track of the x -coordinates of the points of order 2, so we will start with this approach.
- Step 1 (Construction of φ): Suppose E has a Weierstrass equation $y^2 = x^3 + Ax + B$ with A, B integers and let $f(x) = x^3 + Ax + B$.
 - Consider the polynomial quotient ring $R = \mathbb{Q}[x]/(f(x))$, which is a $\mathbb{Q}$ -algebra of dimension 3.
 - By the Chinese remainder theorem, if the factorization of $f(x)$ over $\mathbb{Q}$ is a product of 3 linear factors then $R \cong \mathbb{Q} \oplus \mathbb{Q} \oplus \mathbb{Q}$, if $f(x)$ is a product of a linear and quadratic term then $R \cong \mathbb{Q} \oplus K$ where $K/\mathbb{Q}$ is a field extension of degree 2 (generated by a root of the quadratic), and if $f(x)$ is irreducible then $R \cong L$ where $L/\mathbb{Q}$ is a field extension of degree 3 (generated by any root of f).
 - Let U be the group of units of the ring R , which are the residue classes in R represented by the polynomials relatively prime to $x^3 + Ax + B$ in $\mathbb{Q}[x]$.
 - We now construct a group homomorphism $\varphi : E(\mathbb{Q}) \rightarrow U/U^2$ with kernel $2E(\mathbb{Q})$. Clearly we must take $\varphi(\infty)$ to be the identity element of U/U^2 if this map is to be a homomorphism.
 - Next suppose $P = (\alpha, \beta)$ is a rational point on E with $y \neq 0$. Then the polynomial $x - \alpha$ is relatively prime to $x^3 + Ax + B$ (as α is not a root of this polynomial because $y \neq 0$), so the residue class of $x - \alpha$ lies in U . We define $\varphi(P)$ to be the residue class $\overline{x - \alpha} + U^2 \in U/U^2$.
 - It remains to define φ on the points $(\alpha, 0)$ of order 2. Since $x - \alpha$ divides $x^3 + Ax + B$, we may write $x^3 + Ax + B = (x - \alpha)g(x)$ for a quadratic $g(x)$; then because α is rational and $x^3 + Ax + B$ has no repeated roots, by the Chinese remainder theorem we have $\mathbb{Q}[x]/(f(x)) \cong \mathbb{Q}[x]/(x - \alpha) \oplus \mathbb{Q}[x]/(g(x))$.

Since the first factor $\mathbb{Q}[x]/(x - \alpha)$ is isomorphic to $\mathbb{Q}$ (by the evaluation map $x \mapsto \alpha$), the element $(f'(\alpha) \bmod x - \alpha, \alpha - x \bmod g(x))$ corresponds to a unique unit in U/U^2 .

• Step 2: The map φ is a homomorphism.

- Proof: First, because the definition of φ is independent of the y -coordinate of a point P , we have $\varphi(P) = \varphi(-P)$ for all P .
- It then suffices to show that if P, Q, R are collinear on E , then $\varphi(P)\varphi(Q)\varphi(R) = 1$ in U/U^2 : this will imply that $\varphi(P+Q)\varphi(P)\varphi(Q) = \varphi(P+Q)\varphi(-P)\varphi(-Q) = 1$, and since the square of every element in U/U^2 is 1, this would imply the homomorphism condition $\varphi(P+Q) = \varphi(P)\varphi(Q)$.
- Now suppose that P, Q, R are distinct and not 2-torsion. If $Q = -P$ then $R = \infty$ in which case $\varphi(P)\varphi(Q)\varphi(R) = \varphi(P)^2 = 1$ in U/U^2 .
- Otherwise, the three points lie on a line $y = mx + b$ in which the three x -coordinates x_P, x_Q, x_R of P, Q, R are the roots of $x^3 + Ax + B - (mx + b)^2 = (x - x_P)(x - x_Q)(x - x_R)$: then $\varphi(P)\varphi(Q)\varphi(R)$ is the residue class $x_P - x \cdot x_Q - x \cdot x_R - x = (mx + b)^2 = (\overline{mx + b})^2 = 1$ because this element is the square of a residue class in U/U^2 .
- If one of the points has order 2 (say P) but the others do not, we again check that the image of the product is a square in the various components of $\mathbb{Q}[x]/(f(x))$. For example, if P has order 2 but Q, R do not, then the same argument as above works in the factor $\mathbb{Q}[x]/(g(x))$, while in the factor $\mathbb{Q}[x]/(x - x_P)$ we have $f'(\alpha) = (x_P - x_Q)(x_P - x_R)$ so the product $\varphi(P)\varphi(Q)\varphi(R) = f'(\alpha)^2$ in the first component. Thus since the product is a square in both components, by the Chinese remainder theorem it is a square in U/U^2 hence equals 1.
- Finally, if all of the points have order 2, a similar argument works to show that the resulting product is a square in each of the three resulting components of $\mathbb{Q}[x]/(f(x)) \cong \mathbb{Q}[x]/(x - x_P) \oplus \mathbb{Q}[x]/(x - x_Q) \oplus \mathbb{Q}[x]/(x - x_R)$.

• Step 3: The kernel of φ is $2E(\mathbb{Q})$.

- Proof: First observe that for any $P \in E(\mathbb{Q})$, we have $\varphi(2P) = \varphi(P)^2 = 1$ since squares in U/U^2 are 1. Therefore $2E(\mathbb{Q})$ is contained in $\ker(\varphi)$.
- For the other containment suppose $\varphi(P) = 1$ for $P = (\alpha, \beta)$. Then $\varphi(P)$ is the residue class of $\alpha - x$ in U/U^2 , meaning that $\alpha - x$ is a unit and a square in $\mathbb{Q}[x]/(x^3 + Ax + B)$.
- Suppose $\alpha - x \equiv (c_1x^2 + c_2x + c_3)^2$ modulo $x^3 + Ax + B$ for some $c_1, c_2, c_3 \in \mathbb{Q}$. Note c_1 must be nonzero (otherwise the congruence would have a linear polynomial congruent to one of degree 0 or 2).
- One may check that $(-c_1x + c_2)(c_1x^2 + c_2x + c_3) \equiv dx + e$ modulo $x^3 + Ax + B$ for $d = Ac_1^2 + c_2^2 - c_1c_3$ and $e = Bc_1^2 + c_2c_3$. Thus the polynomial $(-c_1x + c_2)^2 - (\alpha - x)(dx + e)^2$ is zero modulo $x^3 + Ax + B$: but since this polynomial is a monic cubic, it must equal $x^3 + Ax + B$.
- Therefore, $x^3 + Ax + B = (-c_1x + c_2)^2 - (\alpha - x)(dx + e)^2$. Geometrically, this means that the line $y = -c_1x + c_2$ intersects $y^2 = x^3 + Ax + B$ at one point with x -coordinate α (namely, at P or at $-P$) and a double intersection at some other point Q . This means $\pm P = 2Q$, and in either case $P \in 2E(\mathbb{Q})$, as desired.

• Step 4: Proof of the weak Mordell theorem.

- Using the homomorphism φ we can now finish the proof: by the first isomorphism theorem, $E(\mathbb{Q})/2E(\mathbb{Q})$ is isomorphic to the image of φ inside U/U^2 , the group of units modulo squares inside R .
- Since R is a direct sum of number fields, by the Chinese remainder theorem, the group U/U^2 is a direct sum of groups of the form $(K^*)/(K^*)^2$ where K is a number field. It therefore suffices to show that the projection of the image of φ inside each of these groups $(K^*)/(K^*)^2$ is finite, for then the image of φ itself is finite.
- We will show the result in the situation where E has rational 2-torsion (i.e., when the roots of $f(x)$ are all rational), in which case $U/2U$ is the direct sum of three copies of $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$.

- Suppose we are considering the component associated to a 2-torsion point P . By translating P to the origin, we may equivalently work with E having a Weierstrass form $y^2 = x^3 + Cx^2 + Dx$, where (as we showed above during the motivation for the argument) the desired map is simply the x -coordinate map $x(\alpha, \beta) = \alpha$.
- We claim that the image of $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$ lies inside the subgroup generated by -1 and the prime divisors of D . To see this, suppose $Q = (q/d^2, r/d^3)$ is a rational point on E (recall that we showed all rational points have this form in our proof of Nagell-Lutz; the proof works equally well for arbitrary Weierstrass forms). By rescaling d , we may also assume that q is squarefree, in which case $q = \varphi(Q)$ inside $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$.
- By clearing denominators we see that $r^2 = q^3 + Cq^2d + Dqd^2$. Let p be a prime dividing q (which necessarily does not divide d): then p divides the right-hand side, so p divides r^2 and hence it divides r . But then $Dqd^2 = r^2 - q^3 - Cq^2d$ is divisible by p^2 , and since q is squarefree, it is not divisible by p^2 , and d^2 is also not divisible by p , so D must be divisible by p .
- Therefore, all prime divisors of $\varphi(Q)$ divide D , and so $\varphi(Q)$ lies inside the finite subgroup of $(\mathbb{Q}^*)/(\mathbb{Q}^*)^2$ generated by -1 and the prime divisors of D . Since this holds for all Q , we see that the image of φ lies inside this finite subgroup, so it is finite.
- In the other cases, where some of the 2-torsion points of E do not lie in $\mathbb{Q}$, one may adapt this argument inside $(K^*)/(K^*)^2$ to see that there are only finitely many possible values for $\varphi(Q)$ when it is a principal ideal. Then because the ideal class group of K is finite, one can extend this argument to show that there are only finitely many possible values for $\varphi(Q)$ in general. (We omit the details since they require some nontrivial calculations with ideal classes.)
- Now that we have finished the weak Mordell's theorem, we can use the result to prove the full version. To do this we will use the following descent theorem:
- **Theorem (Descent Theorem):** Suppose that G is an abelian group with a “height function” $h : G \rightarrow [0, \infty)$ such that (i) for all nonnegative M , the number of elements $g \in G$ with $h(g) \leq M$ is finite, (ii) for all $g_0 \in G$ there is a constant c_g with $h(g + g_0) \leq 2h(g) + c_g$ for all $g \in G$, (iii) there is a constant d such that $h(2g) \geq 4h(g) - d$ for all $g \in G$, and (iv) $G/2G$ is finite. Then G is finitely generated.
 - **Proof:** Let S be a set of coset representatives for $G/2G$ and let $P_0 \in G$. Then P_0 lies in one of these cosets, say the coset represented by Q_0 , meaning that $P_0 - Q_0 \in 2G$. This means $P_0 - Q_0 = 2P_1$ for some $P_1 \in G$.
 - In the same way, P_1 lies in some coset, say represented by Q_1 , so that $P_1 - Q_1 = 2P_2$ for some $P_2 \in G$. By iterating this procedure we obtain a sequence of coset representatives $Q_0, Q_1, Q_2, \dots$ and elements $P_1, P_2, P_3, \dots$ such that $P_i - Q_i = 2P_{i+1}$ for each $i \geq 0$.
 - By substituting these equations into one another, we see that $P = Q_0 + 2Q_1 + 4Q_2 + \dots + 2^n Q_n + 2^{n+1} P_{n+1}$ for each $n \geq 0$.
 - Now, by (ii) applied with $g_0 = -Q_i$ we have $h(g - Q_i) \leq 2h(g) + c_i$ for some c_i and all $g \in G$.
 - Since there are only finitely many possible Q_i (namely, the elements in the set S of coset representatives), letting c be the maximum of the corresponding c_i shows that $h(g - Q_i) \leq 2h(g) + c$ for all $g \in G$ and all $i \geq 0$.
 - Then by (iii) applied with $g = P_{i+1}$ we have $4h(P_{i+1}) \leq h(2P_{i+1}) + d = h(P_i - Q_i) + d \leq 2h(P_i) + c + d$ where the last step follows from what we just did above.
 - In particular, when $h(P_i) \geq c + d$, we have $h(P_{i+1}) \leq \frac{3}{4}(c + d) \leq \frac{3}{4}h(P_i)$. In other words, if the height of P_i is large enough, then the height of P_{i+1} necessarily decreases exponentially.
 - We therefore see that there must exist some n with $h(P_{n+1}) \leq c + d$. Let T be the set of g with $h(g) \leq c + d$, which is finite by (i).
 - Then $P = Q_0 + 2Q_1 + 4Q_2 + \dots + 2^n Q_n + 2^{n+1} P_{n+1}$ is a linear combination of the Q_i (which all lie in S) and P_{n+1} (which lies in T). Since this holds for any point P , we deduce that $S \cup T$ generates G : since S and T are both finite, this means G is finitely generated.
- It remains to show that there exists a height function h on the elliptic curve E that satisfies all of the hypotheses of the descent theorem. The final step is to prove that the height function $h(q/r, s/t) = \log \max(|q|, |r|)$ satisfies all of the requirements.

- For (i), clearly there are only finitely many rational numbers with height $\leq M$, since the numerator and denominator must both be at most e^M in absolute value.
- For (ii), suppose $P = (q/d^2, r/d^3)$ with d relatively prime to q, r and E has a Weierstrass form $y^2 = x^3 + Ax + B$. If P has height h , then $|q| \leq h$ and $d^2 \leq h$, and also $r^2 = |q^3 + Aqd^2 + Bd^3| \leq Ch^3$ where $C = 1 + |A| + |B|$ is a fixed constant.
- Then from the addition formula, if $P_0 = (x, y)$, the x -coordinate of $P + P_0$ is $(\frac{y - y_0}{x - x_0})^2 - x_0 - x$, which can eventually be simplified to the form $\frac{c_1y + c_2x^2 + c_3x + c_4}{c_5x^2 + c_6x + c_7}$ for some integers $c_1, \dots, c_7$. Setting $x = q/d^2$ and $y = r/d^3$ then yields an expression for the x -coordinate that is a ratio of two integers. Applying the triangle inequality and the bounds above to the numerator and denominator then yield an inequality of the desired form.
- For (iii), we must estimate the height of $2P$ in terms of the height of P . If $P = (x, y)$ then the x -coordinate of $2P$ is $\frac{(3x^2 + A)^2}{4(x^3 + Ax + B)} - 2x = \frac{x^4 - 2Ax^2 - 8Bx + A^2}{4(x^3 + Ax + B)}$.
- The desired height estimate then follows from the following general fact about rational functions given by quotients of relatively prime polynomials: if $f(x)$ and $g(x)$ are relatively prime polynomials in $\mathbb{Z}[x]$ with $d = \max(\deg f, \deg g)$, then there exist a constant C such that $\left| h\left(\frac{f(x)}{g(x)}\right) - dh(x) \right| \leq C$ for all x .
- Showing this estimate is quite nontrivial, and we will omit the details. Intuitively, however, the idea is to show that there can only be a bounded amount of factor cancellation between $f(x)$ and $g(x)$ for each rational x , and so since $f(x)$ and $g(x)$ are relatively prime, the height of $\frac{f(x)}{g(x)}$ up to some bounded amount is the same as the height of $\frac{x^d}{g(x)}$, which is just $h(x^d) = dh(x)$.
- Finally, (iv) is the weak Mordell's theorem, which we proved above.
- Putting all of these facts together, at last, completes the proof of Mordell's theorem that $E(\mathbb{Q})$ is finitely generated.

0.4 (Sep 21) $\mathbb{A}^n$, Affine Varieties

- The explicit calculations resulting in the group law that we worked out during the last few lectures have a rather *ad hoc* feel to them. Our goal now is to give a more coherent approach to the group law on an elliptic curve, in a way that will make more clear that the existence of the group law is not just some mere computational accident, but rather something that is forced to exist by the structural properties of the curve.
 - To do this we will review some basic facts about the algebraic geometry of plane curves.
- Definition: For a field k , we define affine n -space $\mathbb{A}^n(k) = \{(x_1, x_2, \dots, x_n) : x_i \in k\}$ to be the set of n -tuples of elements of k . The elements of $\mathbb{A}^n(k)$ are called points.
 - Definition: For $f \in k[x_1, \dots, x_n]$, we define the vanishing locus of f to be $V(f) = \{P \in \mathbb{A}^n(k) : f(P) = 0\}$, the set of points $P \in \mathbb{A}^n(k)$ where f vanishes. We extend this definition to subsets $T \subseteq k[x_1, \dots, x_n]$ by setting $V(T) = \bigcap_{f \in T} V(f) = \{P \in \mathbb{A}^n(k) : f(P) = 0 \text{ for all } f \in T\}$.
 - Exercise: Draw $V(x)$, $V(x^2)$, $V(y - x)$, $V(y - x^2)$, $V(xy)$, $V(x, y)$, and $V(y^2 - x^3 - x)$ in $\mathbb{A}^2(\mathbb{R})$.
 - Definition: For a subset $S \subseteq \mathbb{A}^n(k)$, we define the ideal of functions vanishing on S to be $I(S) = \{f \in k[x_1, \dots, x_n] : f(P) = 0 \text{ for all } P \in S\}$. It is easy to see that $I(S)$ is an ideal of $k[x_1, \dots, x_n]$ for any set S .
 - Exercise: Identify $I(S)$ in $\mathbb{R}[x, y]$ for $S = \{(t, 0) : t \in \mathbb{R}\}$, $\{(t^2, t) : t \in \mathbb{R}\}$, $\{(1, 1)\}$, $\{(0, 0), (1, 1)\}$, $\{(\cos t, \sin t) : t \in \mathbb{R}\}$, and $\{(t, \sin t) : t \in \mathbb{R}\}$.
- We have various properties of the maps V and I :

1. If I is the ideal generated by $T \subseteq k[x_1, \dots, x_n]$, then $V(T) = V(I)$. Thus, we need only consider the behavior of V on ideals, meaning that we will only consider $I : [\text{sets}] \rightarrow [\text{ideals}]$ and $V : [\text{ideals}] \rightarrow [\text{sets}]$.
2. $V(0) = \mathbb{A}^n(k)$, $V(1) = \emptyset$, and $V(x_1 - a_1, \dots, x_n - a_n) = \{(a_1, \dots, a_n)\}$.
3. $I(\emptyset) = k[x_1, \dots, x_n]$, $I(\mathbb{A}^n) = 0$ when k is infinite, and $I(\{(a_1, \dots, a_n)\}) = (x_1 - a_1, \dots, x_n - a_n)$.
4. $V(\cup_i I_i) = \cap_i V(I_i)$ and $V(IJ) = V(I) \cup V(J)$.
5. For ideals I and J , if $I \subseteq J$ then $V(I) \supseteq V(J)$, and for sets X and Y , if $X \subseteq Y$ then $I(X) \supseteq I(Y)$. (Thus, both I and V are inclusion-reversing.)
6. For any subset S of $k[x_1, \dots, x_n]$, $S \subseteq I(V(S))$ and $V(S) = V(I(V(S)))$.
7. For any subset X of $\mathbb{A}^n(k)$, $X \subseteq V(I(X))$ and $I(X) = I(V(I(X)))$. Furthermore, $I(X)$ is a radical⁴ ideal.

◦ Proofs: Exercises.

- Definition: For a field k , an affine algebraic set in $\mathbb{A}^n(k)$ is a subset of $\mathbb{A}^n(k)$ of the form $V(I)$ for some ideal I .

- Examples: Single points $\{(a_1, \dots, a_n)\} = V(x_1 - a_1, \dots, x_n - a_n)$ are affine algebraic sets by (2) above. The sets $\{(t, 0) : t \in k\} = V(y)$ and $\{(t^2, t^3) : t \in k\} = V(y^2 - x^3)$ are affine algebraic sets.
- By (4), we see that affine algebraic sets are closed under finite unions and arbitrary intersections, and (3) shows that $\mathbb{A}^n$ and $\emptyset$ are affine algebraic sets.
- Thus, if we consider affine algebraic sets to be closed (with the open sets therefore being their complements), we obtain a topology on $\mathbb{A}^n(k)$. This topology is known as the Zariski topology.
- By Hilbert's basis theorem, every ideal of $k[x_1, \dots, x_n]$ is finitely generated, so by (4) above, we see that every affine algebraic set is of the form $V(f_1) \cap V(f_2) \cap \dots \cap V(f_i)$ for some polynomials $f_1, \dots, f_i$. (Equivalently, the complements of the sets $V(f_i)$ form a base for the Zariski topology.)
- It is natural to seek "minimal" elements under the Zariski topology.

- Definition: An affine algebraic set V is reducible if it can be written as $V = V_1 \cup V_2$ where $V_1, V_2 \neq V$, and it is irreducible otherwise.

- We have a few more properties:

8. V is irreducible if and only if $I(V)$ is a prime ideal of $k[x_1, \dots, x_n]$.
 - Proof: If $V = V_1 \cup V_2$ with $V_1, V_2 \neq V$, then $I(V_1)$ and $I(V_2)$ both properly contain V : if $f \in I(V_1) \setminus V$ and $g \in I(V_2) \setminus V$ then $fg \in I(V_1) \cap I(V_2) = I(V)$, meaning that $I(V)$ is not prime.
 - Conversely, if $fg \in I(V)$ with $f, g \notin I(V)$, we can take $V_1 = V \cap V(f)$ and $V_2 = V \cap V(g)$: then $V_1 \cup V_2 = V$ and $V_1, V_2 \neq V$ so V is reducible.
9. Any affine algebraic set V can be written uniquely as a union of irreducible affine algebraic sets $V_1 \cup V_2 \cup \dots \cup V_n$ such that $V_i \not\subseteq V_j$ for any $i \neq j$. (These sets V_i are the irreducible components of V .)

- Proof: Exercise. This result is the geometric version of primary decomposition (generalizing the notion of prime factorization of elements).

- Exercise: If k is algebraically closed, show that the irreducible affine algebraic sets in $\mathbb{A}^2(k)$ are $\emptyset$, $\mathbb{A}^2(k)$, single points, and curves of the form $V(f)$ for a monic irreducible polynomial $f \in k[x, y]$. [Hint: Show that if $f, g \in k[x, y]$ are relatively prime, then (f, g) contains a nonzero polynomial in $k[x]$ and a nonzero polynomial in $k[y]$.]
- Although it may appear that I and V should behave like inverses, they are not quite.

- For example, even in $\mathbb{A}^1(k)$, we have $V(x^2) = \{0\}$ so that $I(V(x^2)) = (x)$. The point here is that $I = (x^2)$ is not a radical ideal, and in this case, $I(V(I)) = \text{rad}(I)$.

⁴Recall that if I is an ideal of a commutative ring R , then the radical $\text{rad}(I) = \{r \in R : r^n \in I \text{ for some } n \geq 1\}$, and I is a radical ideal if $I = \text{rad}(I)$. (Note that $\text{rad}(I)$ is an ideal, as is easily seen via an application of the binomial theorem.)

- However, even if I is radical, it is not always true that $I(V(I)) = \text{rad}(I)$: for example, in $\mathbb{A}^1(\mathbb{R})$ we have $V(1+x^2) = \emptyset$ so that $I(V(1+x^2)) = \mathbb{R}[x]$.
 - Indeed, there is no subset S of $\mathbb{A}^1(\mathbb{R})$ with $I(S) = (1+x^2)$ since the only set S with $I(S) \supseteq (1+x^2)$ is the empty set. The issue here is that $\mathbb{R}$ is not algebraically closed: if instead we work in $\mathbb{C}$, then $S = \{i, -i\}$ does have $I(S) = (1+x^2)$.
- Working over an algebraically closed field resolves all of these difficulties: this is the content of Hilbert's Nullstellensatz, which has various forms:
- Theorem (Affine Nullstellensatz): Suppose k is an algebraically closed field.
 - (Weak) If I is a proper ideal of $k[x_1, \dots, x_n]$, then $V(I) \neq \emptyset$.
 - (Strong) If I is any ideal of $k[x_1, \dots, x_n]$, then $I(V(I)) = \text{rad}(I)$.
 - We outline the arguments, leaving the full details as an exercise in commutative algebra or looking up the appropriate references.
 - For the weak Nullstellensatz, it suffices to show the result for maximal ideals, and then since $k[x_1, \dots, x_n]$ is Noetherian, it is in turn sufficient to show that the finitely many generators of a maximal ideal I must have a common zero somewhere.
 - This in turn follows from showing that the quotient ring $k[x_1, \dots, x_n]/I$, which is a field extension of k because I is maximal, is a finite-degree extension of k : then since k is algebraically closed, k has no finite-degree field extensions, so the extension simply equals k itself. Then if $\varphi : k[x_1, \dots, x_n]/I \rightarrow k$ is the associated isomorphism, all elements of I vanish at the point $\varphi(x_1, \dots, x_n)$.
 - For the full Nullstellensatz, after noting that $\text{rad}(I) \subseteq I(V(I))$, one uses the “Rabinowitsch trick” for the other containment: if $g \in I(V(f_1, \dots, f_r))$, consider the ideal $J = (f_1, \dots, f_r, x_{n+1}g - 1)$ of $k[x_1, \dots, x_n, x_{n+1}]$, which has empty vanishing locus hence cannot be proper (by the weak Nullstellensatz), so it contains 1. By writing 1 as an appropriate linear combination of the generators of J and then setting $x_{n+1} = 1/g$ and clearing denominators appropriately, one obtains g^N as a linear combination of the f_i for some N , so $g \in \text{rad}(I)$.
- Definition: If k is algebraically closed, an irreducible affine algebraic set in $\mathbb{A}^n(k)$ is called an affine variety.
- Per the Nullstellensatz we see that I and V give nice bijections between various sets in $\mathbb{A}^n(k)$ and ideals of $k[x_1, \dots, x_n]$.
 - By the full Nullstellensatz, since $I(V(I)) = \text{rad}(I)$, we obtain a correspondence between radical ideals and affine algebraic sets.
 - Furthermore, by the weak Nullstellensatz, if I is a proper ideal then $V(I)$ must contain some point $(a_1, \dots, a_n)$, whence I is contained in $I(\{(a_1, \dots, a_n)\}) = (x_1 - a_1, \dots, x_n - a_n)$. But since the quotient of $k[x_1, \dots, x_n]$ by $(x_1 - a_1, \dots, x_n - a_n)$ is isomorphic to k via the evaluation map $p \mapsto p(a_1, \dots, a_n)$, the latter ideal is maximal. Thus, the maximal ideals of $k[x_1, \dots, x_n]$ correspond precisely with points $(a_1, \dots, a_n)$.
 - Also, by the full Nullstellensatz, if I is a prime ideal, then $I(V(I)) = \text{rad}(I) = I$ since prime ideals are radical, and so by property (8) earlier, we see that $V(I)$ is irreducible. Thus, the prime ideals of $k[x_1, \dots, x_n]$ correspond with irreducible affine algebraic sets (i.e., affine varieties).
 - To summarize, we have the following correspondences:

$$\begin{aligned} [\text{Affine algebraic sets}] &\xrightleftharpoons[V]{I} [\text{Radical Ideals}] \\ [\text{Affine varieties}] &\xrightleftharpoons[V]{I} [\text{Prime Ideals}] \\ [\text{Points of } \mathbb{A}^n(k)] &\xrightleftharpoons[V]{I} [\text{Maximal Ideals}] \end{aligned}$$
- Next, we bring rational functions into the discussion:
- Definition: If $V = V(I)$ is an affine variety, the coordinate ring of V is the ring $\Gamma(V) = k[x_1, \dots, x_n]/I(V)$, and its associated field of rational functions (or function field) $k(V)$ is the field of fractions of $\Gamma(V)$.

- Recall that if R is an integral domain, the field of fractions of R consists of the equivalence classes of elements of the form a/b with $a, b \in R$ and b nonzero under the usual equivalence $a/b \sim c/d$ if and only if $ad = bc$. (The field of fractions is also the localization of R at $R \setminus \{0\}$.)
- Exercise: Let $\mathcal{F}(V, k)$ be the ring of k -valued functions on V . We say $f \in \mathcal{F}(V, k)$ is a polynomial function if there exists $g \in k[x_1, \dots, x_n]$ such that $f(P) = g(P)$ for all $P \in V$. Show that $\Gamma(V)$ is the set of equivalence classes of polynomial functions under the relation $g_1 \sim g_2$ if $g_1(P) = g_2(P)$ for all $P \in V$.
- By the exercise above, the coordinate ring of V can be thought of as the collection of distinct polynomial functions on V , and thus the field of rational functions is, quite explicitly, the collection of rational functions on V .
- Examples: For the affine variety $V = V(y - x^2)$ in $\mathbb{A}^2(\mathbb{C})$, some examples of functions in the coordinate ring are x , $3x - 7$, y , and x^2 . For this variety, the functions y and x^2 are the same, since they represent the same coset in the quotient ring. Some examples of rational functions are y/x , which also equals x , and $(x^2 + 5)/(3x - 7)$.
- Rational functions can have poles, which are points $P \in V$ where the function is not defined.
- Definition: If V is an affine variety, we say $f \in k(V)$ is defined at a point P if $f = a/b$ for some $a, b \in \Gamma(V)$ and $b(P) \neq 0$. If f is defined at P , its value $f(P)$ is the ratio $a(P)/b(P) \in k$. The local ring of V at P , denoted $\mathcal{O}_P(V)$, is the set of rational functions $f \in k(V)$ that are defined at P . The points P for which f is not defined are the poles of f , since they are necessarily zeroes of its denominator.
 - Exercise: Show that $\Gamma(V) = \cap_{P \in V} \mathcal{O}_P(V)$: in other words, that a function with no poles is a polynomial. (Note of course that k is still assumed to be algebraically closed.)
 - Examples: For the affine variety $V = V(y - x^2)$ in $\mathbb{A}^2(\mathbb{C})$, the rational function $f(x, y) = y/(x - 2)$ is defined everywhere on V except at the point $(1, 1)$, which is a pole of f .
 - The local ring $\mathcal{O}_P(V)$ has a unique maximal ideal $m_P(V)$ given by the polynomials f that vanish at P (i.e., with $f(P) = 0$).
 - Exercise: Show that the evaluation-at- P map $\varphi_P : \mathcal{O}_P(V) \rightarrow k$ is a surjective ring homomorphism with kernel $m_P(V)$. Deduce that $m_P(V)$ is maximal, and show also that if $P = (a_1, \dots, a_n)$ then $m_P(V)$ is generated by the polynomials $x_i - a_i$ for $1 \leq i \leq n$.
 - We remark also that the local ring $\mathcal{O}_P(V)$ is simply the localization of the function field $k(V)$ at the ideal $m_P(V)$; this is why $\mathcal{O}_P(V)$ is called the “local ring” of V at P .
 - When the variety V is clear from context we will often just write $\mathcal{O}_P$ and m_P .
- We will emphasize here that there may be numerous ways to write $\alpha = f/g$ as a quotient of polynomials inside the function field $k(V)$, and it may be necessary to work with different “equivalent” formulas in order to verify that α is defined at a particular point P .
- Example: Consider the affine variety $V = V(y^2 - x^2 + 1)$ in $\mathbb{A}^2(k)$ for $k = \mathbb{C}$ and the rational function $\alpha = \frac{x-1}{y} \in k(V)$.
 - It is clear from the expression $\alpha = \frac{x-1}{y}$ that α is defined at all points $P = (x, y) \in V$ where $y \neq 0$.
 - However, because $\Gamma(V) = k[x, y]/(y^2 - x^2 + 1)$, we see that $y^2 = x^2 - 1$ in $\Gamma(V)$, so by factoring and rearranging we see that $\frac{x-1}{y} = \frac{y}{x+1}$ inside $k(V)$. Therefore, α is also equal to $\frac{y}{x+1}$, and this latter expression shows that f is also defined at the point $(1, 0)$.
 - On the other hand, there is no way to rewrite $\alpha = \frac{x-1}{y}$ in such a way that it is defined at $(-1, 0)$: if $\frac{x-1}{y} = \frac{p}{q}$ then $(x-1)q = yp$ but then evaluating both sides at $P = (-1, 0)$ produces $-2q(P) = 0$, which is a contradiction.
 - Remark: More generally, the same argument shows that if the expression for $\alpha(P)$ is of the form $a/0$ for $a \neq 0$, then α is not defined at P . (If, of course, we obtain an expression $0/0$, then f could possibly be defined at P .)

- Definition: If V is an affine variety with function field $k(V)$, its dimension is defined to be the transcendence degree of $k(V)$ over k . An affine curve is an affine variety of dimension 1.
 - Examples: $V(y - x)$ and $V(y^2 + a_1xy + a_3y - x^3 - a_2x^2 - a_4x - a_6)$ are affine curves in $\mathbb{A}^2(k)$.
 - If we think of $V = V(I)$ as being cut out from $\mathbb{A}^n(k)$ by the generators of I , then the dimension (as defined above) agrees with the intuitive topological sense of the dimension of $V(I)$ as a (hyper)surface, when $k = \mathbb{C}$.

0.5 (Sep 24) Affine Curves, $\mathbb{P}^n$

- We outline some additional facts about affine curves in $\mathbb{A}^2(k)$:
 1. Via the correspondence $C \mapsto V(f)$, an affine plane curve C is the same as a nonconstant monic irreducible polynomial $f \in k[x, y]$. We define the degree of C to be the degree of the corresponding polynomial f .
 - As noted in an exercise earlier, the irreducible affine sets in $\mathbb{A}^2(k)$ are $\emptyset$ (dimension 0), single points (dimension 0), $\mathbb{A}^2(k)$ (dimension 2), and the sets of the form $V(f)$ where f is a monic irreducible polynomial (these are the only sets of dimension 1, so they are the only curves).
 2. If P is a point of the affine curve $C = V(f)$, we say P is a singular point if $f_x(P) = f_y(P) = 0$, and otherwise we say P is a nonsingular point (or smooth point or simple point). We say that C itself is smooth if all points of C are smooth points.
 - The main idea here is that a point P is singular if and only if C does not have a well-defined tangent line at P .
 - To find the tangent line(s) to a curve at a point P , we simply expand the defining polynomial f as a local Taylor series centered at $P = (x_0, y_0)$, i.e., as $f = a_{0,0} + a_{1,0}(x - x_0) + a_{0,1}(y - y_0) + a_{2,0}(x - x_0)^2 + a_{1,1}(x - x_0)(y - y_0) + a_{0,2}(y - y_0)^2 + \dots$. Then the tangent lines are obtained by factoring the lowest-degree homogeneous component appearing in the factorization.
 - In particular, since $a_{0,0} = f(P) = 0$, $a_{1,0} = f_x(P)$, and $a_{0,1} = f_y(P)$ by the usual Taylor expansion, we see that there is a unique tangent line precisely when the linear term does not vanish (i.e., P has multiplicity 1), which is to say, precisely when $f_x(P)$ and $f_y(P)$ are not both zero.
 - Example: The point $(0,0)$ lies on the variety $V(x + x^3 - 2y - y^5)$. Writing the curve locally near $(0,0)$ yields $f = (x - 2y) + x^3 - y^5$, and the lowest-degree homogeneous component is $x - 2y$. Here, the curve has a unique tangent line at $(0,0)$ given by $x - 2y = 0$ (which one may check explicitly using calculus).
 - Example: The elliptic curve $V(y^2 - x^2 - x^3)$ has a singular point at $(0,0)$. Writing the curve locally near $(0,0)$ yields $f = -x^2 + y^2 - x^3$, and the lowest-degree homogeneous component is $(-x^2 + y^2) = (-x + y)(-x - y)$. Here, the curve has two different tangent lines, $y = x$ and $y = -x$, yielding a node at $(0,0)$.
 - Example: The elliptic curve $V(y^2 - x^3)$ has a singular point at $(0,0)$. Writing the curve locally near $(0,0)$ yields $f = y^2 - x^3$, and the lowest-degree homogeneous component is y^2 . Here, the curve has a double tangent line $y = 0$, yielding a cusp at $(0,0)$.
 - The degree of the lowest term with a nonzero coefficient in the local expansion of f at P is called the multiplicity of P . One may show that for sufficiently large n , the multiplicity of C at P is equal to $\dim_k(m_P^n/m_P^{n+1})$, where m_P is the maximal ideal of the local ring $\mathcal{O}_P$ at P .
 3. If P is a smooth point of the curve C , then the maximal ideal $m_P(C)$ of the local ring $\mathcal{O}_P(C)$ is principal. Any generator for this maximal ideal is called a uniformizer at P .
 - Exercise: Let R be a commutative ring with 1 having a maximal ideal M . Show that M^n/M^{n+1} is a vector space over the field $k = R/M$ for each positive integer n .
 - Exercise: Let R be a local ring (a commutative ring with 1 having a unique maximal ideal M). Show that every element of R is either a unit or an element of M .
 - The principality of m_P follows from the more general statement that if P is a smooth point of a variety, then $\dim_k(m_P/m_P^2) = \dim(V)$. Since curves have dimension 1, this yields $\dim_k(m_P/m_P^2) = 1$. If t generates the vector space m_P/m_P^2 , then in fact one may show that $m_P = (t)$, though this takes some effort.

- Example: Consider the smooth elliptic curve $C : y^2 = x^3 + x$ over $\mathbb{C}$, whose function field is $k(C) = \mathbb{C}[x, y]/(y^2 - x^3 - x)$. At the point $P = (0, 0)$, the associated maximal ideal of the local ring is $m_P = (x, y)$ having $m_P^2 = (x^2, xy, y^2)$. A priori we can see that m_P/m_P^2 is spanned as a vector space by x and y , but in fact since $x = y^2 - x^3 \equiv 0 \pmod{m_P^2}$, m_P/m_P^2 is generated by y by itself. (In terms of the local expansion near $(0, 0)$, this is the same as saying that the lowest-degree homogeneous component has degree 1, which is in turn simply saying that C is smooth at P .) As elements of the local ring $\mathcal{O}_P(C)$ we can observe that $x = \frac{y^2}{x^2 + 1}$ and since $\frac{1}{x^2 + 1} \in \mathcal{O}_P(C)$ does not vanish at P , this means $x \in (y^2)$ as an ideal of $\mathcal{O}_P(C)$, so again $m_P(C) = (x, y) = (y)$.
 - Exercise: Show that for any elliptic curve in reduced Weierstrass form $y^2 = x^3 + Ax + B$ and any point $P = (a, b)$ on C , then the corresponding maximal ideal $m_P = (x - a, y - b)$ of the local ring is principal and generated by either $y - b$ (when $y'(P) \neq 0$) or $x - a$ (when $y'(P) = 0$).
4. If P is a smooth point of the curve C and $g \in \mathcal{O}_P(C)$, we define the order of vanishing of $v_P(g)$ at P to be the maximum n for which $g \in m_P(C)^n$. We extend this map to rational functions $\alpha = f/g \in k(C)$ by setting $v_P(f/g) = v_P(f) - v_P(g)$.
- We will often also write $\text{ord}_P(\alpha)$ interchangeably with $v_P(\alpha)$.
 - If $g(P) \neq 0$ then the order of vanishing is zero, while if $g(P) = 0$ then the order of vanishing is 1 or larger. Since $\bigcap_{n=0}^{\infty} m_P(C)^n = 0$, any nonzero g has a finite order of vanishing (as usual we take the convention that $v_P(0) = \infty$).
 - Although the definition is somewhat complicated, the point is that this order-of-vanishing map is simply the familiar notion of the multiplicity of a zero or pole of a rational function (or of a convergent power series, in analytic contexts).
- Example: On $C = \mathbb{A}^1(\mathbb{C})$, consider $P = 0$. Then $\mathcal{O}_P$ is the set of rational functions $\frac{f(x)}{g(x)}$ with $g(0) \neq 0$ (i.e., rational functions defined at 0) and m_P is the set of rational functions vanishing at 0. It is easy to see that $m_P = (x)$, and so in general if we write a nonzero rational function in the form $x^a \frac{f(x)}{g(x)}$ where $f(0), g(0) \neq 0$, then $v_P(x^a \frac{f(x)}{g(x)}) = a$. For example, $v_P(x^2) = 2$ while $v_P(\frac{1}{x+1}) = 0$ and $v_P(\frac{x-1}{x^2+x}) = -1$. In each case we are simply computing the order of the zero or pole of the rational function at $x = 0$.
 - Example: On $C : y^2 = x^3 + x$ over $\mathbb{C}$, consider $P = (0, 0)$. As we saw above, $m_P = (y)$ and $x = \frac{y^2}{x^2 + 1}$, so for example we have $v_P(y) = 1$, $v_P(x) = 2$, and $v_P(\frac{1}{y^2 - x}) = v_P(\frac{1}{x^3}) = -6$.
5. If C is a smooth curve, then for any nonzero rational function $\alpha \in k(C)$, there are only finitely many points P such that $v_P(\alpha) \neq 0$. When $v_P(\alpha) = d > 0$ we say that α has a zero of order d at P , and when $v_P(\alpha) = -d < 0$ we say that α has a pole of order d at P .
- Exercise: Suppose C is a plane curve and $f(x, y)$ is a polynomial that is not identically zero on C . Show that there are only finitely many $P \in C$ for which $f(P) = 0$.
 - The idea is that for $\alpha = f/g$, any point with $v_P(\alpha) > 0$ requires $f(P) = 0$ and any point with $v_P(\alpha) < 0$ requires $g(P) = 0$. By the exercise above, for any fixed nonzero polynomials f and g on C , there are only finitely many such $P \in C$ with $f(P) = 0$ or $g(P) = 0$.
 - Example: On $C = \mathbb{A}^1(\mathbb{C})$, the rational function $\alpha = \frac{x^3}{x^2 - 1}$ has a zero of order 3 at $P = 0$ and poles of order 1 at $P = -1$ and $P = 1$, with no other zeroes or poles.
6. The order-of-vanishing map at a point P is in fact a discrete valuation on the function field $k(C)$.
- Recall that a discrete valuation on a field F is a surjective function $v : F^\times \rightarrow \mathbb{Z}$ such that $v(ab) = v(a) + v(b)$ for all $a, b \in F^\times$ and $v(a + b) \geq \min(v(a), v(b))$ for all $a, b \in F^\times$ with $a + b \neq 0$. By convention we also take $v(0) = \infty$, in which case the statements hold for all a, b . The valuation ring R is the set of elements $r \in F$ with $v(r) \geq 0$.
 - The valuation properties $v(ab) = v(a) + v(b)$ and $v(a + b) \geq \min(v(a), v(b))$ are essentially immediate, and the only result that needs to be checked is that there is an element of the maximal ideal $m_P(C)$ whose valuation equals 1. This follows by generalizing the observation made in the exercise following (3) that for $P = (a, b)$, either $x - a$ or $y - b$ must have valuation 1, for if not, the point P would be singular.

- Exercise (Properties of DVRs): Let F be a field with a discrete valuation v and valuation ring R . Also let $t \in R$ be a uniformizer (i.e., an element with $v(t) = 1$). Show that
 - (a) For any $r \in F^\times$, either r or $1/r$ is in R .
 - (b) An element $u \in R$ is a unit of R if and only if $v(u) = 0$. In particular, if $\zeta \in F$ is any root of unity, then $v(\zeta) = 0$.
 - (c) If $r \in R$ is nonzero and $v(r) = n$, then r can be written uniquely in the form $r = ut^n$ for a unit $u \in R$.
 - (d) Every nonzero ideal of R is of the form (t^n) for some $n \geq 0$.
 - (e) The ring R is a Euclidean domain (hence also a PID and a UFD) and also a local ring.
 - (f) The ring S is a DVR if and only if it is a PID and a local ring but not a field.
- The main issue with affine space is that it is missing points in a way that creates many unpleasant special cases and exceptions to various fundamental results. In order to rectify these issues we now enlarge our perspective to work in projective space:
- Definition: For a field k , we define projective n -space $\mathbb{P}^n(k) = \{[x_0 : x_1 : \cdots : x_n] : x_i \in k \text{ not all zero}\} / \sim$, where $P \sim Q$ if $P = \lambda Q$ for some nonzero $\lambda \in k$. Equivalently, $\mathbb{P}^n(k)$ is the set of lines through the origin in $\mathbb{A}^{n+1}(k)$.
 - We use the notation $[x_0 : x_1 : \cdots : x_n]$ to evoke the idea of considering only the ratios between the coordinates, since (for example) in $\mathbb{P}^1(k)$ the points $[1 : 1]$ and $[2 : 2]$ are the same. The coordinates x_i of a point $P \in \mathbb{P}^n(k)$ are not well-defined, but since the equivalence is only up to scaling by a nonzero constant, the statement “ $x_i = 0$ ” is still well-defined, as are the ratios x_i/x_j .
 - For the set $U_i = \{[x_0 : x_1 : \cdots : x_n] : x_i = 1\}$, we can see that U_i looks exactly like $\mathbb{A}^n(k)$ (if we just delete the coordinate $x_i = 1$), and $\mathbb{P}^n(k) = \bigcup_{i=0}^n U_i$.
 - The complement of the set U_i is the hyperplane $x_i = 0$, and it looks exactly like $\mathbb{P}^{n-1}$ (if we just delete the coordinate $x_i = 0$).
 - Thus, somewhat informally, we have $\mathbb{P}^n(k) = \mathbb{A}^n(k) \cup \mathbb{P}^{n-1}(k)$, where we can think of $\mathbb{A}^n(k)$ as being the points with $x_n = 1$ and $\mathbb{P}^{n-1}(k)$ as being the points with $x_n = 0$.
 - Example: We have $\mathbb{P}^1(k) = \{[x : 1] : x \in k\} \cup \{[1 : 0]\}$, which looks like $\mathbb{A}^1$ along with a point at ∞ .
- Evaluating an arbitrary polynomial on a projective point is not well defined, since projective points have various equivalent representatives, and the resulting polynomial value is not well-defined even up to scaling. But we are only interested in vanishing sets, which can be sensibly defined.
 - A natural but somewhat ill-advised option would be to say that $P \in \mathbb{P}^n(k)$ is in the vanishing set of $f \in k[x_0, \dots, x_n]$ if $f(P) = 0$ for *all* choices of coordinates for P .
 - Exercise: Suppose k is an infinite field, $P \in \mathbb{A}^{n+1} \setminus \{0\}$, and $f \in k[x_0, \dots, x_n]$. If we write $f = f_0 + f_1 + \cdots + f_d$ for homogeneous⁵ polynomials f_i of degree i , show that $f(\lambda P) = 0$ for all $\lambda \in k^\times$ if and only if $f_i(P) = 0$ for all i . [Hint: Use linear algebra and the fact that Vandermonde determinants are nonvanishing.]
 - Per the exercise above, we see that when k is an infinite field, requiring $f(P) = 0$ for all choices of coordinates for P is equivalent to requiring that all of the homogeneous components of f vanish.
 - For consistency with finite fields (which have nonzero polynomials that vanish everywhere, causing issues with the argument above), we instead define the vanishing of a polynomial f on a projective point P in terms of homogeneous components.
- Definition: If $f \in k[x_0, \dots, x_n]$ is a polynomial with $f = f_0 + f_1 + \cdots + f_d$ for homogeneous polynomials f_i of degree i , we say that f vanishes at $P \in \mathbb{P}^n(k)$, and write $f(P) = 0$, if $f_i(P) = 0$ for each i .
 - Note that $f_i(\lambda P) = \lambda^i f_i(P)$ so the vanishing condition on f_i does not depend on which equivalent coordinates are used for P .

⁵Recall that a polynomial is homogeneous of degree d if all of its monomial terms have total degree d . For example, $x^2y - 3x^3 + xyz$ is homogeneous of degree 3.

- Example: The polynomial $f(x, y) = x^2 - y^2$ vanishes at the projective point $[1 : 1]$ since its only nonzero homogeneous component $x^2 - y^2$ vanishes at P , but the polynomial $g(x, y) = x - y^2$ does not since its homogeneous components are x and $-y^2$ and these do not vanish at $[1 : 1]$.
- The main theme is that when we want to work with polynomials in projective space, we want to consider only homogeneous polynomials.
- Now that we have given a reasonable definition of vanishing for projective points, we can define the projective versions of the operators V and I :
- Definition: If S is any set of polynomials in $k[x_0, \dots, x_n]$, we define the vanishing locus $V(S) = \{P \in \mathbb{P}^n(k) : f(P) = 0 \text{ for all } f \in S\}$. Conversely, if X is any set of points in $\mathbb{P}^n(k)$, we define the ideal of functions vanishing on X as $I(X) = \{f \in k[x_0, \dots, x_n] : f(P) = 0 \text{ for all } P \in X\}$.
 - Exercise: Identify $V(x_0)$, $V(x_0^2)$, $V(x_1 - x_0)$, $V(x_1 - x_0^2)$, $V(x_1^2 - x_0^2)$, $V(x_0, x_1)$, $V(x_0, x_1, x_2)$, and $V(x_0x_1 - x_2^2)$ in $\mathbb{P}^2(k)$.
- All of the basic properties of the affine operators I and V also hold for the projective I and V (suitably modified):
 1. If I is the ideal generated by $T \subseteq k[x_0, \dots, x_n]$, then $V(T) = V(I)$.
 2. $V(0) = \mathbb{P}^n(k)$, $V(1) = \emptyset$, and $V(\{a_ix_j - a_jx_i\}_{0 \leq i, j \leq n}) = \{[a_0 : a_1 : \dots : a_n]\}$.
 3. $I(\emptyset) = k[x_0, \dots, x_n]$, $I(\mathbb{P}^n) = 0$ when k is infinite, and $I(\{[a_0 : a_1 : \dots : a_n]\}) = (\{a_ix_j - a_jx_i\}_{0 \leq i, j \leq n})$.
 4. $V(\cup_i I_i) = \cap_i V(I_i)$ and $V(IJ) = V(I) \cup V(J)$.
 5. For ideals I and J , if $I \subseteq J$ then $V(I) \supseteq V(J)$, and for sets X and Y , if $X \subseteq Y$ then $I(X) \supseteq I(Y)$.
 6. For any subset S of $k[x_0, \dots, x_n]$, $S \subseteq I(V(S))$ and $V(S) = V(I(V(S)))$.
 7. For any subset X of $\mathbb{P}^n(k)$, $X \subseteq V(I(X))$ and $I(X) = I(V(I(X)))$. Furthermore, $I(X)$ is a radical ideal.
- Owing to our definition of vanishing in terms of homogeneous components, the ideals of sets in $\mathbb{P}^n(k)$ have an additional property:
- Definition: An ideal I of $k[x_0, \dots, x_n]$ is homogeneous if, for any $f \in I$ with homogeneous decomposition $f = f_0 + f_1 + \dots + f_d$, it is true that each component $f_i \in I$.
 - It is easy to see that $I(X)$ is homogeneous, since for any $f = f_0 + f_1 + \dots + f_d \in I(X)$, by definition of vanishing we see that for any $P \in X$ we have $f_i(P) = 0$ and so $f_i \in I(X)$.
 - Exercise: Show that an ideal I of $k[x_0, \dots, x_n]$ is homogeneous if and only if I is generated by finitely many homogeneous polynomials.
- We also have a projective version of the Nullstellensatz, which is essentially the same as the affine version except that we must account for the fact that the vanishing locus of the ideal $(x_0, x_1, \dots, x_n)$ in $\mathbb{P}^n$ is empty since $[0 : 0 : \dots : 0]$ is not a point of $\mathbb{P}^n$:
- Theorem (Projective Nullstellensatz): Let k be an algebraically closed field and I be a homogeneous ideal of $k[x_0, \dots, x_n]$. Then the following hold:
 1. (Weak) $V(I) = \emptyset$ if and only if I contains all monomials of sufficiently large degree, if and only if $\text{rad}(I)$ contains $(x_0, \dots, x_n)$.
 2. (Strong) If $V(I) \neq \emptyset$, then $I(V(I)) = \text{rad}(I)$.
 - The proofs are similar to those of the affine Nullstellensatz, and are left as exercises.
 - Owing to the fact that its vanishing locus is trivial, and thus can essentially be ignored when doing computations, the ideal $(x_0, x_1, \dots, x_n)$ in $k[x_0, \dots, x_n]$ is called the irrelevant ideal.

0.6 (Sep 28) Projective Varieties, Rational Maps, Morphisms

- Next, we define algebraic sets, varieties, and coordinate rings in $\mathbb{P}^n$. The ideas proceed essentially the same way:
- Definition: A projective algebraic set is a set in $\mathbb{P}^n(k)$ of the form $V(I)$ for some ideal I of $k[x_0, \dots, x_n]$. A projective algebraic set V is reducible if it can be written as $V = V_1 \cup V_2$ where $V_1, V_2 \neq V$, and it is irreducible otherwise. A projective variety is an irreducible projective algebraic set.
 - As in the affine case, V is irreducible if and only if $I(V)$ is a prime ideal of $k[x_0, \dots, x_n]$, and any projective algebraic set can be written uniquely as a union of irreducible components $V_1 \cup V_2 \cup \dots \cup V_n$ such that $V_i \not\subseteq V_j$ for any $i \neq j$.
- Definition: If V is a projective variety, then its (homogeneous) coordinate ring is the integral domain $\Gamma(V) = k[x_0, \dots, x_n]/I(V)$.
 - As before, we may decompose the polynomials $f \in \Gamma(V)$ as $f = f_0 + f_1 + \dots + f_d$ where f_i is homogeneous of degree i .
 - Since $I(V)$ is prime, the coordinate ring is an integral domain, so its fraction field is well defined. Unlike in the affine case, however, the elements of this fraction field do not generally determine functions on V , because a ratio of polynomials need not be a function on V .
 - The first obvious issue is that for a ratio $\frac{f}{g} = \frac{f_0 + f_1 + \dots + f_d}{g_0 + g_1 + \dots + g_d}$, the various homogeneous terms in the numerator and denominator will not transform the same way if we choose a different representative for the projective point $P \in V$ at which we are attempting to evaluate f/g . (For example: what is the value of $\frac{x+y^2}{x+y}$ at the projective point $[1 : 1]$?)
 - To handle this issue, we must only have a single homogeneous component in the numerator and denominator. But even here, in order for the ratio to be well-defined, the degrees of the numerator and denominator must be equal.
 - When we restrict to rational functions of this form, however, we do obtain well-defined functions on projective points: if f, g are both homogeneous of degree d , then $\frac{f(\lambda P)}{g(\lambda P)} = \frac{\lambda^d f(P)}{\lambda^d g(P)} = \frac{f(P)}{g(P)}$, so the ratio f/g is well defined regardless of the representative of P we use.
- Definition: If V is a projective variety, its function field $k(V)$ is the set of elements z in the fraction field of $\Gamma(V)$ such that z can be written in the form $z = \frac{f}{g}$ for some homogeneous polynomials $f, g \in k[x_0, \dots, x_n]$ of the same degree. We say z is defined at a point $P \in V$ if $z = f/g$ for some g with $g(P) \neq 0$. The local ring of V at P is $\mathcal{O}_P(V) = \{z \in k(V) : z \text{ is defined at } P\}$ with maximal ideal $m_P(V) = \{z \in \mathcal{O}_P(V) : z(P) = 0\}$.
 - As in the affine case, we may require different expressions $z = f/g$ at different points P .
- Example: Consider the variety $V = V(Y^2 + Z^2 - X^2)$ in $\mathbb{P}^2(\mathbb{C})$ and the rational function $f = \frac{X-Z}{Y} \in k(V)$.
 - It is clear from the expression $f = \frac{X-Z}{Y}$ that f is defined at all points $P = [X : Y : Z] \in V$ where $Y \neq 0$, which is to say, at all points of the form $[X : 1 : Z]$ after rescaling. The only points of V with $Y = 0$ are those with $X^2 = Z^2$, which gives two points: $[1 : 0 : 1]$ and $[1 : 0 : -1]$.
 - However, because $\Gamma(V) = k[X, Y, Z]/(Y^2 + Z^2 - X^2)$, we see that $Y^2 = X^2 - Z^2$ in $\Gamma(V)$, by factoring and rearranging we see that $\frac{X-Z}{Y} = \frac{Y}{X+Z}$ inside $k(V)$. Therefore, f is also equal to $\frac{Y}{X+Z}$, and this latter expression shows that f is also defined at the point $[1 : 0 : 1]$ (and in fact it vanishes there).
 - On the other hand, there is no way to rewrite $f = \frac{X-Z}{Y}$ in such a way that it is defined at $[1 : 0 : -1]$: if $\frac{X-Z}{Y} = \frac{p}{q}$ then $(X-Z)q = Yp$ but then evaluating both sides (as polynomials in X, Y, Z) at $X = 1, Y = 0, Z = -1$ produces $-2q(1, 0, -1) = 0$, which is a contradiction since this means $q(P) = 0$.

- Remark: Note that this is just the projective version of the example we did earlier for the affine variety $V = V(y^2 + 1 - x^2)$ in $\mathbb{A}^2$.
- As clearly indicated by the similarity of the calculations in the example above and the nearly-identical affine example from earlier, there is quite a lot of interplay between projective and affine spaces.
 - One such correspondence is obtained by viewing $\mathbb{P}^n$ as the lines through the origin in $\mathbb{A}^{n+1}$, so for any set S in $\mathbb{P}^n$ we may write down the set of its corresponding points in $\mathbb{A}^{n+1}$ by converting the point $[x_0 : x_1 : \cdots : x_n]$ to the point $(x_0, x_1, \dots, x_n)$.
 - Explicitly, if $S \subseteq \mathbb{P}^n$, the cone $C(S)$ of S in $\mathbb{A}^{n+1}$ is the set $\{(x_0, x_1, \dots, x_n) : [x_0 : x_1 : \cdots : x_n] \in S\} \cup \{(0, 0, \dots, 0)\}$.
 - Exercise: When V is a nonempty projective algebraic variety, show that $I_{\text{affine}}(C(V)) = I_{\text{projective}}(V)$, and when I is a homogeneous ideal with $V_{\text{projective}}(I) \neq \emptyset$, show that $C(V_{\text{projective}}(I)) = V_{\text{affine}}(I)$.
- Although the cone of a variety shares the same underlying ideal, and thus has the same coordinate ring and function field, its dimension is different.
 - We would like instead to think of $\mathbb{P}^n$ as being $\mathbb{A}^n$ plus a hyperplane at ∞ , and so an affine variety in $\mathbb{A}^n$ should give rise to one that looks essentially the same in $\mathbb{P}^n$, except for having some additional points in the hyperplane at ∞ .
 - The main idea, as exemplified by comparing the example above to its affine version, is that of homogenization and dehomogenization.
- Definition: If $F \in k[x_0, x_1, \dots, x_n]$ is a polynomial, its dehomogenization with respect to x_0 is $F_* = F(1, x_1, \dots, x_n)$. Inversely, if $f \in k[x_1, \dots, x_n]$ is a polynomial, its homogenization with respect to x_0 is $f^* = x_0^{\deg(f)} f(x_1/x_0, x_2/x_0, \dots, x_n/x_0)$.
 - More explicitly, if $f \in k[x_1, \dots, x_n]$ has homogeneous decomposition $f = f_0 + f_1 + \cdots + f_d$, then $f^* = x_0^d f_0 + x_0^{d-1} f_1 + \cdots + f_d$.
 - Example: The homogenizations of $x_1^2 + x_2$, $4 + x_1 x_3 - 3x_4^5$, and 1 are $x_1^2 + x_0 x_2$, $4x_0^5 - x_0^3 x_1 x_3 - 3x_4^5$, and 1 respectively.
 - Example: The dehomogenizations of $x_0^2 + 3x_0 x_1 + x_1 x_2$, $x_0^3 + 4x_0 x_2^2 + x_3^3$, and x_0^2 are $1 + 3x_1 + x_1 x_2$, $1 + 4x_2^2 + x_3^3$, and 1 respectively.
 - The main idea is that dehomogenizing removes the variable x_0 by setting it equal to 1 (thereby usually creating a non-homogeneous polynomial in the remaining variables $x_1, \dots, x_n$) while homogenizing takes a non-homogeneous polynomial in $x_1, \dots, x_n$ and makes it homogeneous in $x_0, x_1, \dots, x_n$ by using the extra variable x_0 to make all of the terms have the same degree.
 - Homogenization and dehomogenization are essentially inverses of one another, aside from occasionally losing powers of x_0 .
 - Exercise: Show that $(FG)_* = F_* G_*$, $(fg)^* = f^* g^*$, $(f^*)_* = f$, $(F_*)^* = F/x_0^{v_{x_0}(f)}$, $(F + G)_* = F_* + G_*$, and $x_0^{\deg(f) + \deg(g) - \deg(f+g)} (f + g)^* = x_0^{\deg(g)} f^* + x_0^{\deg(f)} g^*$.
 - It is also possible to homogenize and dehomogenize with respect to the other variables, but we will not need to do this in any substantial way.
- The point is that homogenizing an affine equation creates a projective one, and dehomogenizing a projective equation yields an affine one, thereby giving a correspondence between affine varieties and projective varieties. Since our interest is specifically in plane curves, we will use affine variables $x = x_1$ and $y = x_2$ (written in lowercase), and projective variables X, Y , and Z , with homogenizations performed with respect to Z and dehomogenizations defined via $x = X/Z$, $y = Y/Z$.
 - Motivating Example: Homogenizing the affine equation $x + y = 1$ yields the projective equation $X + Y = Z$. An affine point (x, y) satisfying $x + y = 1$ yields a projective point $[x : y : 1] = [X : Y : Z]$ satisfying $X + Y = Z$. If we compare the affine points to the projective ones, we see that the projective variety consists of the points $[x : y : 1]$, which all correspond to affine points, along with one additional point $[1 : -1 : 0]$ which we think of as the point at ∞ on this line.

- Motivating Example: Dehomogenizing the projective equation $Y^2Z = X^3 + XZ^2$ yields the affine equation $y^2 = x^3 + x$. A projective point $[X : Y : Z]$ satisfying $Y^2Z = X^3 + XZ^2$ yields an affine point $(x, y) = (X/Z, Y/Z)$ satisfying $y^2 = x^3 + x$, as long as $Z \neq 0$. When we dehomogenize, the projective points $[X : Y : Z]$ with $Z = 0$ “disappear” from the affine curve: note here that there is only one such point, namely $[0 : 1 : 0]$, which represents the point at ∞ on this elliptic curve.
- Exercise: Show that there exists a unique projective point $[X : Y : Z]$ with $Z = 0$ on any elliptic curve with a Weierstrass equation $Y^2Z + a_1XYZ + a_3YZ^2 = X^3 + a_2X^2Z + a_4XZ^2 + a_6Z^3$.
- We can extend the notion of homogenization to ideals and then to algebraic sets in fairly natural ways:
 - Definition: If $I = (f_1, \dots, f_k)$ is an ideal of $k[x_1, \dots, x_n]$, the homogenization of I is the ideal $I^* = (f_1^*, \dots, f_k^*)$ generated by the homogenizations of the generators of I . Conversely, if J is an ideal of $k[x_0, x_1, \dots, x_n]$, the dehomogenization of J is the ideal $J_* = \{g_* : g \in J\}$ of dehomogenizations of the elements of J (and is generated by the dehomogenizations of the generators of J).
 - We are only interested in the situation of plane curves, in which the ideals are principal, so the homogenization and dehomogenization are quite easy to handle.
 - Definition: If V is an affine algebraic set, then for $I = I_{\text{affine}}(V)$ we define the homogenization of V to be the projective algebraic set $V^* = V_{\text{projective}}(I^*)$. Conversely, if W is a projective algebraic set, then for $J = I_{\text{projective}}(W)$ we define the dehomogenization of W to be the affine algebraic set $W_* = V_{\text{affine}}(J_*)$.
- Proposition (Equivalence of Function Fields): If V is an affine variety with projective closure V^* , then the function fields $k(V)$ and $k(V^*)$ are isomorphic. Furthermore, if P is any point on V with corresponding point P^* on V^* , then the isomorphism of $k(V)$ and $k(V^*)$ also yields an isomorphism of $\mathcal{O}_P(V)$ with $\mathcal{O}_{P^*}(V^*)$ and of $m_P(V)$ with $m_{P^*}(V^*)$.
 - The point here is that locally (near a given point P) the affine variety V and its projective closure V^* look equivalent, and their function fields are also the same.
 - As such, we may also immediately import all of our other constructions defined in terms of the local ring and its maximal ideal from the affine case: most importantly, the notion of the order of vanishing of a rational function at a point.
- So far, we have mostly been assuming that the constant field k is algebraically closed. In particular, since we are interested in elliptic curves over $\mathbb{Q}$ and $\mathbb{F}_q$, we will need to remove this assumption.
 - Explicitly, suppose V is a variety over k and E is a subfield of k . We would naively like to define the set of E -points of V as $V \cap \mathbb{A}^n(E)$ if V is affine, and as $V \cap \mathbb{P}^n(E)$ if V is projective.
 - We may make this more precise using Galois actions: specifically, assuming that $k = \overline{E}$, then the Galois group of k/E acts naturally on the k -points of V .
- Definition: Let E be a field with algebraic closure k , and let $G = \text{Gal}(k/E)$. If V is a variety over k , we define the E -points of V to be the set of points of V over k that are fixed by G .
 - Explicitly, P is an E -point of V if and only if $\sigma(P) = P$ for all $\sigma \in \text{Gal}(k/E)$.
 - The set of E -points of V is precisely $V \cap \mathbb{A}^n(E)$ if V is affine, and is $V \cap \mathbb{P}^n(E)$ if V is projective, since the given condition is equivalent to saying that all of the coordinates of the point lie in E . (Note that for projective points, we only need one representative to have all its coordinates in E .)
 - Example: For $E = \mathbb{F}_5$ and $V = V(y^2 - x^2 - 1)$ in $\mathbb{A}^2$, the set of E -points of V is $(x, y) = (0, 1), (0, 4), (2, 0)$, and $(3, 0)$.
 - Example: For $E = \mathbb{F}_3$ and $V = V(Y^2Z^2 - XZ^3 - X^4)$ in $\mathbb{P}^2$, the set of E -points of V is $[X : Y : Z] = [0 : 0 : 1], [0 : 1 : 0], [1 : 0 : 2]$.
 - We can also define the elements of the coordinate ring and function field of V over E , namely, as the elements of $\Gamma(V)$ and $k(V)$ fixed by $\text{Gal}(k/E)$, respectively.
- Definition: If E is a field with algebraic closure k , we say that a variety V is defined over E if $I(V)$ can be generated by polynomials with coefficients in E .

- We will think of all varieties as implicitly being defined over an algebraically closed field, even if they are actually defined over a subfield.
- Thus, we may meaningfully speak of the points of V on arbitrary algebraic extensions of E .
- If P is a point on $k(V)$, we define the degree of P over E to be the degree of the smallest field extension L/E such that $P \in L(V)$.
- We now discuss maps between varieties. The most natural starting point is to consider maps defined by polynomials:
- Definition: If V is an affine variety in $\mathbb{A}^n(k)$ and W is an affine variety in $\mathbb{A}^m(k)$, a map $\varphi : V \rightarrow W$ is called a polynomial map from V to W if there exist polynomials $T_1, \dots, T_m \in k[x_1, \dots, x_n]$ such that $\varphi(a_1, \dots, a_n) = (T_1(a_1, \dots, a_n), T_2(a_1, \dots, a_n), \dots, T_m(a_1, \dots, a_n))$.
 - Example: The map $\varphi : \mathbb{A}^1 \rightarrow \mathbb{A}^1$ with $\varphi(a) = a^2 + a$ is a polynomial map, as is the map $\varphi : \mathbb{A}^1 \rightarrow \mathbb{A}^3$ with $\varphi(a) = (a, a^2, a^3)$.
 - Example: The map $\varphi : V(x^2 + y^2 - 1) \rightarrow \mathbb{A}^1$ with $\varphi(x, y) = x$ is a polynomial map.
 - Example: The map $\varphi : \mathbb{A}^2 \rightarrow V(x^2 + y^2 - z^2)$ with $\varphi(a, b) = (2ab, a^2 - b^2, a^2 + b^2)$ is a polynomial map. Note that this map is well-defined because $(2ab)^2 + (a^2 - b^2)^2 - (a^2 + b^2)^2$ is indeed zero for all $(a, b) \in \mathbb{A}^2$, so $(2ab, a^2 - b^2, a^2 + b^2) \in V(x^2 + y^2 - z^2)$.
 - Example: The map $\varphi : V(y - x^2) \rightarrow V(z - xy)$ with $\varphi(x, y) = (x, y, x^3)$ is a polynomial map. Note that this map is well-defined because for all $(x, y) \in V(y - x^2)$ we have $y = x^2$, and then $(x, y, x^3) \in V(z - xy)$.
- Polynomial maps are equivalent to homomorphisms of coordinate rings:
- Proposition (Polynomial Maps and Coordinate Rings): If V and W are affine varieties, then any polynomial map $\varphi : V \rightarrow W$ induces a homomorphism $\varphi^* : \Gamma(W) \rightarrow \Gamma(V)$ on coordinate rings via “plugging in”: $\varphi^*(f) = f \circ \varphi$. Conversely, any homomorphism $\varphi^* : \Gamma(W) \rightarrow \Gamma(V)$ is induced by a unique polynomial map $\varphi : V \rightarrow W$ with $\varphi^*(f) = f \circ \varphi$.
 - Proof: First suppose $\varphi : V \rightarrow W$ is a polynomial map. For any $f \in k[x_1, \dots, x_n]$, define $\psi(f) = f \circ \varphi$. Clearly, ψ is a ring homomorphism (since it is just polynomial evaluation). Furthermore, this map ψ descends to a well-defined map $\tilde{\varphi} : \Gamma(W) \rightarrow \Gamma(V)$: this follows by noting that if $f \in \Gamma(W)$ is the $I(W)$ -residue of a polynomial $G(x_1, \dots, x_n)$, then $\tilde{\varphi}(f) = f \circ \varphi$ is the $I(V)$ -residue of the polynomial $G(T_1, \dots, T_m)$.
 - For the converse, we can simply reconstruct the map φ from its action on each variable x_i . Explicitly, suppose that $\tilde{\varphi} : \Gamma(W) \rightarrow \Gamma(V)$ is a homomorphism. Then $\tilde{\varphi}$ maps $x_i + I(W)$ to some polynomial $T_i + I(V)$ for each $1 \leq i \leq m$. Then the map $\varphi(a_1, \dots, a_n) = (T_1(a_1, \dots, a_n), \dots, T_m(a_1, \dots, a_n))$ is a polynomial map from $\mathbb{A}^n$ to $\mathbb{A}^m$, and it induces a map $\hat{\varphi} : \Gamma(\mathbb{A}^m) \rightarrow \Gamma(\mathbb{A}^n)$. From the information given we know that $\hat{\varphi}(I(W)) \subseteq I(V)$, so $\varphi(V) \subseteq W$. Thus, $\varphi|_V$ is a polynomial map from V to W , and $\tilde{\varphi}(f) = f \circ \varphi$ as required.
- Definition: If V and W are affine varieties, a polynomial map $\varphi : V \rightarrow W$ is an isomorphism if it possesses an inverse polynomial map $\psi : W \rightarrow V$ (i.e., with $\varphi \circ \psi = \text{id}_W$ and $\psi \circ \varphi = \text{id}_V$).
 - By the above, we see that V and W are isomorphic if and only if their coordinate rings are isomorphic as k -algebras (i.e., if their coordinate rings are isomorphic as rings where the isomorphism also fixes k).
 - Example: The map $\varphi : V(x - y) \rightarrow V(x - 2y)$ with $\varphi(x, y) = (2x, y)$ is an isomorphism with inverse $\psi(x, y) = (x/2, y)$.
 - Exercise: Show that the affine linear maps $\varphi : \mathbb{A}^n \rightarrow \mathbb{A}^n$ of the form $\varphi(x) = Ax + b$ where A is an invertible $n \times n$ matrix and b is any vector of constants, are isomorphisms. Find another isomorphism $\varphi : \mathbb{A}^n \rightarrow \mathbb{A}^n$ not of this form.
- We would like to write down a similar definition for projective varieties, which we can do at the cost of a bit of added complexity.
 - The most immediate issue is that we need to insist that all of the polynomials T_i be homogeneous of the same degree, in order to ensure that “plugging in” to a polynomial map is well defined.

- However, this is not the only obstruction; difficulties also arise in the event that all of the polynomials T_i vanish simultaneously, since then the resulting value does not yield a well-defined point in $\mathbb{P}^1$.
- Definition: If V and W are projective varieties, a rational map from V to W is a map of the form $\varphi = [\varphi_0 : \varphi_1 : \cdots : \varphi_m]$ where the $\varphi_i \in k[x_0, \dots, x_n]$ are homogeneous polynomials of the same degree, and such that for all $f \in I(W)$, we have $f \circ \varphi = f(\varphi_0(x_0, \dots, x_n), \dots, \varphi_m(x_0, \dots, x_n)) \in I(V)$.
 - If φ is a rational map, then for $P \in V$ we can evaluate $\varphi(P) = [\varphi_0(P) : \varphi_1(P) : \cdots : \varphi_m(P)] \in W$ as long as not all of the values $\varphi_i(P)$ are zero. We can see that this value $\varphi(P)$ is well defined because the φ_i are homogeneous of the same degree, and $\varphi(P) \in W$ precisely because $f \circ \varphi \in I(V)$ for any $f \in I(W)$.
 - To illustrate, consider the map $\varphi : V(X^2 + Y^2 - Z^2) \rightarrow \mathbb{P}^1$ given by $\varphi[X : Y : Z] = [X + Z : Y]$. On its face, this would appear to be a perfectly well-defined function, since for any equivalent representative $[\lambda X : \lambda Y : \lambda Z]$ we have $\varphi[\lambda X : \lambda Y : \lambda Z] = [\lambda X + \lambda Z : \lambda Y] = [X + Z : Y] = \varphi[X : Y : Z]$.
 - However, for the point $P = [1 : 0 : -1]$ in $V(X^2 + Y^2 - Z^2)$, the definition states $\varphi(P) = [0 : 0]$, which is not a point of $\mathbb{P}^1$.
 - Notice, though, that if we work inside $\Gamma(V)$, we see that $[X + Z : Y] = [(X + Z)(X - Z) : Y(X - Z)] = [-Y^2 : Y(X - Z)] = [-Y : X - Z]$ and this latter expression *is* defined at $[1 : 0 : -1]$ since it evaluates to $[0 : 2]$.
 - We would like to extend our interpretation of the value of $\varphi(P)$ in a way that allows us to make these kinds of manipulations.
- Definition: If $\varphi : V \rightarrow W$ is a rational map, we say that $\varphi = [\varphi_0 : \cdots : \varphi_m]$ is defined at P if there exist homogeneous polynomials $\psi_0, \dots, \psi_n$ of the same degree such that $\varphi_i \psi_j \equiv \varphi_j \psi_i \pmod{I(V)}$ for all pairs (i, j) with $\psi_i(P) \neq 0$ for some i , and we write $\varphi(P) = [\psi_0(P) : \cdots : \psi_m(P)]$.
 - The idea here is that, inside $\Gamma(V)$, we view the homogeneous coordinates $[\varphi_0 : \cdots : \varphi_m]$ and $[\psi_0 : \cdots : \psi_m]$ as being projectively equivalent.
 - We call these “rational maps” because if we work affinely, they arise from rational functions.
- Definition: If V and W are varieties, a morphism from V to W is a rational map that is defined at all points of V . An isomorphism is a morphism possessing an inverse morphism.
 - If $\varphi : V \rightarrow W$ is a morphism, then φ induces an injective homomorphism on function fields $\varphi^* : k(W) \rightarrow k(V)$ via composition: $\varphi^*(f) = f \circ \varphi$.
 - As in the affine case for polynomial maps, the converse is true as well: any injective k -algebra homomorphism (i.e., a ring homomorphism fixing k) on function fields $\varphi^* : k(W) \rightarrow k(V)$ yields a morphism $\varphi : V \rightarrow W$.
 - Example: The map $\varphi : V(Y^2Z - X^3 - XZ^2) \rightarrow \mathbb{P}^1$ given by $\varphi[X : Y : Z] = [Y : Z]$ is a morphism. (Note that there are no points of $V(Y^2Z - X^3 - XZ^2)$ where φ is undefined, since if $Y = Z = 0$ then X would also be zero.)
 - Example: The map $\varphi : V(X^2 + Y^2 - Z^2) \rightarrow \mathbb{P}^1$ given by $\varphi[X : Y : Z] = [X + Z : Y]$ is a morphism, since it is defined at all points of $V(X^2 + Y^2 - Z^2)$ as shown earlier.
 - Example: The map $\psi : \mathbb{P}^1 \rightarrow V(X^2 + Y^2 - Z^2)$ given by $\psi[S : T] = [S^2 - T^2 : 2ST : S^2 + T^2]$ is a morphism. In fact, it is the inverse of the previous morphism, since we have $(\varphi \circ \psi)[S : T] = \varphi[S^2 - T^2 : 2ST : S^2 + T^2] = [2S^2 : 2ST] = [S : T]$ and $(\psi \circ \varphi)[X : Y : Z] = \psi[X + Z : Y] = [(X + Z)^2 - Y^2 : 2Y(X + Z) : (X + Z)^2 + Y^2] = [2X(X + Z) : 2Y(X + Z) : 2Z(X + Z)] = [X : Y : Z]$.
 - Example: The map $\psi : V(Y^2Z - X^3 - XZ^2) \rightarrow V(Y^2Z - X^3 - XZ^2)$ given by $\psi[X : Y : Z] = [X : -Y : Z]$ is a morphism. In fact, it is an isomorphism, since it is its own inverse. (This is the additive inverse map on this elliptic curve.)
 - Example: The map $\psi : V(Y^2Z - X^3 - XZ^2) \rightarrow V(Y^2Z - X^3 - XZ^2)$ given by $\psi[X : Y : Z] = [2XY(Y^2 - 9Z^2) : Y^4 + 18Y^2Z^2 - 27Z^4 : 8Y^3Z]$ is a morphism. (Actually checking that it is well-defined using the definition is rather unpleasant, but it does work out!) This morphism does not magically arise from nowhere, of course: in fact it is simply the doubling map on this elliptic curve.

- Example: More generally, if E is any elliptic curve in projective Weierstrass form, the multiplication-by- m map is a morphism from E to E , as follows from the fact that it has a formula as a rational function (as we saw semi-explicitly in our proof of Nagell-Lutz) and is defined at every point on E .
 - Example: If k has characteristic q and V is defined over $\mathbb{F}_q$, the map $\varphi : V \rightarrow V$ given by $\varphi[X_0 : X_1 : \cdots : X_n] = [X_0^q : X_1^q : \cdots : X_n^q]$ is a morphism called the Frobenius morphism.
 - Example: The map $\varphi : \mathbb{P}^1 \rightarrow \mathbb{P}^2$ given by $\varphi[X : Y] = [X^2 : XY : Y^2]$ is a morphism giving an embedding of $\mathbb{P}^1$ into $\mathbb{P}^2$ (it is an example of the general family of d -uple embeddings). The image of φ is the variety $V(XZ - Y^2)$.
- Restricting now to the case of projective curves, we have the following facts:
 1. If C_1 is a smooth projective curve, then any rational map $\varphi : C_1 \rightarrow C_2$ is automatically a morphism.
 - The idea here is that if P is any point on C_1 , then since C_1 is smooth at P (meaning that the local ring $\mathcal{O}_P(V)$ is a DVR), we may choose a local uniformizer t at P (i.e., a generator for the maximal ideal $m_P(V)$).
 - Then we can rescale the components of $\varphi = [\varphi_0 : \varphi_1 : \cdots : \varphi_m]$ by an appropriate power of t in order to make the minimum valuation among the φ_i equal to zero, at which point we see that φ is defined at P .
 - Exercise: Show that the map $\varphi : \mathbb{P}^2 \rightarrow \mathbb{P}^2$ given by $\varphi[X : Y : Z] = [YZ : ZX : XY]$ is a rational map that is its own inverse, yet φ is not a morphism because it is not defined at the points $[1 : 0 : 0]$, $[0 : 1 : 0]$, and $[0 : 0 : 1]$. (The point here is that in general, rational maps and morphisms are not the same; even birational maps need not be morphisms!)
 2. If $\varphi : C_1 \rightarrow C_2$ is a nonconstant morphism of projective curves, then φ is surjective, and $k(C_1)$ is a finite-degree extension of $\varphi^*(k(C_2))$. The degree of this field extension $[k(C_1) : \varphi^*(k(C_2))]$ is the degree of the map φ .
 - The first statement follows from the result that the image of a morphism of a projective variety is itself a projective variety (this is usually phrased as saying that projective varieties are complete). Thus, the image $\varphi(C_1)$ is a subvariety of C_2 : if its dimension is 1 then since C_2 is irreducible this means $\varphi(C_1) = C_2$, and otherwise if its dimension is 0 then $\varphi(C_1)$ would be a single point and φ would be constant, which we assumed it was not.
 - The fact that $k(C_1)$ is an extension of $k(C_2)$ follows from the fact that φ is surjective, and the fact that the extension has finite degree follows because both $k(C_1)$ and $k(C_2)$ have transcendence degree 1 over k .
 3. If $\iota : k(C_2) \rightarrow k(C_1)$ is an injection fixing k , then there is a unique nonconstant morphism $\varphi : C_1 \rightarrow C_2$ such that $\varphi^* = \iota$.
 - Example: Let C be any smooth projective curve and $\alpha \in k(C)$ be any rational function on C . Then α defines a rational map $\alpha : C \rightarrow \mathbb{P}^1$ via $P \mapsto \alpha(P)$, where we take $\alpha(P) = \infty$ when α is not defined at P . By (1) above, this map α is a morphism.
 - In fact, aside from constant maps, the rational maps described above are all possible morphisms from C to $\mathbb{P}^1$: if $\alpha : C \rightarrow \mathbb{P}^1$ is a rational map, say $\alpha = [f : g]$, then either g is identically zero in which case α is constant, or the function $\beta = f/g \in k(C)$ has $\beta(P) = \alpha(P)$ for all P so that $\alpha = \beta$.

0.7 (Oct 1) Divisors on Curves

- Our next task is to study divisors on curves, which will be central to our analysis of elliptic curves using the tools from algebraic geometry we have discussed so far.
 - In all of our discussion, C will be a smooth projective curve defined over the algebraically closed field k .
 - We emphasize here that when we say “points of C ”, we are implicitly thinking of C as being defined over an algebraically closed field, and the points have coordinates in this algebraically closed field.
 - For notational convenience, we will also usually give examples written in affine form rather than projective form, because the notation is less cumbersome: the point $x \in \mathbb{A}^1$ will be written P_x , while the point $(x, y) \in V(f(x, y))$ inside $\mathbb{A}^2$ will be written $P_{(x, y)}$, and the point at ∞ will be written P_∞ .

- Definition: Let C be a smooth curve. The divisor group of C , written $\text{Div}(C)$, is the additive free abelian group generated by the k -points of C . The degree of a divisor $D = \sum_{P \in C} n_P P$ is $\deg(D) = \sum_{P \in C} n_P$. The degree map is a homomorphism from D_C to $\mathbb{Z}$; its kernel is the set of degree-0 divisors $\text{Div}^0(C)$.
 - The elements of $\text{Div}(C)$ are of the form $D = \sum_{P \in C} n_P P$ for $n_P \in \mathbb{Z}$, where all but finitely many of the n_P are zero. We will write $\text{ord}_P(D) = n_P$.
 - Note that the degree map is well defined since all but finitely many n_P are zero.
- As an aside, we will give a bit of motivation for why divisors are called “divisors”, since they seem to have nothing obvious to do with divisibility.
 - If $C_1 = V(f)$ and $C_2 = V(g)$ are two distinct projective plane curves sharing no common component, then their intersection $C_1 \cap C_2 = V(f, g)$ is finite. (Indeed, more is true: Bézout’s theorem states that the number of intersection points is at most $\deg(f) \cdot \deg(g)$.)
 - We may then associate a divisor to this intersection $C_1 \cap C_2$ as $\sum_{P \in C_1 \cap C_2} n_P P$, where n_P is the intersection number of $C_1 \cap C_2$ at P given by $n_P = \dim_k \mathcal{O}_P(\mathbb{P}^2)/(f, g)$.
 - For polynomials in one variable, the ideal (f, g) is principal and generated by the gcd of f and g . (One may check that the intersection number at a point P , under the definition above, is the power of $x - P$ that divides their gcd.)
 - For polynomials in two variables (f, g) will no longer be principal, but it still carries the natural sense of being a “common divisor”. Thus, we can think (roughly) of the divisor $\sum_{P \in C_1 \cap C_2} n_P P$ as describing the precise way in which the curves C_1 and C_2 intersect.
 - It is not particularly obvious that this value $\dim_k \mathcal{O}_P(\mathbb{P}^2)/(f, g)$ is really the right definition. It is not hard to see that the value is invariant under linear changes of coordinates, and that the intersection number is 1 whenever P is a simple point of C_1 and C_2 where C_1 and C_2 meet transversally (i.e., their tangent lines at P are different). It is also additive when we take unions of curves.
 - We will not really use this particular formulation of divisors; it is merely some motivation for how divisors arise in a fairly natural way in the context of curves.
- If E is a subfield of the algebraically closed field k over which C is defined, the Galois group $\text{Gal}(k/E)$ acts on the k -rational points of C , and thus it also acts on divisors pointwise.
- Definition: Suppose C is a smooth curve defined over the algebraically closed field k , and E is a subfield of k with $\bar{E} = k$. If $\sigma \in \text{Gal}(k/E)$ is an element of the Galois group and $D = \sum_{P \in C} n_P P$ is a divisor, we define the action of σ on D via $\sigma(D) = \sum_{P \in C} n_P \sigma(P)$. We then say a divisor D is defined over E when $\sigma(D) = D$ for all $\sigma \in \text{Gal}(k/E)$, and we denote the subgroup of divisors defined over E as $\text{Div}_E(C)$.
 - If all of the points with nonzero coefficients in D are defined over E then certainly D is defined over E , but this is not necessary. All that is required is for Galois-conjugate points to have the same coefficients, as is seen immediately by comparing $\sigma(D) = \sum_{P \in C} n_P \sigma(P)$ to the reindexed sum $D = \sum_{P \in C} n_{\sigma(P)} \sigma(P)$: one requires $n_{\sigma(P)} = n_P$ for all $P \in C$ and all $\sigma \in \text{Gal}(k/E)$.
 - For example, for the curve $C = \mathbb{A}^1(\mathbb{C})$, with $P = i$ and $Q = -i$, the divisor $2P + Q$ is defined over $\mathbb{Q}(i)$ (any element of the Galois group $\mathbb{C}/\mathbb{Q}(i)$ fixes i and $-i$, hence sends P to P and Q to Q) while the divisor $P + Q$ is defined over $\mathbb{Q}$ (any element of the Galois group $\mathbb{C}/\mathbb{Q}$ either fixes i or maps it to $-i$, and these operations map $P + Q$ to $P + Q$ or $Q + P$ respectively).
- We can attach a divisor to a rational function on C using its zeroes and poles:
- Definition: Let C be a smooth curve and $\alpha \in k(C)$ be a nonzero rational function on C . We define the divisor of α , denoted $\text{div}(\alpha)$, as $\text{div}(\alpha) = \sum_{P \in C} v_P(\alpha) P$. The divisors of the form $\text{div}(\alpha)$ for some $\alpha \in k(C)^\times$ are called principal divisors.
 - Remark: In many sources, the divisor of α is often written (α) . In our context, this can lead to ambiguities, since the same notation is also used for the ideal generated by α . As such, we will only ever write $\text{div}(\alpha)$ for the divisor of α .

- As we have already shown, for any nonzero α , $v_P(\alpha)$ is nonzero only for finitely many $P \in C$, so $\text{div}(\alpha)$ is well defined.
- Now because $\text{ord}_P(\alpha/\beta) = \text{ord}_P(\alpha) - \text{ord}_P(\beta)$, summing over all primes shows that $\text{div}(\alpha/\beta) = \text{div}(\alpha) - \text{div}(\beta)$, so the principal divisors are a subgroup of the divisor group $\text{Div}(C)$.
- When computing the divisor of a function on a smooth curve C , remember that all of our curves are (implicitly) projective curves. (Thus, even when we are working with an affine equation, we must also include the point at ∞ .)
- Example: For $C = \mathbb{P}^1(\mathbb{C})$, with points denoted $[X : Y]$, for the rational function $\alpha = \frac{X}{Y}$ we have $\text{div}(\alpha) = P_{[0:1]} - P_{[1:0]}$ where $P_{[0:1]}$ represents the point $[0 : 1]$ (i.e., the point where $X = 0$) and $P_{[1:0]}$ represents the point $[1 : 0]$ (i.e., the point where $Y = 0$).
- Example: For $C = \mathbb{P}^1(\mathbb{C})$, for the rational function $\beta = \frac{X^3 - XY^2}{Y^3}$ we have $\text{div}(\beta) = P_{[0:1]} + P_{[1:1]} + P_{[-1:1]} - 3P_{[1:0]}$, using the same notation as above. Note that β has three single zeroes at $[0 : 1]$, $[1 : 1]$, and $[-1 : 1]$ and a triple pole at $[1 : 0]$.
- If we dehomogenize the two examples above, so as to work instead with the affine line $\mathbb{A}^1$, the corresponding rational functions are $\alpha_* = x$ and $\beta_* = x^3 - x$, with associated divisors $\text{div}(\alpha_*) = P_0 - P_\infty$ and $\text{div}(\beta_*) = P_0 + P_1 + P_{-1} - 3P_\infty$.
- Exercise: On $C = \mathbb{A}^1(\mathbb{C})$, suppose $\alpha = u \frac{(x - p_1)^{a_1} \cdots (x - p_l)^{a_l}}{(x - q_1)^{b_1} \cdots (x - q_m)^{b_m}}$ for $u \in k^\times$ and take distinct elements $p_1, \dots, p_l, q_1, \dots, q_m \in k$ having associated points $P_1, \dots, P_l, Q_1, \dots, Q_m$ respectively. Show that $\text{div}(\alpha) = a_1 P_1 + \cdots + a_l P_l - b_1 Q_1 - \cdots - b_m Q_m + [\sum_j b_j - \sum_i a_i] \infty$. [Hint: This is just a generalization of the examples above.]
- Exercise: Show that for any $C = \mathbb{A}^1(\mathbb{C})$ and any nonzero rational function $\alpha \in \mathbb{C}(C)$ we have $\deg(\text{div}(\alpha)) = 0$.
- Example: For $C = V(Y^2Z - X^3 - XZ^2)$ consider the rational function $\gamma = \frac{Y}{Z}$. The zeroes for γ can only occur when $Y = 0$ yielding the points $[0 : 0 : 1]$, $[i : 0 : 1]$, $[-i : 0 : 1]$, while the poles for γ can only occur when $Z = 0$ yielding the point $[0 : 1 : 0]$. To compute the order of vanishing γ at each point we may compute a local uniformizer (for the three zeroes, $\gamma = Y/Z$ is itself a local uniformizer, while for the pole, Z/X is a local uniformizer). One obtains $\text{ord}_{[0:0:1]}\gamma = \text{ord}_{[i:0:1]}\gamma = \text{ord}_{[-i:0:1]}\gamma = 1$ and also $\text{ord}_{[0:1:0]}\gamma = -3$, so $\text{div}(\gamma) = P_{[0:0:1]} + P_{[i:0:1]} + P_{[-i:0:1]} - 3P_{[0:1:0]}$.
- If we dehomogenize the example above, so as to work instead with the affine model $y^2 = x^3 + x$, the corresponding rational function is $\gamma_* = y$ with associated divisor $\text{div}(\gamma_*) = P_{(0,0)} + P_{(i,0)} + P_{(-i,0)} - 3P_\infty$.
- Motivated by the calculations for $K = \mathbb{C}(t)$, we can also pick out the zeroes (respectively, poles) of an element by extracting only the portion of its divisor with positive (respectively, negative) coefficients:
- Definition: If $\alpha \in k(C)^\times$ has divisor $\text{div}(\alpha) = \sum_P n_P P$, we define the “zero divisor” $\text{div}_+(\alpha) = \sum_P \max(0, n_P) P = \sum_{P: n_P > 0} n_P P$ and the “pole divisor” $\text{div}_-(\alpha) = \sum_P \min(0, n_P) P = \sum_{P: n_P < 0} n_P P$.
 - Notice that $\text{div}(\alpha) = \text{div}_+(\alpha) - \text{div}_-(\alpha)$ for any element $\alpha \in k(C)^\times$.
 - Remark: There are various other notations for these quantities that are often used, such as $(a)_0$ for div_+ and $(a)_\infty$ for div_- , which are intended to evoke the idea of picking out the zeroes and poles of a .
 - Exercise: For any field k , if $f(t), g(t) \in k[t]$ are relatively prime, show that $[k(t) : k(\frac{f(t)}{g(t)})] = \max(\deg f, \deg g)$. [Hint: Use Gauss’s lemma to show that $q(y) = f(y) - \frac{f(t)}{g(t)}g(y) \in k(\frac{f(t)}{g(t)})[y]$ is the minimal polynomial of t over $k(\frac{f(t)}{g(t)})$.]
 - In the example above, we can also compute that $\deg(\text{div}_+(\alpha)) = \deg(\text{div}_-(\alpha)) = \deg(f) = \deg(g)$, and by the exercise above, this quantity is equal to the extension degree $[k(C) : k(\alpha)]$. In fact, this result is true in general:
- Theorem (Divisor Degrees): For any nonconstant $\alpha \in k(C)^\times$ on a curve C/k , we have $\deg(\text{div}_+(\alpha)) = \deg(\text{div}_-(\alpha)) = [k(C) : k(\alpha)]$. As a consequence, $\deg(\text{div}(\alpha)) = 0$ for all such α .

- We will defer the proof of this result temporarily, since it would otherwise require developing a lot of additional material out of order.
- Our main observation here is that the divisor of an element $a \in k(C)^\times$ always has degree 0, which is to say, the principal divisors are actually a subgroup of the group of degree-0 divisors.
- Definition: On a curve C/k , we say two divisors D_1 and D_2 are linearly equivalent (and write $D_1 \sim D_2$) if $D_1 - D_2$ is principal. The resulting equivalence classes (i.e., divisors modulo principal divisors) form a group called the class group, or the Picard group, of C .
 - Exercise: Verify that this relation is an equivalence relation and that the equivalence classes are the elements in the quotient group of divisors modulo principal divisors.
 - Some notation for all of these various groups: $\text{Div}(C) = D_C$ is the group of all divisors on C , $\text{Div}^0(C)$ is the group of degree-0 divisors on C , $\text{Cl}(C) = \text{Pic}(C) = \text{Div}(C)/[\text{principal divisors}]$ is the class group of C .
 - Since principal divisors all have degree zero, we can also form the reduced Picard group $\text{Pic}^0(C) = \text{Div}^0(C)/[\text{principal divisors}]$.
- For $\mathbb{P}^1$, the reduced Picard group is trivial:
- Proposition (Reduced Picard Group of $\mathbb{P}^1$): If $C = \mathbb{P}^1$, then $\text{Pic}^0(C) = \text{Div}(C)/[\text{principal divisors}]$ is the trivial group, and $\text{Pic}(C) \cong \mathbb{Z}$.
 - Proof: The result is equivalent to showing that every divisor of degree 0 is principal, so suppose $D = \sum_P b_P P$ has degree 0.
 - For a point $P = [a : b] \in \mathbb{P}^1$ let f_P be the rational function $f_P = \frac{bX - aY}{Y}$, whose divisor is easily seen to be $\text{div}(f_P) = P - P_\infty$.
 - Now consider the rational function $\alpha = \prod_P f_P^{b_P}$: by the calculation above we have $\text{ord}_P(\alpha) = b_P$ for each point $P \neq \infty$, but since $\sum_P b_P \deg(P) = 0$ by the assumption on D , and $\deg(\text{div}(\alpha)) = 0$ as well, we must have $\text{ord}_\infty(\alpha) = b_\infty$ also.
 - Then $\text{ord}_P(\alpha) = b_P$ for all $P \in \mathbb{P}^1$, so $\text{div}(\alpha) = D$ and so D is principal as claimed.
 - The statement that $\text{Pic}(K) \cong \mathbb{Z}$ follows immediately from $\text{Div}(K)/\text{Div}^0(K) \cong \mathbb{Z}$.
 - Remark: It can be shown that the case $C = \mathbb{P}^1$ is essentially the only situation where the reduced Picard group is trivial. So do not be misled by the convenience of this particular result!
- We have a fundamental analogy between divisors on curves and ideals of algebraic number fields.
 - If $K/\mathbb{Q}$ is an algebraic number field, we have an exact sequence $1 \rightarrow [\text{units of } \mathcal{O}_K] \rightarrow K^\times \rightarrow [\text{fractional ideals of } \mathcal{O}_K] \rightarrow [\text{ideal class group of } K] \rightarrow 1$.
 - If C is an algebraic curve defined over k , the analogous exact sequence is $1 \rightarrow k^\times \rightarrow k(C)^\times \rightarrow \text{Div}^0(C) \rightarrow \text{Pic}^0(C) \rightarrow 1$.
 - The constant field k plays the role of the units of an algebraic number field, the group of degree-0 divisors plays the role of the fractional ideals in the ring of integers, and the reduced Picard group plays the role of the ideal class group.
- We now put a partial ordering on divisors that is motivated by the idea of divisibility for integers and rational functions.
 - The idea is that if we look at p -adic valuations of elements of $\mathbb{Q}$, we can identify the elements of $\mathbb{Z}$ as those whose valuations are nonnegative at every finite prime p .
 - The same principle holds for considering valuations of a rational function at points on an algebraic curve C : we can identify polynomial functions as those having no poles except at the points at ∞ .
- Definition: If a divisor $D = \sum_P n_P P$ on a curve C/k has $n_P \geq 0$ at all points P , we say D is effective and we write $D \geq 0$. We extend this notion to a partial ordering on divisors by writing $D_1 \leq D_2$ if and only if $D_2 - D_1$ is effective.

- Exercise (easy): Check that the relation $D_1 \leq D_2$ is a partial ordering on divisors.
- The partial ordering on divisors allows us to specify the order of zeroes and poles: to illustrate, for $\mathbb{A}^1$, saying that f has a pole of order at most 2 at $x = 0$ and a zero of order at least 3 at $x = 1$ is equivalent to saying $\text{div}(f) \geq 2P_0 - 3P_1$.

0.8 (Oct 5) The Riemann-Roch Theorem + Elliptic Curves (Properly)

- Definition: If D is a divisor on a curve C/k , the Riemann-Roch space associated to D is the set $L(D) = \{\alpha \in k(C)^\times : \text{div}(\alpha) \geq -D\} \cup \{0\}$. Equivalently, an element $\alpha \in k(C)^\times$ is in $L(D)$ if and only if $v_P(\alpha) \geq -v_P(D)$ at all points $P \in C$.
 - When D is an effective divisor, $L(D)$ represents all rational functions whose poles are “no worse” than D .
 - More generally, if $D = \sum_P n_P P - \sum_Q m_Q Q$ with $n_i, m_i > 0$, then $L(D)$ consists of all $\alpha \in k(C)^\times$ such that α has a zero of order at least m_Q at each point Q , and may have poles only at the points P , of order at most n_P at P .
 - It is not hard to see that $L(D)$ is a k -vector space: if $\alpha, \beta \in L(D)$, then $\alpha + \beta \in L(D)$ because $v_P(\alpha + \beta) \geq \min(v_P(\alpha), v_P(\beta))$ for each point P , and $c\alpha \in L(D)$ for all $c \in k$ since $v_P(c\alpha) = v_P(c) + v_P(\alpha) = v_P(\alpha)$ since $v_P(c) = 0$ at all points P .
 - Example: For $C = \mathbb{A}^1$ and $D = P_0$, we can see that $L(D) = \text{span}(1, x^{-1})$, since the only possible poles of an element $f/g \in L(D)$ function occur at $x = 0$ (of order 1) and the function must also have $\deg g \geq \deg f$ since there is no pole at the point at infinity P_∞ .
 - Example: For $C = \mathbb{A}^1$ and $D = 3P_\infty$, we can see that $L(D) = \text{span}(1, x, x^2, x^3)$ since the function f/g has no poles except a pole of order at most 3 at P_∞ (meaning that $\deg g \leq \deg f + 3$), which is to say, f/g is a polynomial of degree at most 3.
 - Example: For $C = \mathbb{A}^1$ and $D = -P_0$, we can see that $L(D) = \{0\}$, since any nonzero element $f/g \in L(D)$ would need to be zero at $x = 0$ and defined at all other points, but this cannot occur because g would have to be constant, but then $\deg f > \deg g$ would force f/g to have a pole at P_∞ .
 - Example: For arbitrary C/k , we have $L(0) = k$, since $\text{div}(c) = 0$ for all $c \in k^\times$, but any element $x \in k(C)^\times \setminus k$ necessarily has at least one pole (its degree as a rational function must be positive, and then any zero of the denominator yields a pole).
 - Exercise: Determine $L(D)$ when $C = \mathbb{A}^1(\mathbb{C})$ for $D = P_0 - P_\infty$, $P_0 + P_\infty$, and $P_0 + P_1$.
 - We can also consider Riemann-Roch spaces over non-algebraically-closed fields. The only alteration to considering $L_E(D)$ for some subfield E of its algebraic closure k is that $L_E(D) = \{\alpha \in E(C)^\times : \text{div}(\alpha) \geq -D\} \cup \{0\}$ consists only of the elements of the function field that are defined over E .
 - Example: For $C = \mathbb{A}^1$ and $D = P_\infty - P_i$, we have $L_{\mathbb{R}}(D) = \{0\}$ because any such rational function f/g would necessarily be a polynomial in $\mathbb{R}[x]$ of degree at most 1 (since it could only have a pole of order 1 at ∞) and would have to be zero at $x = i$, but any such polynomial would also be zero at $x = -i$ meaning that its degree is too large.
 - Example: For $C = \mathbb{A}^1$ and $D = 2P_\infty - P_i - P_{-i}$, we have $L_{\mathbb{R}}(D) = \text{span}(1 + x^2)$ because as above any element would be a real polynomial of degree at most 2 that is zero at both $x = i$ and $x = -i$, hence is a multiple of $1 + x^2$.
 - Note that the field of definition affects the dimension in the first example above but not the second, since over $\mathbb{C}$ we have $L_{\mathbb{C}}(P_\infty - P_i) = \text{span}(i - x)$ but $L_{\mathbb{C}}(2P_\infty - P_i - P_{-i}) = \text{span}(1 + x^2)$; that difference arises merely because the divisor D is actually defined over $\mathbb{R}$ while the divisor from the first example is not.
 - Exercise: Suppose E is a subfield of k and D is a divisor of k that is defined over E . Show that $\dim_k[L_k(D)] = \dim_E[L_E(D)]$. [Hint: Show that a basis for L_E remains a basis over L_k .]
- Definition: If D is a divisor on a curve C/k , we define $\ell(D) = \dim_k L(D)$.
 - Examples: By the examples worked out above, for $C = \mathbb{A}^1(\mathbb{C})$ we have $\ell(P_0) = 2$, $\ell(3P_\infty) = 4$, and $\ell(-P_0) = 0$.

- Example: For an arbitrary C , we have $\ell(0) = 1$, since $L(0) = k$.
- Proposition (Properties of $l(D)$): Let C be an algebraic curve over k and let D be a divisor of C .
 1. If $D_1 \leq D_2$, then $\ell(D_1) \leq \ell(D_2)$.
 - Proof: This follows immediately from the definition, since $D_1 \leq D_2$ clearly implies that $L(D_1)$ is a subspace of $L(D_2)$.
 2. If $D_1 \sim D_2$, then $L(D_1) \cong L(D_2)$ and so $\ell(D_1) = \ell(D_2)$.
 - Proof: If $D_1 = D_2 + \text{div}(g)$, then the map from $L(D_1)$ to $L(D_2)$ sending $f \mapsto fg$ is easily seen to be an isomorphism of vector spaces since it has an inverse map $h \mapsto h/g$.
 3. If $\deg(D) \leq 0$, then $L(D) = \{0\}$ and $l(D) = 0$ except when $D = \text{div}(\alpha)$ is principal, in which case $L(D) = \text{span}(\alpha)$ and $l(D) = 1$.
 - Proof: Suppose $f \in L(D)$ and $f \neq 0$. Then $0 = \deg(\text{div}(f)) \geq \deg(-D) = -\deg(D)$.
 - Furthermore, equality can hold only if $D = -\text{div}(f)$ for some $f \in k(C)^\times$, in which case D is principal.
 - If D is principal, then $\ell(D) = \ell(0) = 1$ by (2), and $L(D) = \text{span}(\alpha)$ by the same calculation.
 4. If D_1 and D_2 are divisors with $D_1 \leq D_2$, then $\dim_k(L(D_2)/L(D_1)) \leq \deg(D_2) - \deg(D_1)$.
 - Proof: Induct on the sum of the coefficients of the points in the effective divisor $B - A$. The base case $B - A = 0$ is trivial.
 - For the inductive step, suppose that $D_2 = D_1 + P$ for some point P , and choose $x \in k(C)$ such that $v_P(x) = v_P(D_2) = v_P(D_1) + 1$.
 - Then for any $y \in L(D_2)$, we have $v_P(xy) = v_P(x) + v_P(y) \geq v_P(D_2) - v_P(D_2) \geq 0$, so $xy \in \mathcal{O}_P$, the local ring at P .
 - By composing with the evaluation map at P , we obtain a k -linear transformation $\varphi : L(D_2) \rightarrow \mathcal{O}_P/m_P \cong k$ with $\varphi(y) = (xy)(P)$.
 - Then $y \in \ker(\varphi)$ if and only if $(xy)(P) = 0$ if and only if $v_P(xy) \geq 1$ if and only if $v_P(y) \geq 1 - v_P(D_2) = -v_P(D_1)$, and this last statement is equivalent to $y \in L(D_1)$.
 - Thus, by the first isomorphism theorem, we have an injection from $L(D_2)/L(D_1)$ to $\mathcal{O}_P/m_P$. Taking dimensions yields $\dim_k(L(D_2)/L(D_1)) \leq \dim_k(\mathcal{O}_P/m_P) = 1$.
 - This establishes the inductive step, so the general result follows.
 5. For any effective divisor D , we have $\ell(D) \leq \deg(D) + 1$. In fact, this inequality holds for any divisor D of degree ≥ 0 .
 - Proof: For effective divisors, this follows immediately by induction on the degree of D using (4), starting with the base case $l(0) = 1$.
 - For general divisors, the result is trivial if $\ell(D) = 0$, so suppose otherwise that $\ell(D) \geq 1$ and let $\alpha \in L(D)$ be nonzero. Then $\text{div}(\alpha) \geq -D$ which is equivalent to $D - \text{div}(\alpha^{-1}) \geq 0$.
 - Then for $D' = D - \text{div}(\alpha^{-1})$, we see that D is equivalent to the effective divisor D' , and so by (2) we have $\ell(D) = \ell(D') \leq \deg(D') + 1 = \deg(D) + 1$, as required.
 6. For any divisor D , the quantity $\ell(D)$ is finite.
 - Proof: If $\deg(D) < 0$ then (3) gives $\ell(D) = 0$, while if $\deg(D) \geq 0$ then (5) gives $\ell(D) \leq \deg(D) + 1$.
- What we would like to do now is to calculate the actual dimension $\ell(D)$ for arbitrary divisors D . Rather than delaying the point, we will now get right to our main result:
- Theorem (Riemann-Roch): For any algebraic curve C/k , there exists an integer $g \geq 0$ called the genus of C , and a divisor class $\mathcal{C}$, called the canonical class of C , such that for any divisor $C \in \mathcal{C}$ and any divisor $A \in \text{Div}(K)$, we have $\ell(A) = \deg(A) - g + 1 + \ell(C - A)$.
 - Remark: The divisor class $\mathcal{C}$, as we will explain later in our discussion of differentials, is the divisor class associated with the meromorphic differentials of C .
- Proving the general Riemann-Roch theorem would take us a bit too far of our way at the moment, so we will instead just derive some of its important consequences in our context.

- Later, when we are discussing elliptic curves over $\mathbb{C}$, we can outline the argument for Riemann-Roch for Riemann surfaces. It contains most of the main ideas but is more accessible since the complex-analytic notion of a differential is quite natural.
- For now, we will run through some consequences of the Riemann-Roch theorem.
- Proposition (Corollaries of Riemann-Roch): Let C/k be an algebraic curve.
 1. For any divisor A with $\deg(A) \geq 0$, we have $\deg(A) - g + 1 \leq \ell(A) \leq \deg(A) + 1$.
 - Proof: We showed the upper bound earlier using an inductive argument. The lower bound follows immediately from Riemann-Roch since $\ell(C - A) \geq 0$.
 2. For $C \in \mathcal{C}$ we have $\ell(C) = g$ and $\deg(C) = 2g - 2$.
 - Proof: First set $A = 0$ in Riemann-Roch: this yields $\ell(0) = \deg(0) - g + 1 + \ell(C)$, so since $\ell(0) = 1$ and $\deg(0) = 0$, we get $\ell(C) = g$.
 - Now set $A = C$ in Riemann-Roch: this yields $\ell(C) = \deg(C) - g + 1 + \ell(0)$, and so $\deg(C) = \ell(C) + g - 1 - \ell(0) = 2g - 2$.
 3. If $\deg(A) \geq 2g - 2$, then $\ell(A) = \deg(A) - g + 1$ except when $A \in \mathcal{C}$ (in which case $\ell(A) = g$).
 - Proof: If $\deg(A) \geq 2g - 2$, then $\deg(C - A) \leq 0$, and so $\ell(C - A) = 0$ except when $C - A$ is principal (i.e., when $A \in \mathcal{C}$).
 - When $\ell(C - A) = 0$ Riemann-Roch immediately gives $\ell(A) = \deg(A) - g + 1$, and when $A \in \mathcal{C}$ we have $\ell(A) = g$ by (2).
 4. The genus g is unique, as is the equivalence class $\mathcal{C}$.
 - Proof: Pick A of sufficiently large degree: then $\deg(A) - \ell(A) + 1 = g$ by (3), so g is uniquely determined.
 - For $\mathcal{C}$, if $\ell(A) = \deg(A) - g + 1 + \ell(C - A) = \deg(A) - g + 1 + \ell(D - A)$ for some other divisor D , then $\ell(C - A) = \ell(D - A)$ for all A .
 - Setting $A = C$ yields $\ell(D - C) = 1$ and setting $A = D$ yields $\ell(C - D) = 1$, and these are contradictory unless $D - C$ is principal, which is to say, $D \sim C$.
- Our main highlight is that we can use Riemann-Roch to study curves of small genus over an arbitrary field F with algebraic closure k . We start with the simplest genus $g = 0$, so suppose that C is a (smooth projective) curve of genus 0 over the field F , and let $K = F(C)$ be its function field.
 - By Riemann-Roch, we have $\ell(A) = \deg(A) + 1 + \ell(C - A)$ for any divisor A , and also $\deg(C) = -2$.
 - Also, by (3), if $\deg(A) \geq -1$ then $\ell(A) = \deg(A) + 1$. In particular, since $\deg(-C) = 2$, we have $\ell(-C) = 3$.
 - Now, for any point P , we have $\ell(P) \leq \deg(P) + 1$. So, if P is any point with $P \leq C$ (there must be at least one since $\deg(-C)$ is positive), we see $\ell(P) \leq \ell(-C) = 3$. Thus, $\deg(P)$ must be either 1 or 2.
 - First suppose that there is a point P of degree 1. Then $\ell(P) = 2$. Since F is a subspace of $L(P)$, there is a basis of $L(P)$ of the form $\{1, x\}$ for some $x \notin F$.
 - Then since $\deg(\operatorname{div}(x) + P) = 1$ and $\operatorname{div}(x) + P \geq 0$, we must have $\operatorname{div}(x) + P = Q$ for some point Q (necessarily of degree 1). Then $\operatorname{div}(x) = P - Q$, and so $[K : F(x)] = \deg(\operatorname{div}_+(x)) = \deg(P) = 1$, which means $K = F(x)$.
 - Now suppose there is no point P of degree 1: per earlier, we have a point $P \leq C$ of degree 2.
 - Then $\ell(P) = 3$, so again since $L(P)$ contains k , we may take a basis for $L(P)$ of the form $\{1, x, y\}$ for some F -linearly independent $x, y \notin F$.
 - In the same way as above, we see that $\operatorname{div}(x) = P - Q$ and $\operatorname{div}(y) = P - R$ for some (necessarily distinct) points Q and R of degree 2.
 - Then $[K : F(x)] = \deg(\operatorname{div}_+(x)) = 2$ and $[K : F(y)] = \deg(\operatorname{div}_+(y)) = 2$ also. Since $F(x) \neq F(y)$ (by linear independence and the fact that K is a degree-2 extension of both), we see $K = F(x, y)$.
 - Furthermore, Riemann-Roch says that $\ell(2P) = 1 + \deg(2P) = 5$, but we can find six different elements in $L(2P)$, namely $\{1, x, y, x^2, xy, y^2\}$. They must therefore be F -linearly dependent, so we see that x and y satisfy some quadratic relation $ax^2 + bxy + cy^2 + dx + ey = f$.

- Geometrically, this case corresponds to a conic, while the case $K = F(x)$ corresponds to a line (since we can think of $F(x) = F(x, y)$ where y is a linear function of x).
- We can use similar ideas to study curves of genus 1: now suppose that C is a curve of genus 1 over the field F , again with function field K .
 - In this case, for $g = 1$ Riemann-Roch and its corollaries say that $\ell(A) = \deg(A) + \ell(C - A)$, that $\deg(C) = 0$ and $\ell(C) = 1$, and that if $\deg(A) \geq 1$ then $\ell(A) = \deg(A)$.
 - Unlike the case $g = 0$, we are not necessarily guaranteed to have a point of any given degree any more, since we cannot use C to construct a point of small degree – indeed, since $\deg(C) = 0$ and $\ell(C) = 1$, in fact C is principal (and $C \sim 0$).
 - So let us instead merely suppose that we do have a point P of degree 1. Then $\ell(2P) = 2$, so choose a basis $\{1, x\}$ for $L(2P)$, where we necessarily must have $v_P(x) = 2$ since $x \notin L(P)$. Then $\ell(3P) = 3$, so choose a basis $\{1, x, y\}$ for $L(3P)$, where we must necessarily have $v_P(y) = 3$ since $y \notin L(2P)$.
 - Then, as above, $[K : F(x)] = \deg(\text{div}_+(x)) = 2$ and $[K : F(y)] = \deg(\text{div}_+(y)) = 3$, so since 2 and 3 are relatively prime, we see $K = F(x, y)$.
 - Now we would like to identify what kind of algebraic relation x, y must satisfy (they are, after all, algebraically dependent), which we can do by looking at the spaces $L(kP)$ for larger values of k , since the various monomials $x^i y^j$ will all only have poles at P .
 - We have $\ell(4P) = 4$, but we can only identify 4 elements that must lie in this space: $\{1, x, y, x^2\}$. In fact, they are all linearly independent since they all have different valuations at P .
 - Likewise, $\ell(5P) = 5$, but we only have 5 elements in this space: $\{1, x, y, x^2, xy\}$. Again, these elements are all linearly independent since they have different valuations at P .
 - However, $\ell(6P) = 6$, and we can generate 7 elements in this space: $\{1, x, y, x^2, xy, x^3, y^2\}$. We must therefore have a linear dependence among these elements, and in fact since x^3 and y^2 are the only elements with valuation 6 at P , they must both occur with nonzero coefficients.
 - By rescaling x, y appropriately, we obtain an algebraic relation of the form $y^2 + a_1 xy + a_3 y = x^3 + a_2 x^2 + a_4 x + a_6$ for some $a_1, a_2, a_3, a_4, a_6 \in E$: in other words, C has an equation in Weierstrass form. (Additionally, this also explains where the indices on the coefficients a_i come from: they are giving the “missing” pole valuation at P for the corresponding monomial term.)
 - To make this more precise, we observe that the map $\varphi : C \rightarrow \mathbb{P}^2$ defined by $[x : y : 1]$ is a rational map (by definition, because x, y are elements of the function field of C) whose image is a subvariety of the curve $V(Y^2 Z + a_1 X Y Z + a_3 Y Z^2 - X^3 - a_2 X^2 Z - a_4 X Z^2 - a_6 Z^3)$. Thus φ is a morphism, and since it is nonconstant it is surjective.
 - But also, since the function field $F(x, y)$ equals the function field K of the curve, φ has degree 1, so φ is an in fact an isomorphism. Thus, C is isomorphic to a projective curve with a Weierstrass equation, as claimed.
- We therefore see that a curve with genus 1 over F having a point of degree 1 is an elliptic curve in Weierstrass form. We now adopt this as our more highbrow definition of an elliptic curve:
- Definition: Let F be a field. An elliptic curve E over F is a smooth projective curve defined over F with genus 1 that has an F -rational point O .
 - The specific choice of F -rational point O is part of the definition of an elliptic curve: if we take the same projective curve but choose different selections for O , we view the resulting elliptic curves as distinct. (As we will see, however, they will be isomorphic, so the distinction is not of great importance.)
- Now we can establish the existence of the group law on an elliptic curve.
 - In the discussion below, we will denote the divisor of a point P by $[P]$, since we will need to keep separate the notion of P as a divisor and as a point on a curve.
- Theorem (Group Law): Let F be a field and E be an elliptic curve defined over F with an F -rational point O . Then the following hold:

1. If P and Q are F -rational points such that $[P] \sim [Q]$ as divisors, then $P = Q$.
 - Proof: Suppose that $[P] \sim [Q]$, so that $[P] - [Q] = \text{div}(f)$ for some f .
 - Then in particular, $f \in L([Q])$: but Riemann-Roch on E says that $l([Q]) = 1$, so since the constants all lie in $L([Q])$, f must be constant. Then $\text{div}(f) = 0$ and hence $P = Q$, as claimed.
 2. For every degree-zero divisor D , there exists a unique point $P \in E$ such that $D \sim [P] - [O]$.
 - Proof: To see that such a P exists, since $\deg(D + [O]) = 1$, our consequences of Riemann-Roch imply that $l(D + [O]) = 1$.
 - Let f span $L(D + [O])$: then $\text{div}(f) \geq -D - [O]$ and $\deg(\text{div}(f)) = 0$, so since $-D - [O]$ has degree -1 we must have $\text{div}(f) = -D - [O] + [P]$ for some degree-1 point P , whence $D \sim [P] - [O]$.
 - Uniqueness of Q then follows immediately from (1), since if $[P] - [O] \sim D \sim [Q] - [O]$ then $P = Q$.
 3. If $\sigma : \text{Div}^0(E) \rightarrow E$ denotes the map in (2), then σ induces a bijection $\tilde{\sigma} : \text{Pic}^0(E) \rightarrow E$.
 - Proof: First observe that $\sigma([P] - [O]) = P$ so σ is certainly surjective from $\text{Div}^0(E)$ to E .
 - Also, by the definition of σ for any divisors D_1 and D_2 we have $\sigma(D_1) - \sigma(D_2) \sim D_1 - D_2$, so $D_1 \sim D_2$ if and only if $\sigma(D_1) = \sigma(D_2)$, which shows that σ descends to a bijection $\tilde{\sigma}$ from $\text{Pic}^0(E)$ to E .
 4. With $\tilde{\sigma}$ as in (3), the group operation on E induced from $\text{Pic}^0(E)$ via $\tilde{\sigma}$ is the same as the geometric group law on E . (In other words, if we think of E as a group with the geometric law, then E is isomorphic to $\text{Pic}^0(E)$ via $\tilde{\sigma}$.)
 - Proof: The inverse map of $\tilde{\sigma}$ is $\tau : P \rightarrow [P] - [O]$. We want to see that $\tau(P+Q) = \tau(P) + \tau(Q)$, where the addition on the left is the geometric group law, and the addition on the right is the addition of divisor classes in the Picard group.
 - Equivalently, we want to see that $[P+Q] - [P] - [Q] + [O] \sim 0$, where again $P+Q$ represents addition via the geometric group law.
 - Let f be the line through P and Q , let R be the third intersection point of E with this line, and let g be the line through R and O . Then since the line $Z = 0$ intersects E at O with multiplicity 3, we have $\text{div}(f/Z) = [P] + [Q] + [R] - 3[O]$ and $\text{div}(g/Z) = [R] + [P+Q] - 2[O]$.
 - Therefore, $[P+Q] - [P] - [Q] + [O] = \text{div}(f/g) \sim 0$, as required. This means τ is a group homomorphism and thus a group isomorphism, as desired.
 5. The group law defines morphisms $+: E \times E \rightarrow E$ mapping $(P, Q) \mapsto P + Q$ and $-: E \rightarrow E$ mapping $P \mapsto -P$.
 - Proof: It is enough to show that the maps are rational, since rational maps from a smooth curve to a variety are morphisms. But the addition map and the additive-inverse maps are both rational as we have already seen via the explicit formulas: the only possible exceptions involve adding a point to itself or a point to O . One may check explicitly in these cases that the maps still yield morphisms.
 6. For any divisor $D \in \text{Div}(E)$, D is principal if and only if $\deg(D) = 0$ and the formal sum representing D evaluates to O when viewed as a sum of points using the group law.
 - Proof: As we have previously noted, the degree of any principal divisor is 0, so certainly we must have $\deg(D) = 0$.
 - Now if $D \in \text{Div}^0(E)$ is $D = \sum_P n_P [P]$ we have $D \sim 0$ if and only if $\sigma(D) = O$. But $\sigma(D) = \sigma(\sum_P n_P [P]) = \sum_P n_P \sigma([P]) = \sum_P n_P (P - O) = \sum_P n_P P$ by definition of σ and the equivalence of the group operations in (4). So we see $\sigma(D) = O$ if and only if $\sum_P n_P P = O$ when viewed as a sum of points using the group law.
- Exercise: Show that we have an exact sequence $1 \rightarrow k^* \rightarrow k(E)^* \xrightarrow{\text{div}} \text{Div}^0(E) \xrightarrow{(6)} E \rightarrow 0$ where div represents the divisor map $f \mapsto \text{div}(f)$ and (6) represents the map discussed in (6) that takes a divisor $\sum_P n_P [P]$ and evaluates it as a sum of points on E .

0.9 (Oct 8) Differentials on Curves

- We would now like to establish the converse of our theorem above: namely, that every smooth projective curve with a Weierstrass equation $Y^2Z + a_1XYZ + a_3YZ^2 = X^3 + a_2X^2Z + a_4XZ^2 + a_6Z^3$ is actually an elliptic curve.

- Since $[0 : 1 : 0]$ (the affine point at ∞) is always a rational point on this curve, we need only show it has genus 1.
- In order to do this, we need to discuss differentials, since they allow us to calculate the genus.
- **Definition:** Let C/k be a (smooth projective) curve. The space $\Omega(C)$ of meromorphic differential 1-forms on C is the k -vector space consisting of symbols of the form dx for $x \in k(C)$, subject to the following three relations:
 1. The additivity relation $d(x + y) = dx + dy$ for all $x, y \in k(C)$.
 2. The Leibniz rule $d(xy) = x dy + y dx$ for all $x, y \in k(C)$.
 3. Derivatives of constants are zero: $da = 0$ for all $a \in k$.
- We remark also that there is a more general notion of differential form defined using the notion of a derivation from a commutative ring R to an R -module M . (We will not need this added formalism, but we include the definition purely for reference.)
 - * A derivation is an additive map $D : R \rightarrow M$ such that $D(ab) = aD(b) + bD(a)$ for all $a, b \in R$.
 - * If B is a k -algebra, we say D is a k -derivation if k is contained in the kernel of D (i.e., D vanishes on k).
 - * Then the module of relative differential forms of B over k is a B -module $\Omega_{B/A}$ together with a k -derivation $d : B \rightarrow \Omega_{B/A}$ such that for any other B -module M and any k -derivation $d' : B \rightarrow M$ there exists a unique B -module homomorphism $f : \Omega_{B/A} \rightarrow M$ such that $d' = f \circ d$.
- Although the space $\Omega(C)$ contains differentials of the form df for all $f \in k(C)$, and may therefore appear to be very large, in fact the relations impose all of the familiar rules of calculus.
- Exercise: Show that the relations (1)-(3) also imply the power rule $d(x^n) = nx^{n-1}dx$ and the quotient rule $d(\frac{x}{y}) = \frac{x dy - y dx}{y^2}$.
- Exercise: Suppose C/k is a curve and $x_1, x_2, \dots, x_n \in k(C)$. For any rational function $f \in k(x_1, \dots, x_n)$, show the “chain rule”: that $df = f_{x_1} dx_1 + \dots + f_{x_n} dx_n$, where f_{x_i} denotes the usual partial derivative. [Hint: First show the result for polynomials f , then use the quotient rule.]
- As a corollary of the above exercises, we see immediately that if the function field $k(C)$ is generated (as a field extension) by $x_1, \dots, x_n$ then $\Omega(C)$ is spanned by $dx_1, dx_2, \dots, dx_n$ as a $k(C)$ -vector space.
- Example: For $C = \mathbb{P}^1$, we have $k(C) = k(x)$ for $x = X/Y$. Since x generates the function field by itself we see that $\Omega(C)$ is spanned by dx . In fact, $\{dx\}$ is a basis, since there are no additional relations arising in the definition of $\Omega(C)$.
- Example: Let p be a prime. For $C = \mathbb{P}^1$ over a field of characteristic not equal to p , by the above we know that $\{dx\}$ is a basis of $\Omega(C)$. Then for $f = x^p$, since $df = px^{p-1}dx$ is a nonzero scalar multiple of dx , we see that $\{df\}$ is also a basis of $\Omega(C)$. On the other hand, over a field of characteristic p , we have $df = px^{p-1}dx = 0$, and so $\{df\}$ is not a basis of $\Omega(C)$.
- Example: For $C = V(Y^2Z - X^3 - XZ^2)$ with $x = X/Z$ and $y = Y/Z$, we have $k(C) = k(x, y)$. By the exercises above we see that $\Omega(C)$ is spanned by dx and dy , but since $y^2 = x^3 + x$ taking differentials yields a linear dependence $2y dy = (3x^2 + 1) dx$. Thus in fact either dx or dy suffices to span $\Omega(C)$. As with $\mathbb{P}^1$, there is no relation imposed on a single differential by itself, so $\{dx\}$ or $\{dy\}$ is a basis for $\Omega(C)$.
- More generally, one may show similarly that $\Omega(C)$ is always a 1-dimensional $k(C)$ -vector space for any curve C : in general, dx generates $\Omega(C)$ if and only if $k(C)/k(x)$ is a separable extension of finite degree. (The second example above shows that separability is necessary, since if k has characteristic p then $k(x)/k(x^p)$ is not separable, and as noted above in that situation dx^p does not span $\Omega(C)$.)
- Our goal now is to show that we may do calculations with differentials that mirror those for rational functions. First, we will give a well-defined notion of the order of a differential ω at a point P , and then we use it to attach a divisor to a differential.
- **Proposition (Properties of Differentials):** Let C/k be a curve, let ω be a differential in $\Omega(C)$, and let P be a point of C with a local uniformizer t . Then the following hold:

1. There exists a unique rational function $f \in k(C)$ such that $\omega = f dt$. (Since f is unique, we may think of it as the “quotient” ω/dt .)
 - Proof: First, since t is a local uniformizer, the extension $k(C)/k(t)$ has finite degree and is separable. Hence by the discussion above, we see that $\{dt\}$ spans $\Omega(C)$ as a $k(C)$ -vector space.
 - This means so there exists a unique rational function $f \in k(C)$ such that $\omega = f dt$.
2. If $f \in k(C)$ is defined at P , then df/dt is also defined at P .
 - The most direct proof of this fact follows by working with local Laurent expansions at P . While this is an extremely useful technique in general, we will mostly avoid actually doing it in practice since it tends to yield unenlightening proofs.
 - That fact notwithstanding, here is an outline: given a rational function $\alpha \in k(C)^\times$ and a point $P \in C$, we can express α as a Laurent series with coefficients in the residue field $\mathcal{O}_P(C)/m_P(C) \cong k$ with respect to a fixed uniformizer t generating $m_P(C)$.
 - For simplicity first suppose that $v_P(\alpha) \geq 0$: then $\alpha \in \mathcal{O}_P(C)$ is defined at P . Let $\varphi : \mathcal{O}_P(C) \rightarrow \mathcal{O}_P(C)/m_P(C)$ be the projection map: then by definition the value of α at P is $\varphi(\alpha) = a_0$; then $\alpha - a_0 \in m_P(C)$ so $\alpha = a_0 + b_1 t$ for an element $b_1 \in \mathcal{O}_P(C)$.
 - Now let $\varphi(b_1) = a_1$, so $b_1 - a_1 \in m_P(C)$ and thus $b_1 = a_1 + b_2 t$ for some $b_2 \in R$: now $\alpha = a_0 + a_1 t + b_2 t^2$. We may clearly continue this process indefinitely to generate a power series expansion $\alpha = a_0 + a_1 t + a_2 t^2 + \dots$.
 - Exercise: Show that the power series expansion method yields an injective ring homomorphism of the metric space $\mathcal{O}_P(C)$ (under the metric induced by the discrete valuation v_P) into the formal power series ring $k[[t]]$ (under the metric induced by the order valuation v_t , giving the lowest-degree term with a nonzero coefficient).
 - For arbitrary rational $\alpha \in k(C)^\times$ with $v_P(\alpha) = d$ we may apply this method to obtain a power series expansion for $t^{-d}\alpha$, and then scale by t^d to obtain a Laurent expansion in t . It is then not hard to check that the resulting map $D : k(C) \rightarrow k((t))$ is a derivation.
 - Finally, given any $f \in \mathcal{O}_P(C)$, the term-by-term power series derivative f' yields a rational function with $df = f' dt$. Since the term-by-term derivative f' lies in $k[[t]]$, it is also defined at P .
3. If t' is another local uniformizer at P , then $\text{ord}_P(\omega/dt) = \text{ord}_P(\omega/dt')$. We may therefore define $\text{ord}_P(\omega)$ to be the value $\text{ord}_P(\omega/dt)$ for *any* local uniformizer t .
 - Proof: Taking $f = t'$ in (2) shows that $dt'/dt = g$ is defined at P , and interchanging t and t' shows that $dt'/dt = 1/g$ is also defined at P . Therefore, we have $\text{ord}_P(g) \geq 0$ and $\text{ord}_P(1/g) \geq 0$ whence $\text{ord}_P(g) = 0$.
 - Then we immediately have $\text{ord}_P(\omega/dt) = \text{ord}_P(\omega/dt' \cdot dt'/dt) = \text{ord}_P(\omega/dt') + \text{ord}_P(g) = \text{ord}_P(\omega/dt')$.
4. Let $x \in k(C)^\times$ with $x(P) = 0$. Then $\text{ord}_P(dx) = \text{ord}_P(x) - 1$ except when the characteristic of k divides $\text{ord}_P(x)$, in which case we have $\text{ord}_P(dx) \geq \text{ord}_P(x)$.
 - Intuitively, the idea of this result is the extremely reasonable notion that taking the derivative of a function lowers its order of vanishing by 1, except in situations where the function is something times a p th power in characteristic p .
 - Proof: Since x is not zero we may write $x = ut^n$ for some u of order 0, and $n = \text{ord}_P(x)$. Then $dx = unt^{n-1} dt + (du/dt)t^n dt$ by the chain rule.
 - From (2) we know that du/dt is defined at P so $\text{ord}_P(du/dt) \geq 0$.
 - If the characteristic of k divides n , then $n = 0$ (in k), so $dx = (du/dt)t^n dt$. Then $\text{ord}_P(dx) = \text{ord}_P(du/dt) + n \geq \text{ord}_P(x)$ as desired.
 - Otherwise, if the characteristic does not divide n , then $n \neq 0$ in k so $\text{ord}_P(unt^{n-1}) = n - 1$ while the order of the second term $(du/dt)t^n$ is at least n (as just calculated above). So since ord_P is a discrete valuation, the order of the sum $unt^{n-1} + (du/dt)t^n$ is $n - 1 = \text{ord}_P(x) - 1$, as desired.
5. For all but finitely many P , we have $\text{ord}_P(\omega) = 0$.
 - Proof: Pick x to be a local uniformizer at an arbitrary point of C : then by (1) we may write $\omega = f dx$.
 - Now, f has finitely many zeroes and poles, as noted in our discussion of divisors of functions. Additionally, as we will discuss in more detail later, there are only finitely many points at which $x - x(P)$ fails to be a local uniformizer at P . (These are the points at which x is ramified, when thought of as a map $x : C \rightarrow \mathbb{P}^1$.)

- So there are only finitely many points P where f has a zero or pole, or where $x - x(P)$ fails to be a local uniformizer.
 - Let Q be any other point. Then $x - x(Q)$ is a local uniformizer, so we have $\text{ord}_Q(dx) = \text{ord}_Q(d(x - x(Q))) = 1 - 1 = 0$ by (4).
 - Hence $\text{ord}_Q(\omega) = \text{ord}_Q(f dx) = \text{ord}_Q(f) + \text{ord}_Q(dx) = 0 + 0 = 0$ because f is defined and does not vanish at Q . This applies for all but finitely many points Q , so we are done.
6. For any differential ω , its divisor $\text{div}(\omega) = \sum_P \text{ord}_P(\omega) P$ is well defined, and for any other differential ω_1 we have $\text{div}(\omega) \sim \text{div}(\omega_1)$. We define the canonical class $\mathcal{C}$ to be the resulting divisor class of $\text{div}(\omega)$ in $\text{Pic}(C)$.
- Proof: Well-definedness follows immediately from (5), since only finitely many terms in the formal sum are nonzero.
 - Now suppose ω_1 is any other differential. By (1) there exists $f \in k(C)$ such that $\omega/\omega_1 = f$: thus $\text{div}(\omega) - \text{div}(\omega_1) = \text{div}(f)$ which means by definition that $\text{div}(\omega) \sim \text{div}(\omega_1)$.
 - The well-definedness of the canonical class is then immediate from the equivalence.
7. A differential ω is holomorphic if $\text{div}(\omega) \geq 0$: equivalently, when $\text{ord}_P(\omega) \geq 0$ for all P , which is to say, when ω has no poles. The holomorphic differentials form a finite-dimensional vector space, whose dimension is defined to be g , the genus of C .
- For completeness, we also say that a differential ω is nonvanishing if $\text{div}(\omega) \leq 0$: equivalently, when $\text{ord}_P \leq 0$ for all P , which is to say, when ω has no zeroes.
 - Proof: Writing $\omega = f dt$ we see that ω is holomorphic if and only if $\text{div}(f) \geq -\text{div}(\omega)$. Therefore, the map $\omega \mapsto \omega/dt$ is an isomorphism of the space of holomorphic differentials with the Riemann-Roch space $L(\text{div}(\omega))$, whose dimension $l(\text{div}(\omega)) = l(\mathcal{C})$ is finite, as follows from our properties of Riemann-Roch spaces.
- Of course, the real point of (6) and (7) is to give a proper definition of the canonical class and the genus of a curve that appear in the statement of the Riemann-Roch theorem.
 - We can also give some explanation of why the genus g , defined here as the dimension of the space of holomorphic differentials C , corresponds to the topological genus.
 - The idea is that when we are working over $k = \mathbb{C}$, then viewing C as a (compact, connected) Riemann surface, we may integrate a holomorphic differential along a path inside C .
 - By standard results from complex analysis, if two paths are homotopic then integrating any differential along the two paths yields the same value. Since the set of paths up to homotopy is the first homology group $H_1(C)$, which is a free abelian group of rank g (the topological genus of C), we obtain a pairing between $H_1(C)$ and the space of holomorphic differentials given by $\langle C, \omega \rangle = \int_C \omega$.
 - One then shows that this is a perfect pairing, and so these vector spaces are isomorphic. (Essentially, the idea is that we can obtain independent holomorphic differentials by integrating around independent non-contractible paths on C .)
 - We remark that all of this is just a rephrasing of Poincaré duality applied to the de Rham cohomology groups of C , considered as a 2-dimensional manifold.
 - Example: On $C = \mathbb{P}^1$ with $x = X/Y$ as usual, find $\text{div}(dx)$ and then show that there are no nonzero holomorphic differentials.
 - First, since $k(C) = k(x)$, so rather trivially $k(C)/k(x)$ is separable and of finite degree, we see that $\Omega(C)$ is spanned by dx . Thus every differential on C is of the form $\omega = f dx$ for some rational function $f \in k(x)$, in which case $\text{div}(\omega) = \text{div}(f) + \text{div}(dx)$.
 - To find $\text{div}(dx)$, first observe that for all $c \in k$ the function $x - c$ is a uniformizer at $[c : 1]$, so $\text{ord}_{[c:1]}(dx) = \text{ord}_{[c:1]}(x - c) - 1 = 0$ by our results in (4).
 - Also, at the point at infinity $[1 : 0]$, the function $1/x$ is a uniformizer, so $\text{ord}_{[1:0]}(x) = -1$ and thus $\text{ord}_{[1:0]}(dx) = \text{ord}_{[1:0]}(x) - 1 = -2$, again by (4).
 - Therefore, $\text{div}(dx) = -2P_{[1:0]}$. We conclude that the canonical class is the image of $-2P_{[1:0]}$ in $\text{Pic}(C)$.

- In particular, the degree of any differential must be -2 . But since the degree of a holomorphic differential is nonnegative, we see immediately that there are no nonzero holomorphic differentials.
- Hence we see that the genus of $\mathbb{P}^1$ is 0 – as it should be, of course, given the results of our earlier calculations for genus-0 curves using Riemann-Roch.
- Example: On $C = V(Y^2Z - X^3 - XZ^2)$ with $x = X/Z$ and $y = Y/Z$ as usual, show that dx/y is a nonvanishing holomorphic differential, when the characteristic of k is not 2.
 - We have previously shown that $\text{div}(y) = P_{[0:0:1]} + P_{[i:0:1]} + P_{[-i:0:1]} - 3P_{[0:1:0]}$ on this elliptic curve.
 - To find $\text{div}(dx)$ we first compute $\text{div}(x)$: since x is only zero at $[0 : 0 : 1]$ and since y is a local uniformizer there, to check the zero order we observe that $x/y^2 = XZ/Y^2 = Z^2/(X^2 + Z^2) = 1$ is defined and nonzero, so $\text{ord}_{[0:0:1]} x = 2$. Then since the only pole of x is at $[0 : 1 : 0]$ the pole also has order 2, and so $\text{div}(x) = 2P_{[0:0:1]} - 2P_{[0:1:0]}$.
 - In the same way we can show that $\text{div}(x - i) = 2P_{[i:0:1]} - 2P_{[0:1:0]}$ and $\text{div}(x + i) = 2P_{[-i:0:1]} - 2P_{[0:1:0]}$.
 - Then since $x - x(P)$ is only zero at $x = 0, i, -i$, by property (4) we deduce that the zeroes of dx occur only at $[0 : 0 : 1]$, $[-i : 0 : 1]$, and $[i : 0 : 1]$ and the zero order there is $2 - 1 = 1$ in each case.
 - Likewise, since the only pole of dx is at $[0 : 1 : 0]$, by (4) again we see the pole order is $-2 - 1 = -3$. (Here is where we need the fact that the characteristic is not 2.)
 - Putting all of this together shows that $\text{div}(dx) = P_{[0:0:1]} + P_{[i:0:1]} + P_{[-i:0:1]} - 3P_{[0:1:0]}$. But this is precisely $\text{div}(y)$, and so that means $\text{div}(dx/y) = 0$ whence dx/y is holomorphic and also nonvanishing.
- Let us now generalize the example above to complete the proof that smooth projective curves of genus 1 having a rational point (per our highbrow definition of elliptic curves) are the same as nonsingular cubic curves in Weierstrass form (per our original definition):
- Proposition (Differentials on Elliptic Curves): Let C/k be a smooth projective curve having an affine Weierstrass equation of the form $y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6$. Then the following hold:
 1. The differential $\omega = \frac{dx}{2y + a_1x + a_3} = -\frac{dy}{3x^2 + 2a_2x + a_4 - a_1y}$ is holomorphic and nonvanishing on C .
 - Proof: Let $f = y^2 + a_1xy + a_3y - (x^3 + a_2x^2 + a_4x + a_6)$: then by the chain rule we see that $\frac{dx}{f_y(x,y)} = -\frac{dy}{f_x(x,y)}$, showing that the two expressions are equal.
 - For any finite point $P = (x_0, y_0)$ we also have $\omega = \frac{d(x - x_0)}{f_y(x, y)} = -\frac{d(y - y_0)}{f_x(x, y)}$ since translating by a constant does not affect differentials.
 - In particular we see that P cannot be a pole of ω since this would require $f_x(P) = f_y(P) = 0$, but that cannot occur because C is smooth at P . So ω could only possibly have a pole at ∞ .
 - For zeroes of ω we observe that the map $\varphi : C \rightarrow \mathbb{P}^1$ with $[X : Y : Z] \mapsto [X : Z]$ has degree 2, so $\text{ord}_P(x - x_0) \leq 2$ with equality if and only if $f(x_0, y)$ has a double root in y at $y = y_0$, which occurs if and only if $f_y(x_0, y_0) = 0$.
 - Therefore by property (4) we see that $\text{ord}_P(\omega) = \text{ord}_P(dx) - \text{ord}_P(f_y) = \text{ord}_P(x - x_0) - \text{ord}_P(f_y) - 1 = 0$ in both the situation when $\text{ord}_P(x - x_0) = 1$ and in the situation when $\text{ord}_P(x - x_0) = 2$.
 - It remains to check the order at ∞ . For this let t be a uniformizer: then because $\text{ord}_\infty(x) = -2$ and $\text{ord}_\infty(y) = -3$ we have $x = t^{-2}u$ and $y = t^{-3}w$ for some $u, w \in k(C)$ that are defined and nonzero at ∞ .
 - Then $\omega = \frac{dx}{f_y(x, y)} = \frac{-2t^{-3}u + t^{-2}(du/dt)}{2t^{-3}w + a_1t^{-2}u + a_3} dt = \frac{-2u + t(du/dt)}{2w + a_1tu + a_3t^3} dt$.
 - When the characteristic of k is not equal to 2, we can then evaluate the function $\frac{-2u + t(du/dt)}{2w + a_1tu + a_3t^3}$ at ∞ (note that $t = 0$ at ∞) to obtain $\frac{-u(\infty)}{w(\infty)}$ which is defined and nonzero.
 - Exercise: When the characteristic of k is not equal to 3, show that the equivalent formula $\omega = -\frac{dy}{f_x(x, y)}$ evaluates to a quantity that is defined and nonzero at ∞ .

- This means $\text{ord}_\infty(\omega) = 0$ as well, so $\text{div}(\omega) = 0$ whence ω is holomorphic and nonvanishing as claimed.
- 2. The space of holomorphic differentials on C is a 1-dimensional k -vector space, whence C has genus 1.
 - Proof: As shown in (1) above, there exists a holomorphic differential ω such that $\text{div}(\omega) = 0$.
 - From our properties of differentials, any other differential ζ is of the form $f\omega$ for some $f \in k(C)$.
 - But then $\text{div}(\zeta) = \text{div}(f) + \text{div}(\omega) = \text{div}(f)$, so in order for ζ to be holomorphic we must have $\text{div}(f) \geq 0$, meaning that f is a rational function with no poles.
 - But the only such (projective) functions are constants, whence ζ is a k -scalar multiple of ω .
 - This immediately implies that the space of holomorphic differentials on C is a 1-dimensional k -vector space, so C has genus 1 as claimed.
- 3. Every smooth projective genus-1 curve has a nonsingular Weierstrass equation, and conversely every nonsingular Weierstrass equation gives a smooth projective genus-1 curve.
 - Proof: We showed the first part earlier using Riemann-Roch, while the second part is simply (2).
- 4. The differential ω from (1) is translation-invariant, meaning that for any point Q on E , if $(x, y) + Q = (\tilde{x}, \tilde{y})$, then $\omega = \frac{d\tilde{x}}{2\tilde{y} + a_1\tilde{x} + a_3}$ as well. We therefore call ω the invariant differential of E .
 - We could in principle show this result just using the point addition formulas, since they give explicit expressions for $\tilde{x}$ and $\tilde{y}$ in terms of x, y , and the coordinates of Q . We will give a less tedious argument.
 - Proof: Let $\tilde{\omega} = \frac{d\tilde{x}}{2\tilde{y} + a_1\tilde{x} + a_3}$. Since $\tilde{\omega}$ is obtained by adding Q to all points on C , for any P on C we see that $\text{ord}_P(\tilde{\omega}) = \text{ord}_{P-Q}(\omega) = 0$, and so $\tilde{\omega}$ is also a nonvanishing holomorphic differential.
 - By (2) since the space of holomorphic differentials is 1-dimensional, that means $\tilde{\omega} = c_Q\omega$ for some scalar $c_Q \in k$ that (a priori) depends on Q .
 - Now consider the map $\varphi : E \rightarrow \mathbb{P}^1$ sending $Q \mapsto [c_Q : 1]$ for each point Q .
 - This map is necessarily rational (since after all the expressions for $\tilde{x}$ and $\tilde{y}$ are rational functions, so the ratio $\tilde{\omega}/\omega$ is some rational function), but it clearly omits $[1 : 0]$ since c_Q is defined for all Q .
 - Thus φ is not surjective, so it must be constant since nonconstant rational maps of curves are surjective. Finally, setting Q to be the identity O on E shows $\tilde{\omega}_O = \omega$, so the constant must be 1.
 - We conclude that $\tilde{\omega} = \omega$ for all Q .

0.10 (Oct 15) HW1 Presentations + Riemann-Roch Outline

- To finish this portion of the discussion, we outline the proof of the Riemann-Roch theorem.
 - The main additional definition required is the residue of a rational function $f \in k(C)$ at a point P , which is the general analogue of the residue of a meromorphic function at a point in $\mathbb{C}$. There are various ways to give this definition, but the standard approach is as the coefficient a_{-1} in a local Laurent expansion $f = \sum_{n=-k}^{\infty} a_n t^n$ where t is a local uniformizer. (Nontrivial work is required to make this rigorous, since uniformizers are only unique up to units in $\mathcal{O}_P(C)$, but the idea is that $dt/t = dt'/t'$ for any two uniformizers t and t' .)
 - The residue of a rational function is only nonzero when the function has a pole at P . By the analogue of Cauchy's residue theorem (or Stokes's theorem, depending on one's interpretation), one may also show that the sum of the residues of any rational function over all its poles is zero.
 - If we have an effective divisor $D = P_1 + P_2 + \cdots + P_d$ for distinct points P_i , we obtain a map $\varphi : L(D) \rightarrow k^d$ by taking $\varphi(D) = (\text{Res}_{P_1} f, \text{Res}_{P_2} f, \dots, \text{Res}_{P_d} f)$. The kernel of this map is the set of functions $g \in L(D)$ whose residue is zero at each P_i , which includes all constant functions.
 - Thus, we obtain an exact sequence $0 \rightarrow k \rightarrow L(D) \xrightarrow{\varphi} k^d$.
- Now we ask the question: how close is the map φ to being surjective? In other words, what conditions are there on the values of the residues of a function in $L(D)$ at the points P_i ?

- We can answer this question by looking at the residues of holomorphic and meromorphic differentials.
- If ω is holomorphic, we define the residue of ω at P as the residue of the ratio ω/dt at P where dt is a local uniformizer at P .
- **Definition:** Let D be a divisor on C . Define $\Omega(D)$ to be the space of differentials ζ such that $\text{div}(\zeta) \geq D$.
 - Observe in particular that $\Omega(0)$ is the space of holomorphic differentials, hence has dimension g by definition of the genus.
 - **Exercise:** Show $\Omega(D)$ is a vector space, and that $\Omega(D)$ is isomorphic to $L(C-D)$ where C is any element of the canonical class of C . [Hint: Fix a differential ω , let $f \in L(C-D)$, and consider $f \mapsto f\omega$, remembering the minus sign in the definition of the Riemann-Roch space $L(C-D)$!]
 - In the same way as for functions, the sum of the residues of any meromorphic differential over all points must be zero: thus, for each holomorphic ω and each $f \in L(D)$, we see that the sum of the residues of $f\omega$ must be zero. This means each differential imposes a linear condition on the possible choices of residues for f .
 - More precisely, we obtain a map $\psi : \Omega(D) \rightarrow k^d$ by taking $\psi(D) = (\text{Res}_{P_1}\omega, \text{Res}_{P_2}\omega, \dots, \text{Res}_{P_d}\omega)$. The kernel of this map is the set of differentials $\omega \in \Omega(D)$ whose residue is zero at each P_i , which includes all of the holomorphic differentials.
 - Thus, we obtain another exact sequence $0 \rightarrow \Omega(0) \rightarrow \Omega(D) \xrightarrow{\psi} k^d$.
 - **Exercise:** If $D \geq 0$, show that Riemann-Roch is equivalent to the statement that $\dim_k[L(D)/L(0)] + \dim_k[\Omega(D)/\Omega(0)] = \deg(D)$.
 - The images of the two maps φ and ψ are orthogonal inside k^d by the observation made above: for any $f \in L(D)$ and any $\omega \in \Omega(D)$, the dot product of $\varphi(f)$ and $\psi(\omega)$ is $\sum_{i=1}^d \text{Res}_{P_i}(f)\text{Res}_{P_i}(\omega) = \sum_{i=1}^d \text{Res}_{P_i}(f\omega) = 0$ since this is again the sum of the residues of a differential.
 - So, since the images of φ and ψ are orthogonal, we see that $\dim(\text{im}\varphi) + \dim(\text{im}\psi) \leq d = \deg(D)$.
 - By the nullity-rank theorem, since $\ker(\varphi) = k$ we get $\dim(\text{im}\varphi) = \dim(L(D)) - 1 = \ell(D) - 1$.
 - Likewise, since $\ker(\psi) = \Omega(D)$ we get $\dim(\text{im}\psi) = \dim(\Omega(0)) - \dim(\Omega(D)) = g - \ell(C-D)$.
 - Thus, we obtain the inequality $\ell(D) - 1 + g - \ell(C-D) \leq \deg(D)$, which is known as Riemann's inequality.
- The Riemann-Roch theorem is then the statement that we have an actual equality here: i.e., that the images of φ and ψ are actually orthogonal complements.
 - As it stands, we only know that $\ell(D) - 1 + g - \ell(C-D) \leq \deg(D)$ when D is an effective divisor.
 - In the event that $C-D$ is also effective, however, we can extract the desired result: in such a case, we have $\ell(D) - 1 + g - \ell(C-D) \leq \deg(D)$ and also $\ell(C-D) - 1 + g - \ell(D) \leq \deg(C-D) = \deg(C) - \deg(D)$, so adding the two inequalities yields $2g - 2 \leq \deg(C)$. But since $\deg(C) = 2g - 2$ (a calculation we take for granted), we must have equality in both cases.
 - This establishes Riemann-Roch for divisors D where both D and $C-D$ are effective divisors (or equivalent to effective divisors, since as we showed, $\ell(D_1) = \ell(D_2)$ when $D_1 \sim D_2$).
 - In fact, this is nearly enough to get the general result, since as we showed, if $L(D) \neq 0$ then D is equivalent to an effective divisor. In general, one needs to verify that when $\ell(C-D) = 0$, one has $\deg(D) \geq \ell(D) - 1 + g$.
 - Assuming the inequality $\deg(D) \geq \ell(D) - 1 + g$, one obtains the general statement of Riemann-Roch: if both D and $C-D$ are equivalent to effective divisors, the result is as above, and if D is but $C-D$ is not, the result follows from $\deg(D) \geq \ell(D) - 1 + g$, and if $C-D$ is but D is not, the result is equivalent by interchanging D and $C-D$.
 - Finally, if neither D nor $C-D$ is equivalent to an effective divisor (i.e., if $\ell(D) = \ell(C-D) = 0$), then by the inequality above we must have $\deg(D) \geq g - 1$ and $\deg(C-D) \geq g - 1$. But since $\deg(C) = 2g - 2$ this forces $\deg(D) = g - 1$, in which case we do get $\deg(D) = \ell(D) - 1 + g - \ell(C-D)$, as required.

0.11 (Oct 19) Ramification and Riemann-Hurwitz

- Our next object of study is how morphisms interact with divisors and differentials. We begin by discussing the notion of ramification.
 - Recall, as we have previously discussed, that if $\varphi : C_1 \rightarrow C_2$ is a nonconstant morphism of curves then we obtain a corresponding injection $\varphi^* : k(C_2) \rightarrow k(C_1)$ on function fields given by $\varphi^* f = f \circ \varphi$ for $f \in k(C_2)$, and conversely any injection of function fields $k(C_2) \hookrightarrow k(C_1)$ arises from a unique morphism.
 - More generally, this association yields an equivalence of categories, where E is an arbitrary field:
 1. (Objects) Function fields K/E of transcendence degree 1 where $K \cap \bar{E} = E$
(Morphisms) Field injections fixing 1 (up to isomorphism)
 2. (Objects) Smooth projective curves defined over E
(Morphisms) Non-constant morphisms defined over E (up to isomorphism)
 - Since both function fields have transcendence degree 1 over k and are finitely generated, the field extension $k(C_1)/\varphi^*k(C_2)$ has finite degree: we define the degree of this extension to be the degree $\deg(\varphi)$. For completeness also we define the degree of constant morphisms to be 0.
 - Additionally, we say φ is separable (or inseparable) when the corresponding field extension is separable (or inseparable) and define the associated separable degree (and inseparable degree) of φ to be the corresponding separable degree (and inseparable degree) of the field extension.
 - Example: The degree of the morphism $\varphi : \mathbb{P}^1 \rightarrow \mathbb{P}^1$ given by $\varphi[X : Y] = [X^2 : Y^2]$ is 2, since with $x = X/Y$ as usual we have $k(C_1) = k(C_2) = k(x)$ and $\varphi(x) = x^2$, so $\varphi^*k(C_2) = k(x^2)$. Then the corresponding function-field extension is $k(x)/k(x^2)$ which has degree 2. Written affinely, the map is simply $\varphi(x) = x^2$, which we quite reasonably would expect to have degree 2 under any sensible definition. When the field characteristic is not equal to 2, this map is separable, and when the characteristic equals 2, it is (purely) inseparable.
- Definition: Let $\varphi : C_1 \rightarrow C_2$ be a nonconstant morphism of (smooth, projective) curves. For each $P \in C_1$ we define the ramification index $e_\varphi(P)$ to be $\text{ord}_P(\varphi^*t_{\varphi(P)})$, where $t_{\varphi(P)}$ is a local uniformizer at $\varphi(P)$.
 - Intuitively, the ramification index $e_\varphi(P)$ measures by what factor the local order of vanishing changes when we apply φ to move from P to $\varphi(P)$.
 - Note by definition that $(\varphi^*t_{\varphi(P)})(P) = (t_{\varphi(P)} \circ \varphi)(P) = t_{\varphi(P)}(\varphi(P)) = 0$, so the function $\varphi^*t_{\varphi(P)}$ is defined at P and evaluates to zero there. Thus, we have $e_\varphi(P) \geq 1$ with equality if and only if $\varphi^*t_{\varphi(P)}$ is a local uniformizer at P .
 - When $e_\varphi(P) = 1$ we say that P is unramified and otherwise (when $e_\varphi(P) > 1$) we say that P is ramified. We extend this to say a point $Q \in C_2$ is unramified when all its preimages $P \in \varphi^{-1}(Q)$ are unramified.
 - Example: Consider the morphism $\varphi : \mathbb{P}^1(\mathbb{C}) \rightarrow \mathbb{P}^1(\mathbb{C})$ given affinely by $\varphi(x) = x^2$. By definition, $\varphi^*f(x) = f(x^2)$. At $P = 2$ we have $\varphi(P) = 4$ and so $t_{\varphi(P)} = x - 4$ is a local uniformizer at $\varphi(P)$. Then $\varphi^*t_{\varphi(P)} = x^2 - 4$, so $\text{ord}_P(\varphi^*t_{\varphi(P)}) = \text{ord}_{x=2}(x^2 - 4) = 1$, so $P = 2$ is unramified. On the other hand, at $Q = 0$ we see that $t_{\varphi(Q)} = x$ so that $\varphi^*t_{\varphi(Q)} = x^2$ and $\text{ord}_Q(\varphi^*t_{\varphi(Q)}) = \text{ord}_x(x^2) = 2$, so $Q = 0$ is ramified. At $R = \infty$ we have $t_{\varphi(R)} = 1/x$ so $\varphi^*t_{\varphi(R)} = 1/x^2$ and so $\text{ord}_R(\varphi^*t_{\varphi(R)}) = \text{ord}_{1/x}(1/x^2) = 2$ so $R = \infty$ is ramified. Indeed, one may check that 0 and ∞ are the only ramified points of this morphism.
 - Exercise: Compute the ramification index $e_\varphi(P)$ for all points $P \in \mathbb{P}^1$ for the map $\varphi : \mathbb{P}^1(\mathbb{C}) \rightarrow \mathbb{P}^1(\mathbb{C})$ with $\varphi(x) = x^3$.
 - Exercise: Let $f \in k(x)$ be a nonconstant rational function. Show that a finite point $P \in k$ is ramified for the map $f : \mathbb{P}^1(k) \rightarrow \mathbb{P}^1(k)$ if and only if $f'(P) = 0$. Deduce that f has only finitely many ramified points. Under what conditions on f will ∞ be ramified?
 - The ramification index defined above is the natural function-field analogue for the ramification index of a prime in a number field.
 - Explicitly, if L/K is an extension of number fields with corresponding rings of integers $\mathcal{O}_L$ and $\mathcal{O}_K$, then each prime ideal R of $\mathcal{O}_L$ lies over a unique prime ideal Q of $\mathcal{O}_K$ with $Q = \mathcal{O}_K \cap R$. If the prime ideal factorization of $Q\mathcal{O}_R$ has its power of R equal to $R^{e(R)}$, then the ramification index of R is $e(R)$. (This quantity is well defined since $\mathcal{O}_L$ is a Dedekind domain and therefore has unique factorization of ideals as a product of prime ideals.)

- In fact, the ramification index in our situation quite literally *is* the ramification index for the prime ideal m_P associated to the valuation ring $\mathcal{O}_P$ in the field extension $k(C_1)/\varphi^*k(C_2)$.
 - The correspondence is a consequence of the general theorems describing the behavior of prime ideals in finite extensions of Dedekind domains, of which the ring of integers $\mathcal{O}_K$ in a number field and the local ring $\mathcal{O}_P$ for a point on a curve are examples.
- We have various other results following from the general theory, as well:
 - Proposition (Properties of Ramification): Let $\varphi : C_1 \rightarrow C_2$ be a nonconstant morphism of (smooth projective) curves.
 1. For all $Q \in C_2$, we have $\sum_{P \in \varphi^{-1}(Q)} e_\varphi(P) = \deg \varphi$.
 - Example: For the squaring map $\varphi : \mathbb{P}^1(\mathbb{C}) \rightarrow \mathbb{P}^1(\mathbb{C})$ with $\varphi(x) = x^2$ of degree 2, for $Q = 4$ we have $\varphi^{-1}(Q) = \{P_2, P_{-2}\}$ and we may compute $e_\varphi(P_2) = e_\varphi(P_{-2}) = 1$. For $R = 0$ we have $\varphi^{-1}(R) = \{P_0\}$ and as we have already computed, $e_\varphi(P_0) = 2$.
 - This result is the analogue of the so-called “*efg*” theorem of number fields: if L/K is an extension of number fields and $f_\varphi(R|Q)$ is the relative degree of the prime R of $\mathcal{O}_L$ lying over the prime Q of $\mathcal{O}_K$, then $\sum_{R|Q} e_i(R)f_i(R) = [L : K]$.
 - In our situation, the analogous definition of the relative degree would be the vector space dimension $\dim_{\mathcal{O}_P/m_P}(\mathcal{O}_{\mathcal{O}_{\varphi^*P}/m_{\varphi^*P}})$, but since k is algebraically closed both fields $\mathcal{O}_P/m_P$ and $\mathcal{O}_{\varphi^*P}/m_{\varphi^*P}$ are isomorphic to k , so the relative degree is always 1.
 - The proof (in both the number field case and our case) follows from examining the prime ideal factorization in the appropriate extension of Dedekind domains.
 2. A point $Q \in C_2$ is unramified if and only if $\#\varphi^{-1}(Q) = \deg \varphi$.
 - Proof: By (1) we have $\sum_{P \in \varphi^{-1}(Q)} e_\varphi(P) = \deg \varphi$.
 - Since there are $\deg \varphi$ terms in the sum and each term is at least 1, the sum is always at least $\#\varphi^{-1}(Q)$, and it equals $\#\varphi^{-1}(Q)$ if and only if $e_\varphi(P) = 1$ for all $P \in \varphi^{-1}(Q)$.
 - So we see $e_\varphi(P) = 1$ for all $P \in \varphi^{-1}(Q)$ if and only if $\#\varphi^{-1}(Q) = \deg \varphi$, as claimed.
 3. For all but finitely many $Q \in C_2$, $\#\varphi^{-1}(Q) = \deg_s \varphi$. As a consequence, when φ is separable, there are only finitely many ramified points Q .
 - The idea here is that typically a point $Q \in C_2$ has a total of $\deg_s \varphi$ preimages under φ , with the exceptions occurring when Q is ramified. Ramification corresponds to the situation where these preimages “collide” and yield fewer preimage points than expected (and the number of such collisions is measured by the ramification index).
 - Exercise: Suppose k is a(n algebraically closed) field of characteristic p and let the Frobenius morphism $\text{Frob} : \mathbb{P}^1(k) \rightarrow \mathbb{P}^1(k)$ be given by $\text{Frob}(x) = x^p$. Verify that $\#\text{Frob}^{-1}(Q) = 1$ for all $Q \in \mathbb{P}^1$, and show that Frob is ramified at every point. Deduce that the hypothesis that φ be separable in (3) above is necessary to ensure there are only finitely many ramified points.
 - This result is the analogue of the statement that there are only finitely many ramified primes in any extension L/K of number fields, which for number fields is typically proven by examining discriminants.
 - Proof (second part): If φ is separable, the result follows immediately from the first part and (2), since $\deg_s \varphi = \deg \varphi$: so for all but finitely many Q we see that Q is unramified.
 4. The ramification index is multiplicative under composition: explicitly, if $\psi : C_2 \rightarrow C_3$ is another nonconstant morphism and $P \in C_1$, we have $e_{\psi \circ \varphi}(P) = e_\varphi(P)e_\psi(\varphi(P))$.
 - This result is the analogue of the fact that the ramification index is multiplicative in towers of number fields.
 - Proof: Applying φ changes the local order of vanishing by a factor of $e_\varphi(P)$, while applying ψ changes the local order of vanishing by a factor of $e_\psi(\varphi(P))$. Thus, the composition changes the local order of vanishing by the product of these two factors.
- When we think of $k(C_1)$ as a finite extension of $\varphi^*k(C_2)$, we may use the norm in this extension to construct a map $\varphi_* : k(C_1) \rightarrow k(C_2)$.

- Explicitly, we define $\varphi_* : k(C_1) \rightarrow k(C_2)$ via $\varphi_* = (\varphi^*)^{-1} \circ N_{k(C_1)/\varphi^*k(C_2)}$.
- We will not bother being more explicit here, because our main interest is in the actions of the maps φ^* and φ_* on divisors and differentials, where we can give much nicer formulas.
- Definition: Let $\varphi : C_1 \rightarrow C_2$ be a nonconstant map of (smooth projective) curves. We define the inverse image map $\varphi^* : \text{Div}(C_2) \rightarrow \text{Div}(C_1)$ on divisor groups by setting $\varphi^*(Q) = \sum_{P \in \varphi^{-1}(Q)} e_\varphi(P)P$ for all $Q \in C_2$ and extending linearly, and we also define the direct image map $\varphi_* : \text{Div}(C_1) \rightarrow \text{Div}(C_2)$ by setting $\varphi_*(P) = \varphi(P)$ for all $P \in C_1$ and extending linearly.
 - In the number fields analogy, the point Q corresponds to a prime ideal π of the ring of integers “downstairs”, whose factorization in an extension is $\pi = P_1^{e_1} \cdots P_k^{e_k}$ with $P_1, \dots, P_k$ being the prime ideal factors in the extension “upstairs”. The map φ^* is the analogous notion of writing the factorization, but in divisor language, while the map φ_* (sending each P_i to π) corresponds to finding the prime π downstairs that lies below a given prime P upstairs.
 - Notational Remark: In principle we could just refer to φ_* as φ , but we want to keep separate the action of φ as a morphism with its action φ_* on divisors and on the associated function fields, and it will be convenient later to write it as φ_* .
 - Rather vacuously, both φ_* and φ^* are homomorphisms.
 - Example: Let $\varphi : \mathbb{P}^1 \rightarrow \mathbb{P}^1$ be the squaring map $\varphi(x) = x^2$. Then for $D = P_4 + 2P_0 - P_\infty$ we have $\varphi^*(D) = P_2 + P_{-2} + 4P_0 - 2P_\infty$ and $\varphi_*(P) = P_{16} + 2P_0 - P_\infty$.
- These actions also extend naturally to differentials:
- Definition: Let $\varphi : C_1 \rightarrow C_2$ be a nonconstant map of (smooth projective) curves. We define $\varphi^* : \Omega(C_2) \rightarrow \Omega(C_1)$ by setting $\varphi^*(f dx) = (\varphi^*f) d(\varphi^*x)$ for all $f, x \in k(C_2)$, and we define $\varphi_* : \Omega(C_1) \rightarrow \Omega(C_2)$ by setting $\varphi_*(g dy) = (\varphi_*g) d(\varphi_*y)$ for all $g, y \in k(C_1)$.
 - We will only need the action of φ^* , but the action of φ_* is recorded for completeness.
 - Example: Let $\varphi : \mathbb{P}^1 \rightarrow \mathbb{P}^1$ be the squaring map $\varphi(x) = x^2$. Then for $\omega_2 = (x+2)dx$ we have $\varphi^*(\omega_2) = (x^2+2)d(x^2) = (x^2+2)2xdx$.
- Proposition (Properties of φ_* and φ^*): Let $\varphi : C_1 \rightarrow C_2$ be a nonconstant map of (smooth projective) curves. Then the following hold:
 1. For any $D \in \text{Div}(C_2)$, we have $\deg(\varphi^*D) = (\deg \varphi)(\deg D)$.
 - Proof: For a single point divisor Q we have $\varphi^*Q = \sum_{P \in \varphi^{-1}(Q)} e_\varphi(P)P$ so $\deg(\varphi^*Q) = \sum_{P \in \varphi^{-1}(Q)} e_\varphi(P) = \deg \varphi$ by property (1) of the ramification index. Now sum over all points in D and apply linearity.
 2. For any $D \in \text{Div}(C_1)$, we have $\deg(\varphi_*D) = \deg D$.
 - Proof: Obvious, since if $D = \sum_{P \in C_1} n_P P$ then $\varphi_*D = \sum_{P \in C_1} n_P \varphi(P)$, whose degree is still $\sum_{P \in C_1} n_P$.
 3. For all $D \in \text{Div}(C_2)$ we have $\varphi_*(\varphi^*D) = (\deg \varphi)D$.
 - Proof: For a single point divisor Q we have $\varphi_*(\varphi^*Q) = \varphi_* \sum_{P \in \varphi^{-1}(Q)} e_\varphi(P)P = \sum_{P \in \varphi^{-1}(Q)} e_\varphi(P) \varphi(P) = [\sum_{P \in \varphi^{-1}(Q)} e_\varphi(P)]Q = (\deg \varphi)Q$. Now sum over all points in D and apply linearity.
 4. If $\psi : C_2 \rightarrow C_3$ is another nonconstant map of smooth projective curves, then $(\psi \circ \varphi)^* = \varphi^* \circ \psi^*$ and $(\psi \circ \varphi)_* = \psi_* \circ \varphi_*$ as maps on the appropriate divisor groups.
 - Proof: For a single point divisor $R \in C_3$ we have $(\psi \circ \varphi)^*R = \sum_{P \in (\psi \circ \varphi)^{-1}(R)} e_{\psi \circ \varphi}(P)P = \sum_{P \in \varphi^{-1}(Q)} [\sum_{Q \in \psi^{-1}(R)} e_\varphi(P)]P = \varphi^* \psi^*R$ using the ramification-in-towers property; now apply linearity.
 - Likewise, for a single point divisor $P \in C_1$ we have $(\psi \circ \varphi)_*P = \psi(\varphi(P)) = (\psi_* \circ \varphi_*)(P)$.
 5. For all nonzero $f \in k(C_2)$ we have $\varphi^*(\text{div } f) = \text{div}(\varphi^*f)$.
 - Exercise: For any nonzero $f \in k(C_2)$ and any $P \in C_1$, show that $\text{ord}_P(\varphi^*f) = e_\varphi(P) \text{ord}_{\varphi(P)}(f)$.
 - Proof: By the exercise we see that $\text{div}(\varphi^*f) = \sum_{P \in C_1} \text{ord}_P(\varphi^*f)P = \sum_{P \in C_1} \text{ord}_{\varphi(P)}(f) \cdot [e_\varphi(P)P] = \sum_{Q \in C_2} \text{ord}_Q(f) \cdot [\sum_{P \in \varphi^{-1}(Q)} e_\varphi(P)]P = \sum_{Q \in C_2} \text{ord}_Q(f) \varphi^*Q = \varphi^* \sum_{Q \in C_2} \text{ord}_Q(f)Q = \varphi^*(\text{div } f)$, as claimed.

6. For all nonzero $g \in k(C_1)$ we have $\varphi_*(\operatorname{div} g) = \operatorname{div}(\varphi_* g)$.
 - This property follows by general facts about the behavior of norms in finite extensions of Dedekind domains.
7. The map φ is separable if and only if $\varphi^* : \Omega(C_2) \rightarrow \Omega(C_1)$ is injective (or equivalently, nonzero).
 - Proof: As noted in our initial discussion of differentials, an element $y \in k(C_2)$ has $\{dy\}$ a basis for $\Omega(C_2)$ if and only if $k(C_2)/k(y)$ is a finite-degree separable extension. Choose such an element y .
 - Applying φ^* shows that $\varphi^*k(C_2)/\varphi^*k(y)$ is also a finite-degree separable extension, and by definition of the action of $\varphi^*y = y \circ \varphi$ we see that $\varphi^*k(y) = k(\varphi^*y)$.
 - Then φ^* is injective $\iff d(\varphi^*y) \neq 0 \iff \{d(\varphi^*y)\}$ is a basis for $k(\Omega_1) \iff k(C_1)/k(\varphi^*y)$ is separable $\iff k(C_1)/\varphi^*k(C_2)$ is separable, where the last equivalence follows from the fact that $\varphi^*k(C_2)/\varphi^*k(y)$ is separable and the composition of separable extensions is separable. And this last statement is simply the definition of separability for φ , so we are done.
 - Also, the equivalence of injectivity and nonzeroness for φ^* on differentials follows from the fact that $d(\varphi^*y)$ being nonzero is equivalent to it being a basis.

- We can now establish the fundamental relationship between the genera⁶ of curves related by a morphism.
- Theorem (Riemann-Hurwitz): Let $\varphi : C_1 \rightarrow C_2$ be a nonconstant separable morphism where C_1 and C_2 are smooth projective curves of respective genera g_1 and g_2 . Let $\omega \in \Omega(C_2)$ be any nonzero differential and define the ramification divisor $R = \operatorname{div}(\varphi^*\omega) - \varphi^*(\operatorname{div}\omega) \in \operatorname{Div}(C_1)$.

1. The ramification divisor R is independent of the choice of ω .
 - Proof: Let $\{dx\}$ be any basis for $\Omega(C_2)$ and write $\omega = f dx$.
 - Then $\varphi^*\omega = (\varphi^*f) d(\varphi^*x)$ so $\operatorname{div}(\varphi^*\omega) = \operatorname{div}(\varphi^*f) + \operatorname{div}[d(\varphi^*x)]$, whereas $\varphi^*(\operatorname{div}\omega) = \varphi^*(\operatorname{div}f) + \varphi^*(\operatorname{div}dx)$.
 - Hence $R = \operatorname{div}(\varphi^*\omega) - \varphi^*(\operatorname{div}\omega) = [\operatorname{div}(\varphi^*f) - \varphi^*(\operatorname{div}f)] + \operatorname{div}[d(\varphi^*x)] - \varphi^*(\operatorname{div}dx) = \operatorname{div}[d(\varphi^*x)] - \varphi^*(\operatorname{div}dx)$ by property (5) above.
 - This last quantity is independent of ω , as desired.
2. We have $\deg R \geq \sum_{P \in C_1} [e_\varphi(P) - 1]$ with equality if and only if the characteristic of k does not divide $e_\varphi(P)$ for any $P \in C_1$. (In particular, equality holds when the characteristic is zero.)
 - Proof: As shown in (1) we have $R = \operatorname{div}[d(\varphi^*x)] - \varphi^*(\operatorname{div}dx)$ for any basis $\{dx\}$ of $\Omega(C_2)$. To compute the order of R at P , we may take $x = t$ where t is a uniformizer at $Q = \varphi(P)$, since as we showed previously, $\{dt\}$ is a basis for $\Omega(C_2)$.
 - By definition, we have $\varphi^*t = us^e$ where s is a uniformizer at P , $e = e_\varphi(P)$ is the ramification index, and $u \in \mathcal{O}_P$ is defined at P with $u(P) \neq 0$.
 - Then $d(\varphi^*t) = [(du/ds)s^e + eus^{e-1}]ds$ so $\operatorname{ord}_P[d(\varphi^*t)] = \operatorname{ord}_P[(du/ds)s^e + eus^{e-1}] = (e-1) + \operatorname{ord}_P[s(du/ds) + eu]$, and we also have $\operatorname{ord}_P[\varphi^*(\operatorname{div}dt)] = 0$.
 - Since u is defined at P we see that du/ds is also defined at P , and quite similarly to our calculations with differentials previously, we see that $\operatorname{ord}_P[d(\varphi^*t)] \geq e-1$ with equality if and only if the characteristic of k does not divide $e = e_\varphi(P)$.
 - Summing over all points $P \in C_1$ yields the result immediately.
3. (Riemann-Hurwitz) We have $2g_1 - 2 = (\deg \varphi)(2g_2 - 2) + \deg R$. As a consequence, $2g_1 - 2 \geq (\deg \varphi)(2g_2 - 2) + \sum_{P \in C_1} [e_\varphi(P) - 1]$ with equality if and only if $\operatorname{char}(k)$ does not divide $e_\varphi(P)$ for any $P \in C_1$.
 - Proof: Taking degrees in the definition of R and rearranging yields $\deg[\varphi^*(\operatorname{div}\omega)] = \deg[\operatorname{div}(\varphi^*\omega)] + \deg R$.
 - By property (1) of φ^* , we have $\deg(\varphi^*\omega) = (\deg \varphi)(\deg \omega) = (\deg \varphi)(2g_2 - 2)$ since ω is a differential on C_2 hence the degree of its divisor is $2g_2 - 2$ as we showed using Riemann-Roch.
 - Likewise, since $\varphi^*(\operatorname{div}\omega)$ is a differential on C_1 , its degree is $2g_1 - 2$.
 - Then (2) yields immediately that $2g_1 - 2 \geq (\deg \varphi)(2g_2 - 2) + \sum_{P \in C_1} [e_\varphi(P) - 1]$ with equality if and only if $\operatorname{char}(k)$ does not divide $e_\varphi(P)$ for any $P \in C_1$, as claimed.

⁶“Genera” is the correct plural of “genus”.

- The Riemann-Hurwitz theorem is really a topological result, and we can give some geometric motivation for where it comes from in the situation of Riemann surfaces, where $k = \mathbb{C}$.
 - If we view the curves C_1 and C_2 as surfaces over $\mathbb{R}$, then the morphism φ represents a d -sheeted covering of C_2 by C_1 , where each unramified point of C_2 has exactly d preimages in C_1 .
 - If φ were unramified everywhere, then (e.g., by considering a triangulation of C_1) we see that the Euler characteristic $\chi_1 = 2 - 2g_1$ of C_1 would be d times the Euler characteristic $\chi_2 = 2 - 2g_2$ of C_2 : this is precisely the statement of Riemann-Hurwitz above.
 - At ramified points of φ , the sheets of the covering collide, which introduces an error term into the calculation.
 - Precisely, at a ramified point the ramification index $e_\varphi(P)$ counts the number of sheets that collide at P , and so relative to unramified points (with ramification index 1) the overall characteristic χ_1 is lowered by a total of $e_\varphi(P)$ from what would be expected if the point were unramified.
 - Summing this correction over all of the ramified points yields the general statement of Riemann-Hurwitz: $\chi_1 = (\deg \varphi)\chi_2 - \sum_{P \in C_1} [e_\varphi(P) - 1]$.

0.12 (Oct 22) Isogenies

- We can now apply these general results to the situation of morphisms of elliptic curves. Since we defined an elliptic curve as a smooth projective curve of genus 1 together with a marked rational point O , we require the maps also to preserve the marked point:
- Definition: Let (E_1, O_1) and (E_2, O_2) be two elliptic curves. An isogeny $\varphi : E_1 \rightarrow E_2$ is a morphism from E_1 to E_2 such that $\varphi(O_1) = O_2$. If E_1 and E_2 are elliptic curves such that there exists a nonzero isogeny between them, we say they are isogenous.
 - Since the identity is uniquely specified for an elliptic curve, we will usually just write it as O .
 - As we will show later, being isogenous is an equivalence relation on elliptic curves. (It is self-evidently reflexive and transitive, since the identity morphism is an isogeny and the composition of two isogenies is an isogeny.)
 - Since nonconstant morphisms of curves are surjective, and the only constant isogeny is the zero map, nonzero isogenies are surjective.
 - When φ is nonzero, recall that we define the degree of φ to be degree of the function-field extension $k(C_2)/\varphi^*k(C_1)$. We also set $\deg(0) = 0$ for convenience.
 - Exercise: Show that the degree map is multiplicative on isogenies: $\deg(\varphi \circ \psi) = (\deg \varphi)(\deg \psi)$.
- Since E_1 and E_2 are groups, the collection of all isogenies from E_1 to E_2 forms an abelian group, and since compositions of isogenies are isogenies, the set of isogenies from E to E forms a ring.
 - Exercise: Let E_1 and E_2 be elliptic curves and define $\text{Hom}(E_1, E_2)$ to be the collection of all isogenies from E_1 to E_2 . Show that $\text{Hom}(E_1, E_2)$ is an abelian group under the addition operation $(\varphi + \psi)P = \varphi(P) + \psi(P)$ for all $P \in E_1$ (where the addition on the right is the sum under the group law on E_2) for $\varphi, \psi \in \text{Hom}(E_1, E_2)$.
 - Exercise: Let E be an elliptic curve and define $\text{End}(E) = \text{Hom}(E, E)$ to be the collection of all isogenies from E to itself. Show that $\text{End}(E)$ is a ring with 1 having no zero divisors, with addition given as in the exercise above and multiplication given by composition. [Hint: For the lack of zero divisors, consider degrees.]
- Our most basic example of an isogeny is the multiplication-by- m map:
 - Example: For an integer m , the multiplication-by- m map $[m] : E \rightarrow E$ is an isogeny, since as we have previously discussed it is a morphism, and it clearly preserves the group identity O .
 - We showed much earlier during our discussion of Mordell's theorem that the multiplication-by- m map has degree m^2 , since as a rational map it is defined by a quotient of polynomials of degree m^2 (we will later give a far nicer and minimally computational proof of this fact).

- In particular, $[m] \neq 0$ for $m \neq 0$, so the endomorphism ring $\text{End}(E)$ always contains the subring $\mathbb{Z}$ generated by the identity map $[1]$.
- Additionally, if $\varphi : E_1 \rightarrow E_2$ is any isogeny, we see that $\deg(m\varphi) = \deg([m] \circ \varphi) = \deg([m]) \deg(\varphi) = m^2 \deg(\varphi)$. Thus, if φ is a torsion element of $\text{Hom}(E_1, E_2)$ so that $m\varphi = 0$, then this calculation shows $\deg(\varphi) = 0$ whence $\varphi = 0$: this means $\text{Hom}(E_1, E_2)$ is torsion-free.
- As we will see, for many elliptic curves the multiplication-by- m maps are the only endomorphisms! So it requires some nontrivial effort to give other examples.
- Example: Consider the map $i : E \rightarrow E$ with $i(x, y) = (-x, iy)$ on the elliptic curve $E : y^2 = x^3 - x$, where $i^2 = -1$ inside the underlying field k (where we assume $\text{char}(k) \neq 2$ to avoid trivialities).
 - This map is a morphism from E to E since $(-x, iy)$ is also a point of E and the map is described by rational functions that are defined everywhere, and since it maps $O = \infty$ to itself, it is an isogeny of E .
 - We can easily see that $[i] \circ [i]$ maps $(x, y) \mapsto (x, -y)$, so $[i] \circ [i] = [-1]$.
 - Taking $b[i]$ to be the b -fold sum of $[i]$ with itself, we see that the endomorphism ring $\text{End}(E)$ contains the elements $[a] + b[i]$ for all $a, b \in \mathbb{Z}$. The ring of such elements is isomorphic to the Gaussian integer ring $\mathbb{Z}[i]$ via the obvious map $[a] + b[i] \mapsto a + bi$, and in fact, these are all of the endomorphisms of this elliptic curve.
 - This curve E is an example of an elliptic curve with complex multiplication, as it possesses an endomorphism that behaves like multiplication by a complex number (in this case, $i = \sqrt{-1}$).
- Example: Let $E = V(f)$ be an elliptic curve and let $E^{(p)} = V(f^{(p)})$, where $f^{(p)}$ is obtained by raising all of the coefficients of f to the p th power⁷. Then the Frobenius map $\text{Frob} : E \rightarrow E^{(p)}$ with $\text{Frob}(x, y) = (x^p, y^p)$ is an isogeny from E to $E^{(p)}$ since it is clearly a morphism and it preserves the point at ∞ .
 - If E is defined over the field $\mathbb{F}_p$, the Frobenius map fixes all of the coefficients (indeed, $\mathbb{F}_p$ is precisely the field fixed by the Frobenius map): then $E^{(p)} = E$ and so Frob is an endomorphism of E .
 - More generally, if E is defined over $\mathbb{F}_q$ for some prime power q , then the q th-power Frobenius map $\text{Frob}(x, y) = (x^q, y^q)$ is an endomorphism of E .
- We obtain various fundamental properties of isogenies that flow (more or less immediately) from the general properties of morphisms we have already shown:
- Theorem (Properties of Isogenies): Let $\varphi : E_1 \rightarrow E_2$ be a nonzero isogeny. Then the following hold:
 1. The map φ is a group homomorphism from E_1 to E_2 : in other words, $\varphi(P + Q) = \varphi(P) + \varphi(Q)$ for all $P, Q \in E_1$.
 - Since isogenies are the natural maps in the category of elliptic curves, and elliptic curves carry a natural group structure (which as we have discussed can be described purely in terms of the divisor group), the fact that isogenies are group homomorphisms is quite reasonable. Indeed, the reason we impose the additional condition that isogenies map the identity of E_1 to the identity of E_2 is precisely to ensure that isogenies are group homomorphisms.
 - Proof: Let P, Q be points of C_1 and O be the identity of C_1 .
 - Then by our earlier results, $[P + Q] - [P] - [Q] + [O]$ is a principal divisor on E_1 as it has degree 0 and the underlying sum of points resolves to the identity on E_1 .
 - For $\text{div}(f) = [P + Q] - [P] - [Q] + [O]$, we then have $\text{div}(\varphi^* f) = \varphi^* \text{div}(f) = [\varphi(P + Q)] - [\varphi(P)] - [\varphi(Q)] + [\varphi(O)]$, so this latter divisor is principal on E_2 .
 - But that implies the resulting sum of points $\varphi(P + Q) - \varphi(P) - \varphi(Q) + \varphi(O)$ resolves to the identity on E_2 , so since $\varphi(O)$ is the identity on E_2 , we conclude immediately that $\varphi(P + Q) = \varphi(P) + \varphi(Q)$ as claimed.

⁷Since the discriminant is a polynomial function of the coefficients of the Weierstrass equation, since the Frobenius map is a field automorphism, the discriminant of $f^{(p)}$ is the p th power of the discriminant of E , so $E^{(p)}$ is also nonsingular when E is nonsingular.

- Remark: Another way of making this argument is to observe that we have constructed group isomorphisms $\tau_1 : E_1 \rightarrow \text{Pic}^0(E_1)$ and $\tau_2 : E_2 \rightarrow \text{Pic}^0(E_2)$ with $\tau_i(P) = [P] - [O]$ as divisor classes. Then $\varphi_* \circ \tau_1 = \tau_2 \circ \varphi$ essentially by definition and the fact that $\varphi(O) = O$, so since φ_* is a homomorphism on the Picard groups, $\varphi = \tau_2^{-1} \circ \varphi_* \circ \tau_1$ is a composition of homomorphisms and thus also a homomorphism.
2. For all $Q \in E_2$, $\#\varphi^{-1}(Q) = \deg_s \varphi$. In particular, $\ker \varphi = \varphi^{-1}(O)$ is a finite subgroup of E_1 .
 - Exercise: Suppose that $\varphi : G \rightarrow H$ is a surjective group homomorphism. Show that for any $h \in H$ there is a bijection between $\varphi^{-1}(h)$ and $\ker \varphi$.
 - Proof: By our results on ramification we know that $\#\varphi^{-1}(Q) = \deg_s \varphi$ for all but finitely many $Q \in E_2$. Since φ is a group homomorphism by (1) and surjective since it is a nonzero morphism, applying the exercise above yields both results immediately.
 3. For all $P \in E_1$, the ramification index $e_\varphi(P) = \deg_i \varphi$, the inseparable degree of φ .
 - Proof: First, let $Q = \varphi(P)$ and take P' to be another point in $\varphi^{-1}(Q)$, and also define $R = P' - P$.
 - Since the translation morphism $\tau_R : E \rightarrow E$ defined by $\varphi(A) = A + R$ is an isomorphism and hence unramified, we have $\varphi(R) = O$ and so $\varphi \circ \tau_R = \varphi$.
 - Then $e_\varphi(P) = e_{\varphi \circ \tau_R}(P) = e_\varphi(\tau_R(P))e_{\tau_R}(P) = e_\varphi(P')$ by the ramification composition formula. This means all points in $\varphi^{-1}(P)$ have the same ramification index.
 - Then $\deg_s \varphi \deg_i \varphi = \deg \varphi = \sum_{P \in \varphi^{-1}(Q)} e_\varphi(P) = \#\varphi^{-1}(Q) \cdot e_\varphi(P) = \deg_s \varphi \cdot e_\varphi(P)$, so we must have $e_\varphi(P) = \deg_i \varphi$ as claimed.
 4. If φ is separable then φ is everywhere unramified and $\#\ker \varphi = \deg \varphi$.
 - Proof: By (3) we see immediately that if φ is separable, then $e_\varphi(P) = \deg_i \varphi = 1$ for all P , so φ is unramified. The cardinality of the kernel is immediate from (2).
 - Exercise: Use Riemann-Hurwitz to prove directly that if $\varphi : E_1 \rightarrow E_2$ is a nonconstant separable morphism of elliptic curves then φ is everywhere unramified.
 5. The kernel $\ker \varphi$ is isomorphic to the automorphism group of the extension $k(E_1)/\varphi^*k(E_2)$ via the map Ξ sending $R \mapsto \tau_R^*$ where τ_R is the translation-by- R morphism.
 - Proof: First, in the same way as noted in the proof of (3), for any $R \in \ker \varphi$ we have $\varphi \circ \tau_R = \varphi$, since $\varphi(x + R) = \varphi(x) + \varphi(R) = \varphi(x)$ since φ is a homomorphism.
 - Then for any $f \in k(E_2)$ we have $\tau_R^*(\varphi^*f) = (\varphi \circ \tau_R)^*f = \varphi^*f$, and so τ_R^* fixes the field $k(E_2)$. Therefore τ_R^* is an automorphism of the extension $k(E_1)/\varphi^*k(E_2)$ so Ξ is well defined.
 - Next, for any $R, S \in \ker \varphi$ since rather obviously $\tau_{R+S} = \tau_S \circ \tau_R$, we have $\tau_{R+S}^* = (\tau_S \circ \tau_R)^* = \tau_R^* \tau_S^*$ so Ξ is a homomorphism.
 - Third, if τ_R^* fixes $k(E_1)$, then for any $f \in k(E_1)$ we have $f \circ \tau_R = f$. Taking f to be a function with poles only at O (which exist by Riemann-Roch since $l(2O) = 2$) we see that $f \circ \tau_R$ has poles only at $-R$, so $R = O$. Thus $\ker \Xi = \{O\}$ so Ξ is injective.
 - Finally, by basic facts about field automorphisms, the cardinality of $\text{Aut}[k(E_1)/\varphi^*k(E_2)]$ is at most the separable degree of the extension $\deg_s(\varphi)$, so by (2) and the fact that Ξ is an injective homomorphism, we must have equality and Ξ is an isomorphism.
 6. If φ is separable then the extension $k(E_1)/\varphi^*k(E_2)$ is a Galois extension of degree $\#\ker \varphi$.
 - Proof: By basic Galois theory, the cardinality of $\text{Aut}[k(E_1)/\varphi^*k(E_2)]$ equals the degree of the extension if and only if the extension is Galois. By (4) and (5) combined, this occurs, and the degree equals $\deg \varphi = \#\ker \varphi$.
 7. Suppose that $\varphi : E_1 \rightarrow E_2$ and $\psi : E_1 \rightarrow E_3$ are nonconstant isogenies and that φ is separable. If $\ker \varphi \subseteq \ker \psi$ then there exists a unique isogeny $\gamma : E_2 \rightarrow E_3$ such that $\psi = \gamma \circ \varphi$.
 - This result gives us a very convenient universal property of isogenies, and is essentially just an application of the fundamental theorem of Galois theory to the appropriate field extensions rephrased in terms of the corresponding curves.
 - Proof: Since φ is separable, by (6) we know that $k(E_1)/\varphi^*k(E_2)$ is Galois of degree $\#\ker \varphi$. Let the Galois group be G . Since $\ker \varphi \subseteq \ker \psi$, every element of G fixes $\psi^*k(E_3)$, so $\varphi^*k(E_2)$ is a field extension of $\psi^*k(E_3)$.

- Since field extensions of function fields correspond to morphisms of curves (per the equivalence of categories discussed earlier), there exists a unique morphism $\gamma : E_2 \rightarrow E_3$ such that $\varphi^*(\gamma^*k(E_3)) = \psi^*k(E_3)$ which on the level of morphisms is equivalent to saying that $\gamma \circ \varphi = \psi$.
 - Finally, we have $\gamma(O) = \gamma(\varphi(O)) = \psi(O) = O$ since φ and ψ are isogenies, and so γ is an isogeny as well.
8. Suppose that Φ is a finite subgroup of the elliptic curve E . Then there exists a unique elliptic curve E' and a separable isogeny $\varphi : E \rightarrow E'$ such that $\ker \varphi = \Phi$.
- Since φ is a surjective group homomorphism, the first isomorphism theorem immediately implies that the group structure of E' is that of the quotient group E/Φ , so since E' is unique here we often simply write $E' = E/\Phi$.
 - Of course, we can certainly construct the quotient group as a group by itself, but it is not immediately obvious why this quotient should also carry the structure of an algebraic variety (let alone why it should be another elliptic curve).
 - But in fact, one can show that the quotient of any smooth projective curve by a finite group of automorphisms also carries the structure of a variety.
 - Proof: As noted in (5), for each $R \in \Phi$ the translation-by- R map $\tau_R(x) = x + R$ yields an automorphism τ_R^* of $k(E)$; note it is an automorphism since it has an inverse map τ_{-R}^* .
 - By the fundamental theorem of Galois theory, if K is the fixed field of the automorphism group $\Phi^* = \{\tau_R^* : R \in \Phi\}$, then $k(E)/K$ is a Galois extension of degree $\#\Phi^* = \#\Phi$. In particular, K has transcendence degree 1 over k , so by our equivalence of categories, there exists a unique (up to isomorphism) smooth projective curve C/k and a unique finite-degree morphism $\varphi : E \rightarrow C$ such that $\varphi^*k(C) = K$.
 - Now, since $k(E)/K$ is Galois hence separable, φ is separable. It remains to show that C is an elliptic curve (i.e., that it has genus 1 and that it has a rational point O).
 - To do this we first show that φ is unramified, and then we apply Riemann-Hurwitz.
 - For any $P \in E$ and $R \in \Phi$ and $f \in k(C)$, we have $f(\varphi(P + R)) = f(\varphi(\tau_R(P))) = (\varphi \circ \tau_R)^*f(P) = \tau_R^*\varphi^*f(P) = \varphi^*f(P) = f(\varphi(P))$ because τ_R^* fixes φ^*f .
 - Since this equality holds for all functions f , by choosing f to be a function with poles only at one point (as in the argument in (5) above) we see that $\varphi(P + R) = \varphi(P)$.
 - Therefore, for any $Q = \varphi(P)$ on C , the set $\varphi^{-1}(Q)$ contains the $\#\Phi$ translates $\{Q + R : R \in \Phi\}$. But by our properties of ramification, $\#\varphi^{-1}(Q) \leq \deg \varphi = \#\Phi$ with equality if and only if Q is unramified. Since this holds for all $Q \in C$, this means φ is everywhere unramified.
 - Now, since φ is separable and unramified everywhere, by Riemann-Hurwitz we have $2g_E - 2 = (\deg \varphi)(2g_C - 2) + 0$ and so since $\deg \varphi$ is positive and $g_E = 1$, we must have $g_C = 1$ also.
 - Finally, if we define $O_C = \varphi(O_E)$, then φ is an isogeny, and then as calculated above $\ker \varphi$ equals $\{O_E + R : R \in \Phi\} = \Phi$ since φ is unramified.
9. Suppose that $\text{char}(k) = p$ and φ is not separable. For $q = \deg_i \varphi$ and $\text{Frob}_q : E_1 \rightarrow E_1^{(q)}$ the q th-power Frobenius map, we may decompose $\varphi = \alpha \circ \text{Frob}_q$ for a separable isogeny $\alpha : E_1^{(q)} \rightarrow E_2$.
- This result extends the discussion above about the separable case and allows us to reduce the study of inseparable isogenies to the specific situation of the Frobenius map.
 - Proof: Let K be the separable closure of $\varphi^*k(E_2)$ in $k(E_1)$. Then by standard results about (in)separable extensions over perfect fields, $k(E_1)/K$ is purely inseparable of degree $q = \deg_i \varphi = p^d$ for some d with $K = k(E_1)^q$, while $K/\varphi^*k(E_2)$ is separable of degree $\deg_s \varphi$.
 - Then by definition, we see $K = \varphi^*k(E_1^{(q)})$, so since we have the tower of extensions $k(E_1)/\varphi^*k(E_1^{(q)})/\varphi^*k(E_2)$, converting to a statement about morphisms we see that $\varphi = \alpha \circ \text{Frob}_q$ where $\alpha : E_1^{(q)} \rightarrow E_2$ is the morphism corresponding to the separable extension $K/\varphi^*k(E_2)$ and $\text{Frob}_q : E_1 \rightarrow E_1^{(q)}$ is the q th-power Frobenius morphism corresponding to $k(E_1)/\varphi^*k(E_1^{(q)})$.
 - Remark: As also follows from the field degree calculations above, the degree of the q th-power Frobenius map Frob is q . This can also be calculated directly.
10. For any $Q \in E_1$, if $\tau_Q : E_1 \rightarrow E_1$ is the translation-by- Q map then $\tau_Q^*\omega = \omega$.
- Proof: We showed this earlier in our discussion of differentials (it is why ω is called the invariant differential).

11. We have $[-1]^*\omega = -\omega$.

◦ Proof: Suppose E_1 has general Weierstrass equation $y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6$.

◦ Now because $[-1](x, y) = (x, -y - a_1x - a_3)$, we see that $d[-1]^*x = dx$ and so $[-1]^*\omega = [-1]^*\frac{dx}{2y + a_1x + a_3} = \frac{dx}{2(-y - a_1x - a_3) + a_1x + a_3} = -\omega$.

12. If ω is the invariant differential on E_1 and φ, ψ are two isogenies from $E_1 \rightarrow E_2$, then $(\varphi + \psi)^*\omega = \varphi^*\omega + \psi^*\omega$.

◦ Proof: If φ or ψ is the zero isogeny the result is trivial.

◦ If $\varphi + \psi = 0$ so that $\psi = [-1] \circ \varphi$ and thus $\psi^* = \varphi^* \circ [-1]^*$, we deduce $\varphi^*\omega + \psi^*\omega = \varphi^*\omega + \varphi^*(-\omega) = 0$ by linearity and (11).

◦ Now assume that none of $\varphi, \psi, \varphi + \psi$ is zero. Take independent coordinates (x_1, y_1) and (x_2, y_2) and let $(x_3, y_3) = (x_1, y_1) + (x_2, y_2)$ via the group law, so that x_3 and y_3 are rational functions of x_1, y_1, x_2, y_2 .

◦ Now let $\omega_i(x_i, y_i)$ be the associated invariant differential $\frac{dx_i}{2y_i + a_1x_i + a_3}$ for each $i = 1, 2, 3$.

◦ Writing $x_3 = f(x_1, y_1, x_2, y_2)$,⁸ the chain rule for differentials yields $dx_3 = f_{x_1}dx_1 + f_{y_1}dy_1 + f_{x_2}dx_2 + f_{y_2}dy_2$. But since dx_1 and dy_1 are $k(x_1, y_1)$ -multiples of $\omega(x_1, y_1)$ and dx_2, dy_2 are $k(x_2, y_2)$ -multiples of $\omega(x_2, y_2)$, we see that $\omega(x_3, y_3)$ is a $k(x_1, y_1, x_2, y_2)$ -linear combination of the differentials $\omega(x_1, y_1)$ and $\omega(x_2, y_2)$.

◦ So now write $\omega_3(x_3, y_3) = g(x_1, y_1, x_2, y_2)\omega_1(x_1, y_1) + h(x_1, y_1, x_2, y_2)\omega_2(x_2, y_2)$ for some $g, h \in k(x_1, y_1, x_2, y_2)$.

◦ By working through the rather horrendous calculations explicitly, one may show that in fact the coefficients g and h are both just 1.

◦ To see this in a more pleasant manner, observe that if we choose any $P \in E_1$ and evaluate our expressions at $x_1 = x_1(P)$ and $y_1 = y_1(P)$, we have $dx_1 = dy_1 = 0$ so $\omega_1 = 0$, while $(x_3, y_3) = P + (x_2, y_2) = \tau_P(x_2, y_2)$.

◦ Thus $\omega_3 = \tau_P^*\omega_2 = \omega_2$ by translation-invariance from (10), so the linear combination expression reads as $\omega_3 = h(x_1(P), y_1(P), x_2, y_2)\omega_3$ whence $h(x_1(P), y_1(P), x_2, y_2)$ is identically 1 as a rational function in x_2 and y_2 . But since this is true for every point $P \in C$, in fact h must be the constant function 1. By a symmetric argument we see $g = 1$ as well.

◦ So now we know that $\omega_3(x_3, y_3) = \omega_1(x_1, y_1) + \omega_2(x_2, y_2)$.

◦ Now apply this result to the case where $(x_1, y_1) = \varphi(x, y)$ and $(x_2, y_2) = \psi(x, y)$, so that $(x_3, y_3) = (\varphi + \psi)(x, y)$: it says that $(\omega \circ (\varphi + \psi))(x, y) = (\omega \circ \varphi)(x, y) + (\omega \circ \psi)(x, y)$ whence $(\varphi + \psi)^*\omega = \varphi^*\omega + \psi^*\omega$, as desired.

13. For any integer m we have $[m]^*\omega = m\omega$. In particular, $[m]$ is a finite, separable morphism whenever $\text{char}(k)$ does not divide m .

◦ Proof: For $m \geq 0$, induct on m . The base case $m = 0$ is trivial. For the inductive step observe that $[m+1]^*\omega = [m]^*\omega + [1]^*\omega = (m+1)\omega$ using (12) for additivity and the obvious $[1]^*\omega = \omega$.

◦ For negative m note that $[m] = [-1] \circ [-m]$ and apply the result for positive m and (11).

◦ The last statement follows immediately from the fact discussed earlier that a morphism is separable whenever it is nonzero on differentials.

Well, you're at the end of my handout. Hope it was helpful.

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⁸Explicitly, $f(x_1, y_1, x_2, y_2) = \left(\frac{3x_1^2 + 2a_2x_1 + a_4 - a_1y_1}{2y_1 + a_1x_1 + a_3}\right)^2 + a_1\left(\frac{3x_1^2 + 2a_2x_1 + a_4 - a_1y_1}{2y_1 + a_1x_1 + a_3}\right) - a_2 - x_1 - x_2$.